



centro de educación continua
división de estudios superiores
facultad de ingeniería, unam



FOTOGRAMETRIA APLICADA AL DISEÑO Y CONSERVACION DE OBRAS
DE INGENIERIA CIVIL

DR. BENGT ADOLFSSON
MARZO DE 1979



Seminar program

Monday:
03-26

Introduction
Photogrammetry in
a location stage
of design

- photography
- topographic maps
- photo interpretation
- orthophotography
- remote sensing

Tuesday:
03-27

Photogrammetry in
preliminary design

- photography
- block(strip) triangulation
- evaluation of photos
- map specifications

Wednesday: Photogrammetry in
03-28 final design and constr.

- photography
- cross-sections, profiles
- digital terrain model
- photogrammetry and field surveying
- data processing

Thursday: Terrestrial photogrammetry
03-29

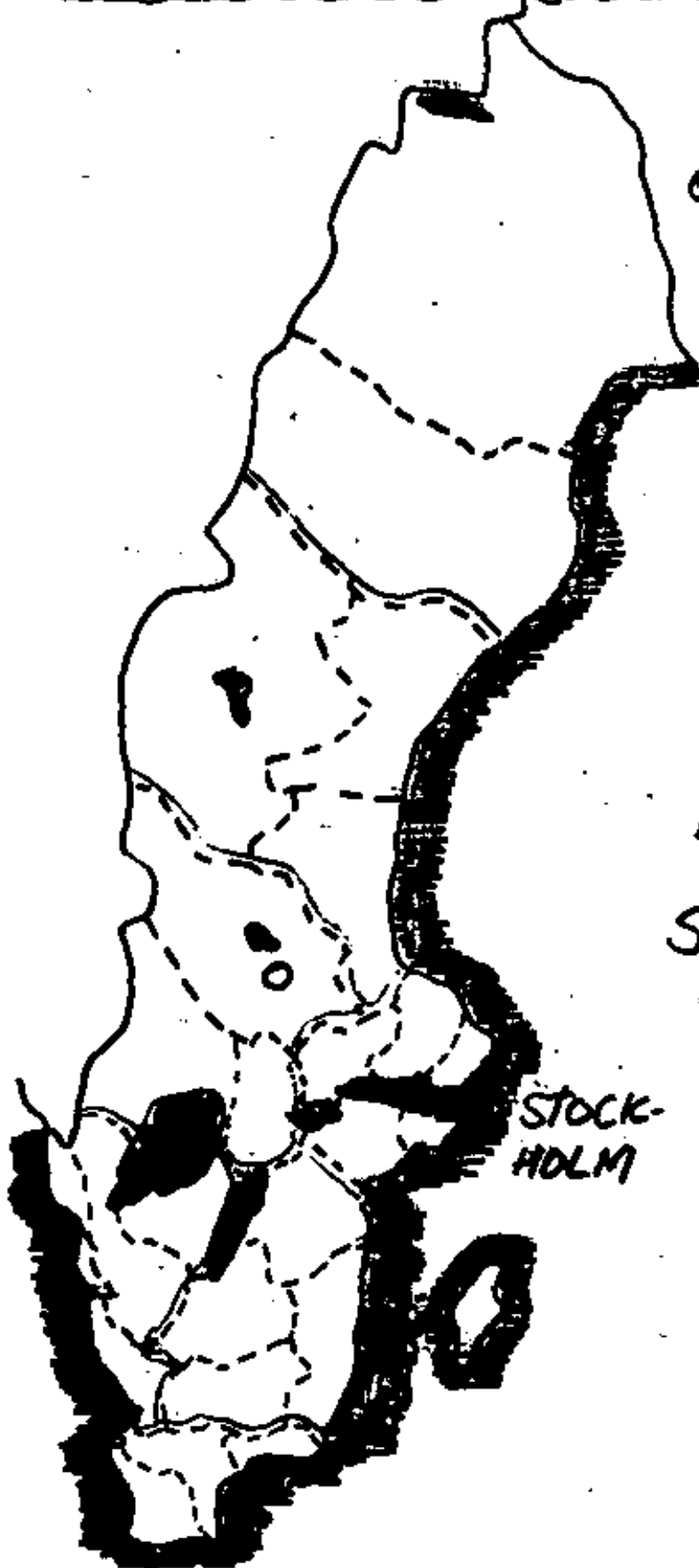
- principles
- cameras, instruments
- orthophotography
- applications
 - architecture
 - volumes
 - deformation

Friday: Field surveying and
03-30 setting out methods

- electro-optical
- tachometry
- field data collection
- self-instructing course
in basic field survey

General remarks on
the development of
photogrammetric and
geodetic instruments

The National Road Administration



central office Sthlm:

24 regions

design
maintenance

7 districts

construction

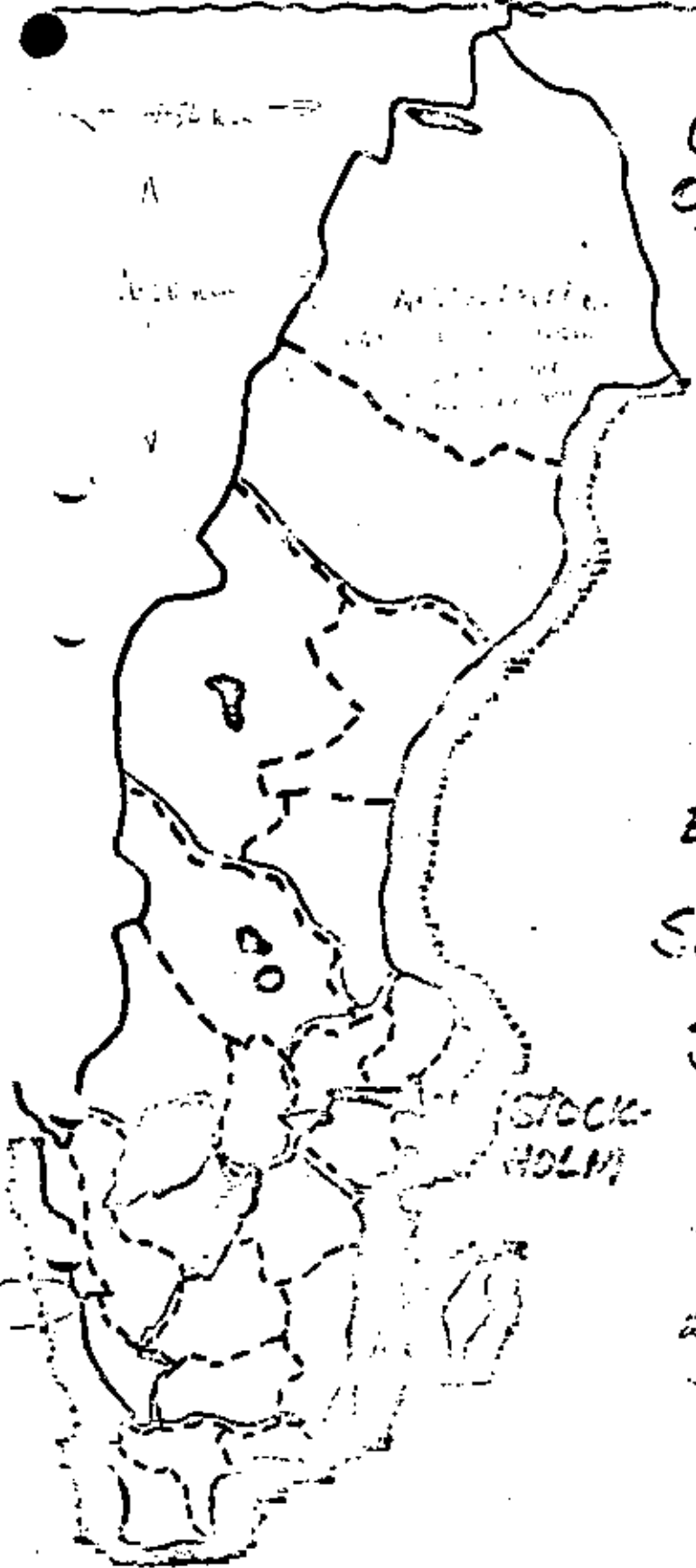
Employees 11000

State roads 100000 km

Bridges 10700

Budget ~~500~~ mill. SWK
5000

The National Road Administration



central office

Stockholm

24 regions

design
maintenance

7 districts

construction

Employees 11000

State roads 10000 km

Bridges 10700

Budget 3400 mill. SEK

Full employment

?

20

3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24

1960-1961
1962-1963
1964-1965

1966-1967
1968-1969
1970-1971

90% of the road network is asphalt
10% is gravel

Highway engineering has constantly to be developed to meet new or extended requirements on

- environment
- traffic safety
- community planning
- aesthetics
- traffic costs
- construction costs

need for constant development of techniques
Highway engineering has consistently
to be developed to meet new or
extended requirements on

- environment

"often wise" facilitates
an practice

- traffic safety

"and alignment" =
more complex alignment elements

- community planning

it can be valuable
design phase

- aesthetics

no road should not destroy the
landscape

- traffic costs =

congestion, delays
and standards
most maintenance

- construction costs

most that can be
fully financed government

but cost of design << cost of construction
with

very low cost of pi
...
...
...

many techniques have to be used e.g.

- field surveying
- photogrammetry
- aerial photointerpretation
- data processing
- automatic plotting

many techniques have to be used e.g.

development of the
aerial photography
photogrammetry

- field surveying

- photogrammetry

- aerial photo interpretation

- data processing

- automatic plotting

2. Major technical questions

a) the user would be able to do the required job

of concept design is vital to get

+ help understanding

what is possible - how

- education

how to do it

step 1, step 2

Why photogrammetry?

+

- high density of information
- over-all and detailed information
- multiple use of photographs
- adaptable to various accuracy requirements
- efficient map production
- 3D design
- data acquisition at wish and at the needed occasion
- high production rates
- aid for presentation of plan.

Why photogrammetry?

- vegetation
- weather dependent
- ground control
- high initial costs

planning procedure



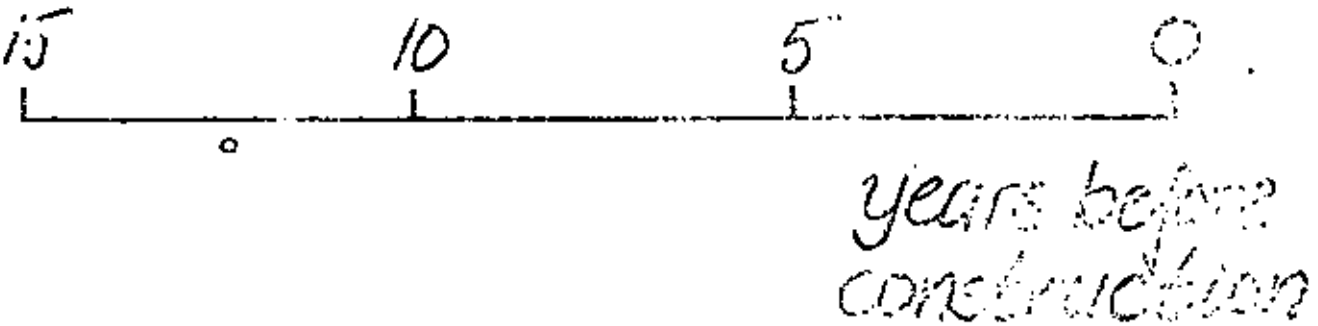
years before
construction

route
location

prel.
design

final
design

planning procedure



route
location

main characteristics
of the highway network
community planning
and analysis of
topography and geology
- determine areas
- identify areas un-
suitable for road-
construction
- result in corridor

prel.
design

- more detailed work
- road lines
- settling and line
- site plan complex
- result in a
- not conflicting
with the general
design

final
design

- final plan of the
- detailed
- result in a
- result in all the
- final design

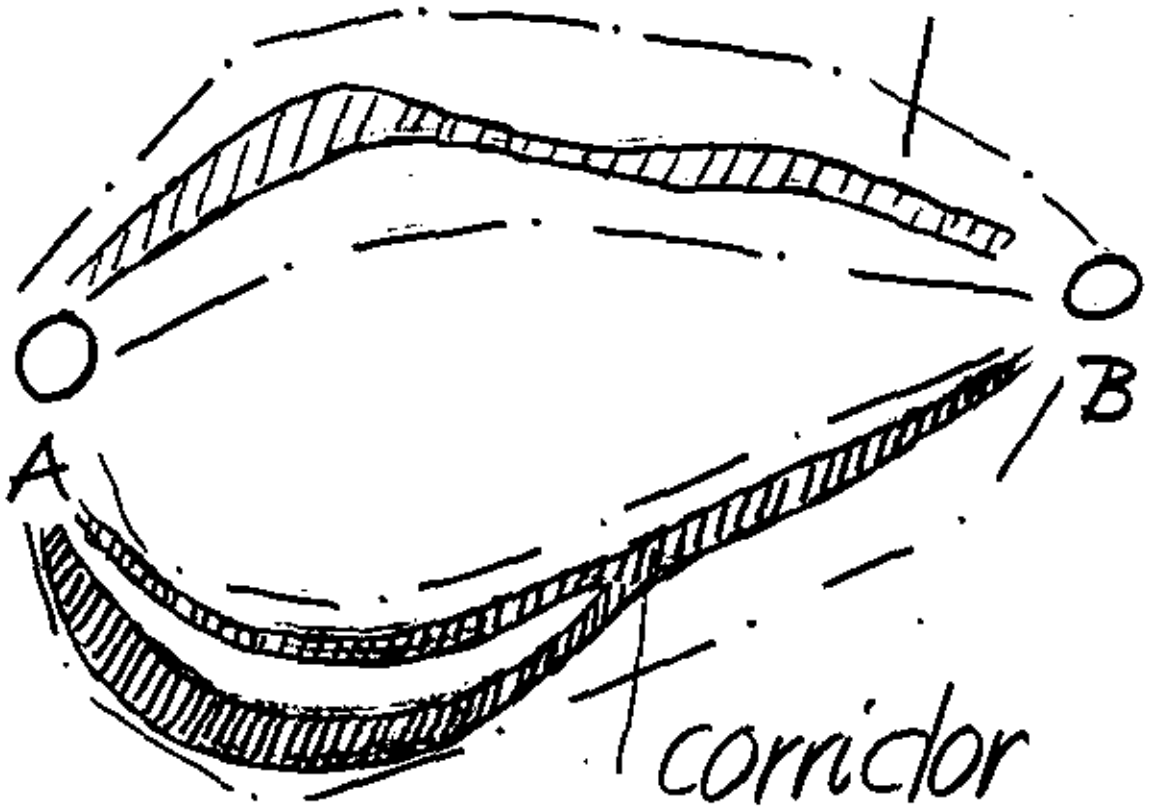
don't go into detailed investigation too soon!

route location

"search"

"select"

band



location factors

route
independent
topography
soils
geology
land use
population
distribution
travel
demand

route
dependent
user costs
construction
costs
maintenance
costs
aesthetics
safety
design geometry

location

- photography
- topographic maps
- photo interpretation
- orthophotography
- remote sensing

route location

data acquisition

aerial photography

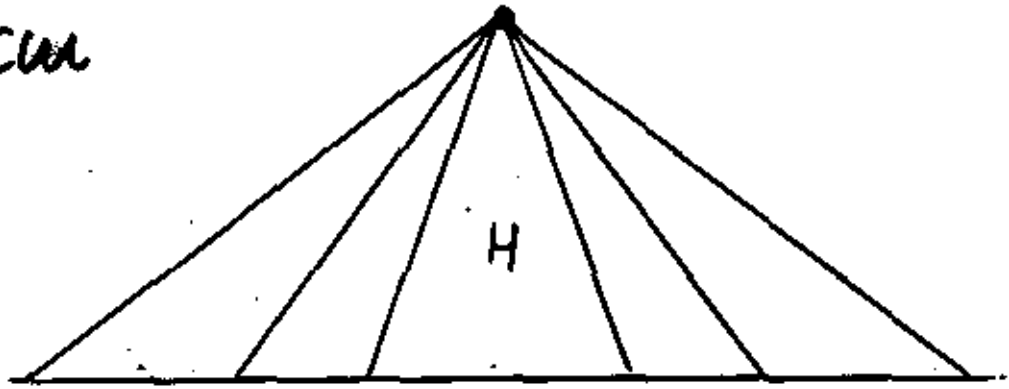
- metric camera

non-metric - " -

remote sensing

Metric cameras

23x23 cm



normal
angle $c = 304 \text{ mm}$

$0.75H$

wide
angle $c = 152 \text{ mm}$

$1.5H$

super-wide
angle $c = 88 \text{ mm}$

$2.5H$

route location

evaluation

topographic
maps

1:5000 - 1:50000

orthophoto
plans

1:5000 - 1:20000

stereoscopic
viewing

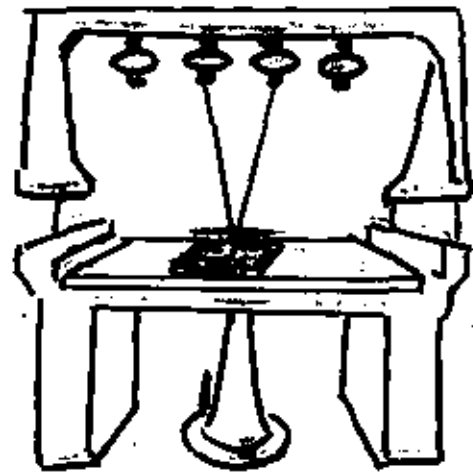
1:15000 - 1:30000

route location

instruments used for
stereoscopic studies

mirror
stereoscope

Walplex
Plotter



route location

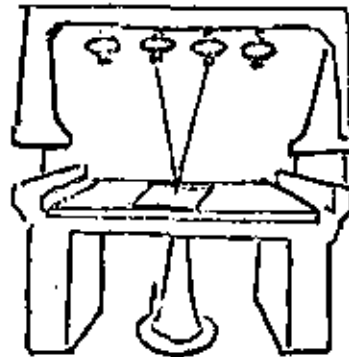
instruments used for stereoscopic studies

mirror
stereoscope

Basic of topography
and other fields
and particularly in
ship stereoscopes

Baldex
Plotter

- Together with
the hand the Map
- 1 inch



lack of new instruments
with for easy 3D-studies
in scaled models

route location

topographic

1:50000

maps

1:10000

1:5000

aerial

photography

1:30000

1:20000

route location

topographic maps

1:50000

1:10000

1:5000

national
military
community

- ecological maps

- aerial photography
National Land Survey

1:30000

1:20000

The Land Use map is based on aerial-photomap 1:10000.

- 1:10000 aerial photo
- 1:10000 aerial photo
- 1:10000 aerial photo

- 1. 1:10000 aerial photo
- 2. 1:10000 aerial photo
- 3. 1:10000 aerial photo
- 4. 1:10000 aerial photo

ecological maps
municipality
national land
survey by ponderosa

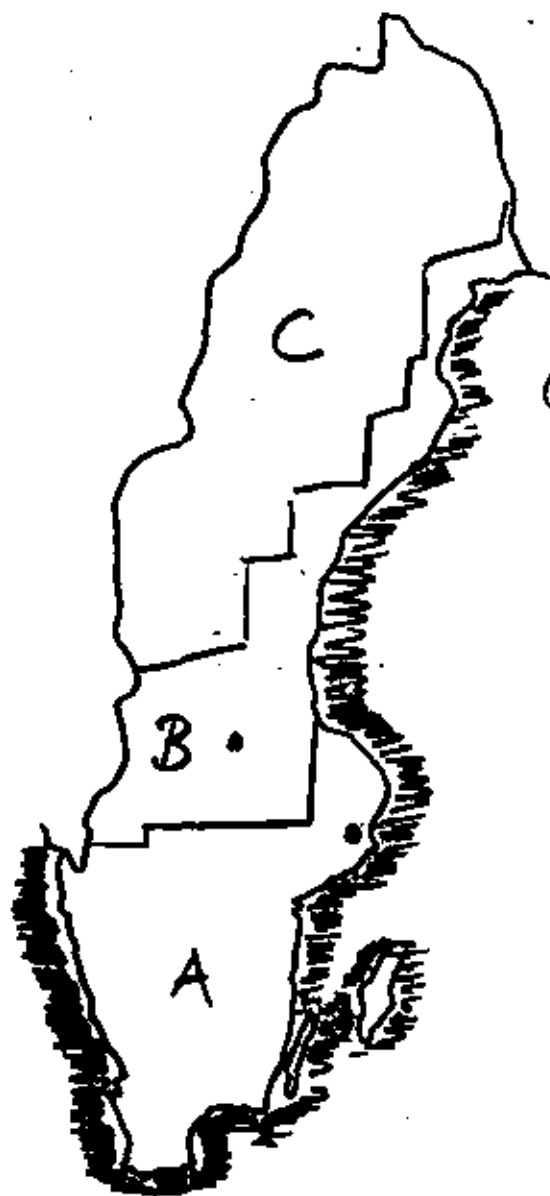
URS:

ecological maps
municipality

ecological maps
municipality

ecological maps
municipality
ecological maps
municipality

rephotography plan



aera altitude interval
m years

A 3000/4600 5

B 3000 10
9200 5

C 4600 10
9200 5

aerial photointerpretation

<u>stage</u>	<u>result</u>	<u>photo-scale</u>
route	unsuitable	1:30000
location	areas for high-way construction	1:20000
preliminary design	soil conditions	1:10000
final design		
construction	coarse	1:30000
maintenance	material	1:20000 1:10000

aerial photointerpretation

<u>stage</u>	<u>result</u>	<u>photo-scale</u>
route	unsuitable	1:30000
location	areas for high-way construction	1:25000
preliminary design	soil conditions	1:10000
final design		
construction	control	1:5000
maintenance	monitoring	1:5000 1:5000

interpretation

can engineer or specialist?

We have now a basic training in the engineering

The qualified interpretation is made by specialist
(civilian staff)

aerial photointerpretation

working procedure

inventory

geological maps

literature

previous results

interpre-
tation

rock outcrop

moraine

coarse sediments

fine sediments

organic deposits

field check

compilation
of data

soil map

1:10000

1:50000

aerial photointerpretation

working procedure

inventory

geological maps
literature
previous results

any communities involved (consultation)

interpretation

rock outcrop
75% moraine

characteristic landforms
and processes (natural
and human activity)

+ coarse sediments
fine sediments
organic deposits

identify stability problems
to the rock body

field check

documentation
of data

soil map 1:10,000
1:50,000

soil photointerpretation

1. knowledge of soil conditions, potential problems early

2. expensive and time-consuming boring can be limited

3. can be made by a group in need of it

aerial photointerpretation

instrument used

mirror

stereoscope

Stereo Facet

Plotter

aerial photointerpretation

instrument used

1940-1950
Stereoscopes

Steno-View
M. H. G.

OMI, Italy

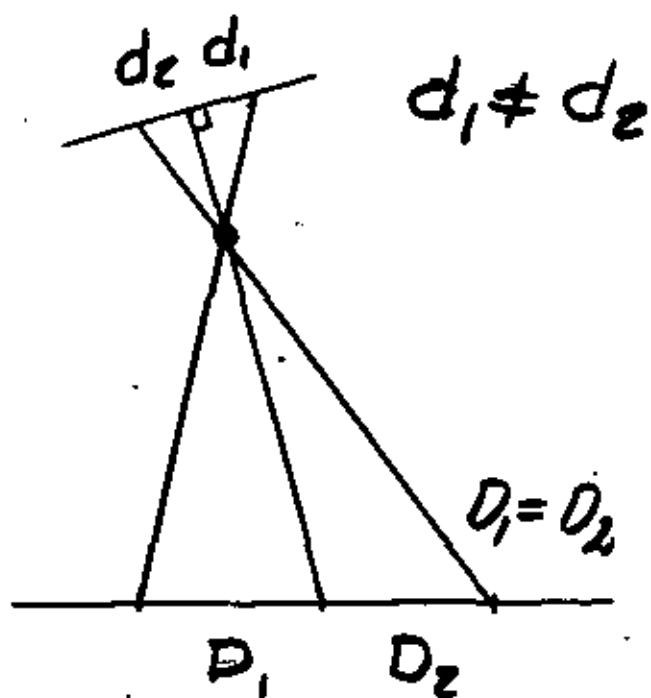
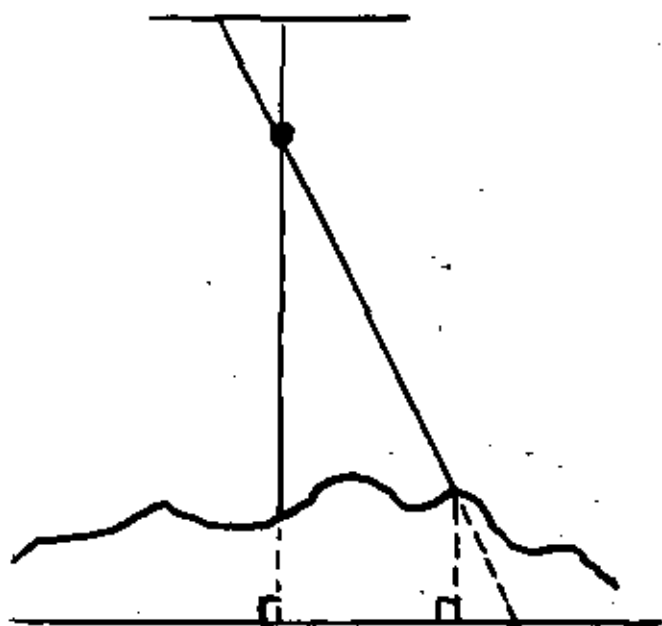
compensator:

- conformal distortions (scale differences)
- perspective -- " -- (collimation between lens and photograph)
- affine -- " -- (inclination of facet in orthogonal projection)

orthogonal
projection
(map)

\neq

central
projection
(photo)

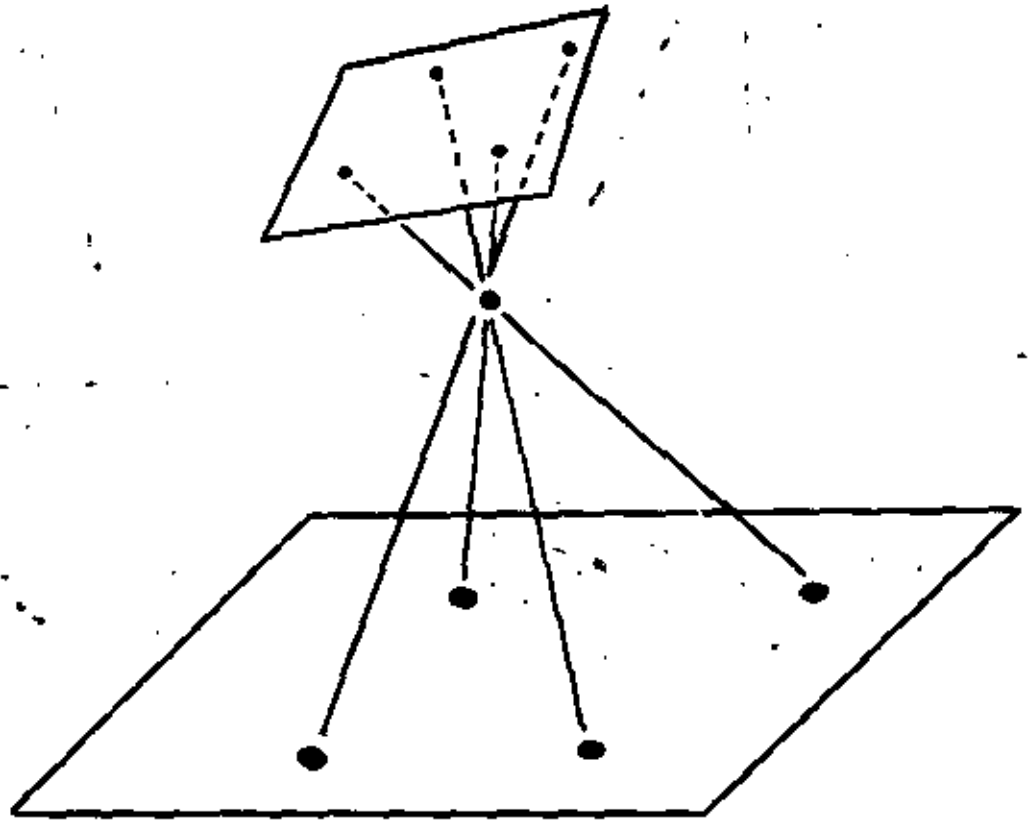


topography

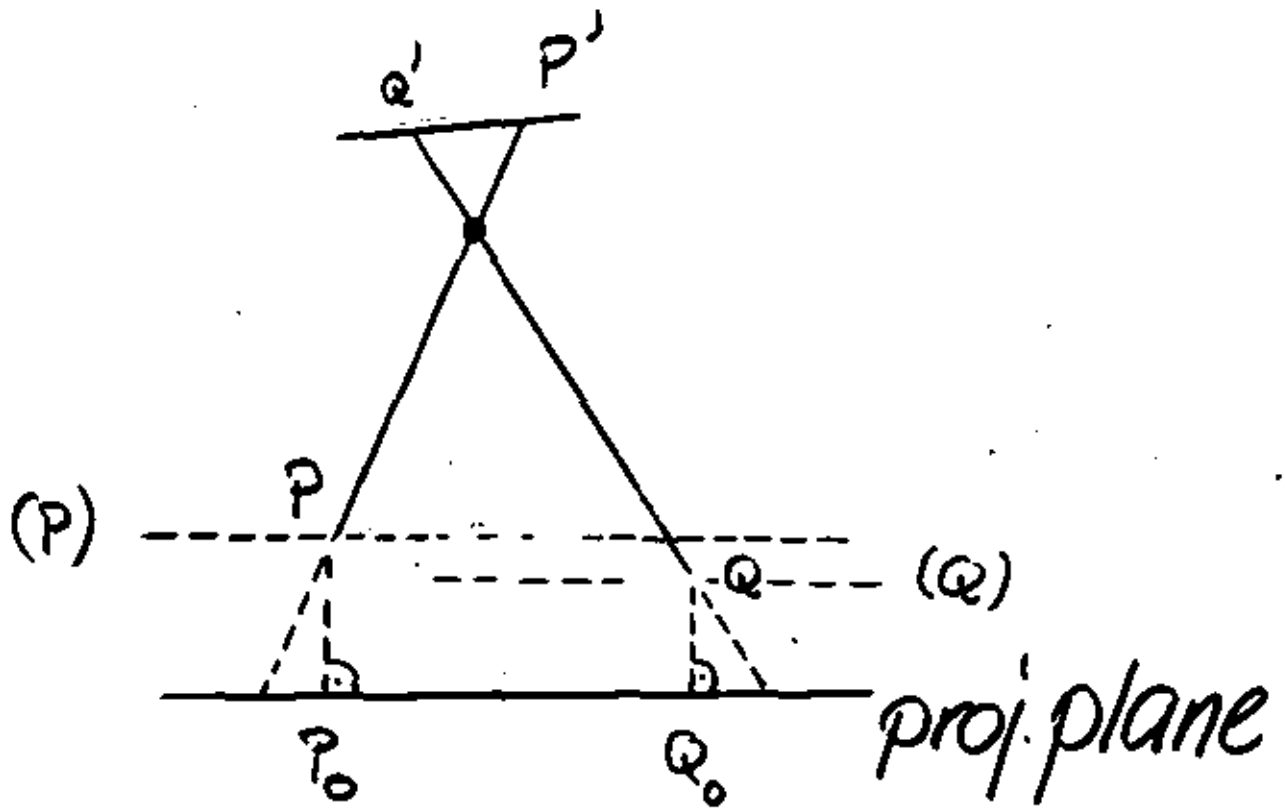
tilt of photo

Rectification

≥ 4 given points



principle of orthophotos



∴ height information
necessary

Orthoptische

1920
orthoptische 1953-57
explorativ 1964 - Zweis-Linje

~~normalvisningskammer~~ = Visningskammer
jfr med vidvinkel
men vidvinkelkammer = en högre höjdutveckling

normalvisning för fuktare
supravidvinkel i höjd

3-4 ggr snabbare än till utveckling

Nackdelar

- utveckling av objekt (biljor etc)
- bildutveckling nödvändig
- höjdhöjningsförändring

visningskammer för utveckling - med utveckling
jfr normalvisning

Sto-ortoptisk

an orthophoto

differentially rectified
photograph

an orthophoto mosaic

joined orthophotos

an orthophoto plan

orthophoto (mosaic)

enhanced by planimetric

details

an orthophoto contour map

orthophoto (mosaic)
with contours

an orthophoto map

orthophoto plan
with contours

orthophoto instruments

optical projection

Zeiss GZ-1

Wild Avioplan OR1

electronic image transfer

Gestalt Photomapper

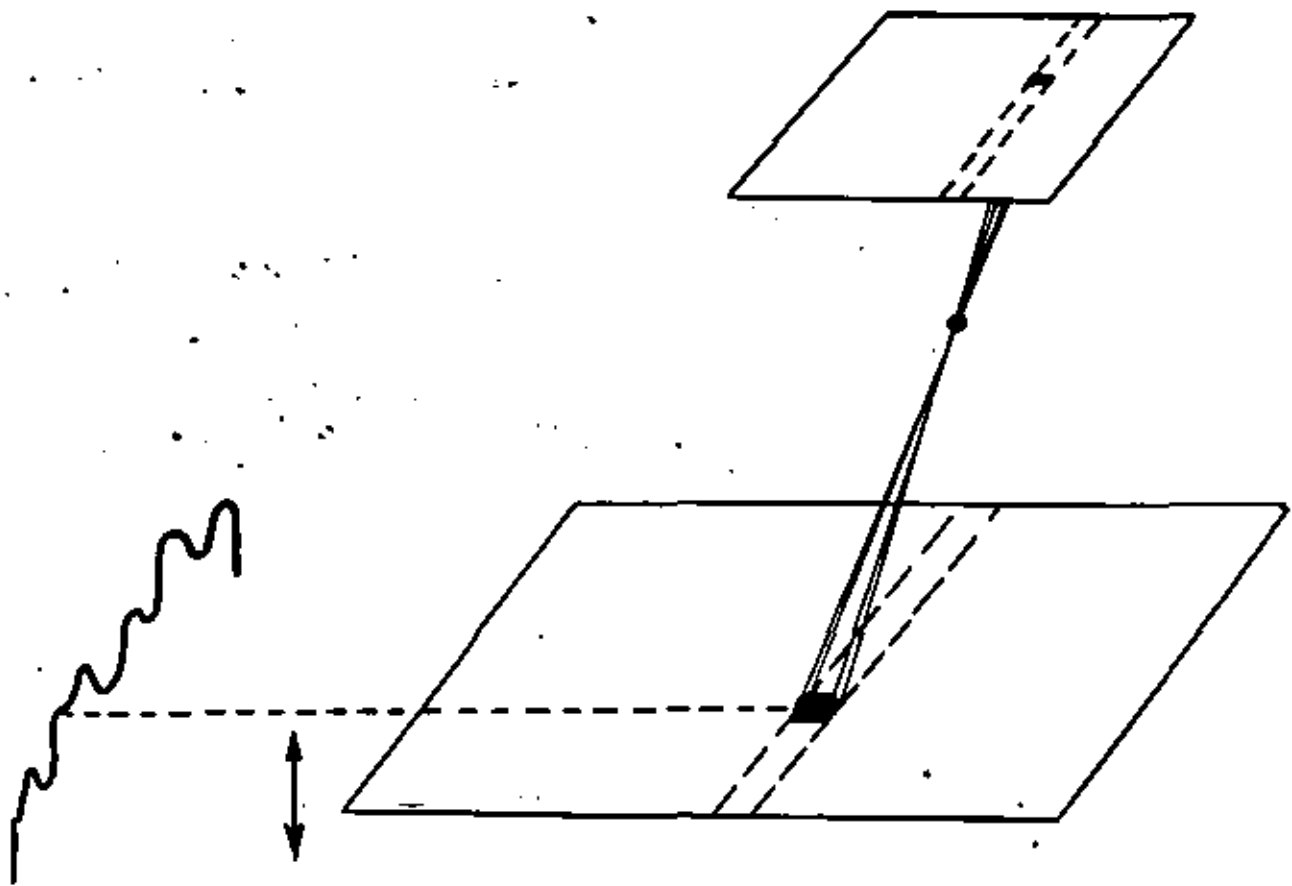
on-line

off-line

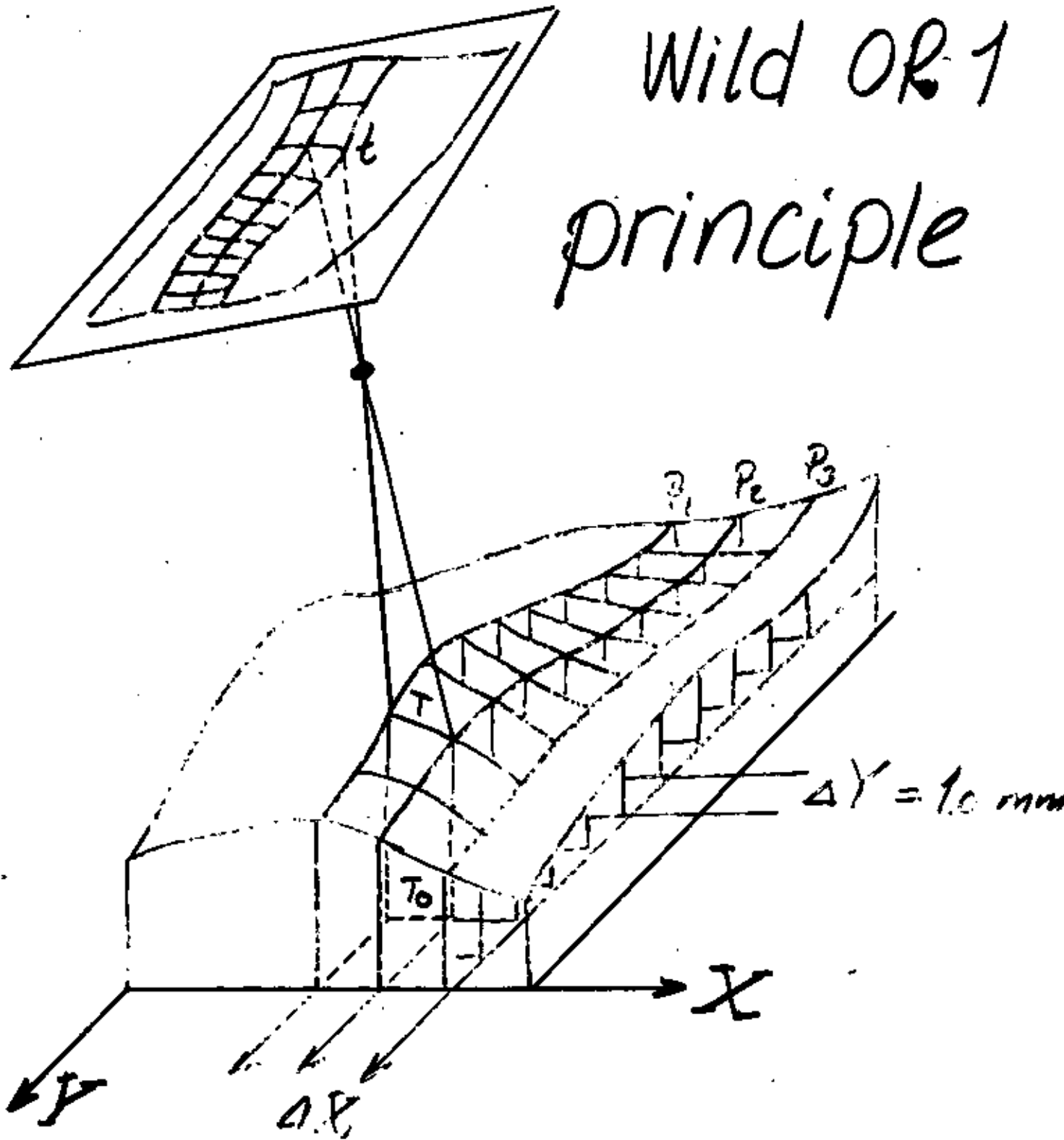
Ortho photo system

Gigas-Zeiss GZ 1

- ① profile measurement
- ② ortho-projection



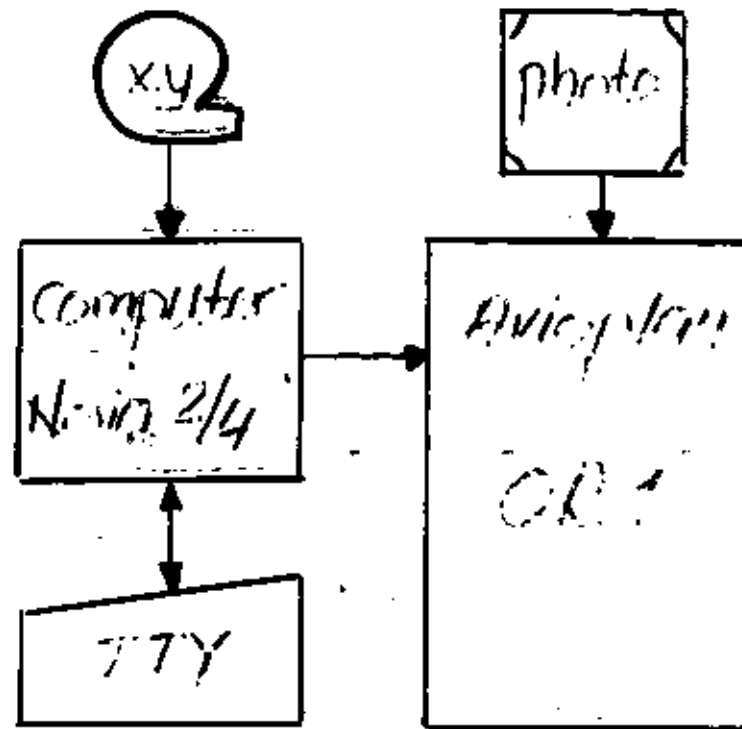
Wild OR-1 principle

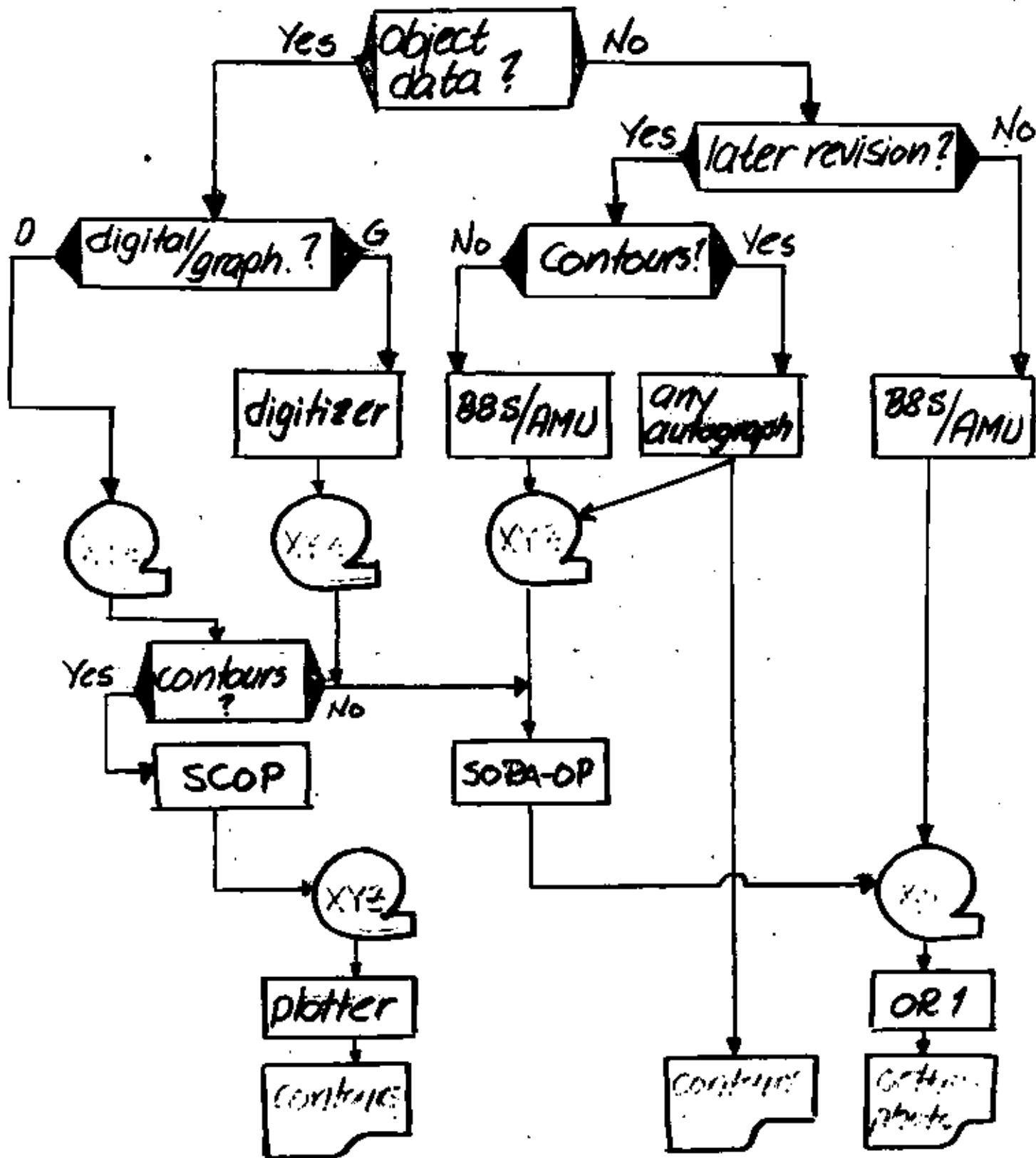


Wild OR1

- off-line operation
- enlargements $0.25x \rightarrow 15x$
- slit masks $0.1\text{ mm} \times (5-12)\text{ mm}$
- max. proj. speed 30 mm/sec
- day-light operation
- any-c-value
- flexible data acquisition
- unconventional projections

OR 1 basic configuration





Wild OR1 production rate

- a double model (60%, 20%)
- 4x photo \rightarrow orthophoto

	<u>hours</u>	
profiling	3.75	
contouring		8
ortho projection	0.75	0.75
	<hr/>	<hr/>
	4.50	8.75

Gestalt Photo Mapper II

- computer-controlled
- auto-correlating

9x8 mm patches

with 2444 points each

- diff. rectification in < 1 sec
- analytical plotter
- electronic image transfer

GPM II

speed: ≈ 1.5 hours for
one model

GPM Plotting System

Mini computer

Data General Nova (40k)

10 MByte disk

plotter (contours

from DTM)

GPM II output

photographic

orthophoto 20x25 cm

stereomate

contours

digital

DTM on mag. tape

($\approx 700\,000$ points/model)

accuracy of ortho-photos

ISP Working Group 1972-76

distributed material

one stereomodel

1:10000 60%

Wild RC8 10 mm resolution

camera calibration data

six targeted (XYZ)-points

paper prints

some aspects on orthophotography

① flight planning
long c-value
double-models
3-5x enlargement
80-90% overlap

② photography
correct exposure
uniform contrast
b/w (color)

③ data acquisition
image profiles
model profiles
contours

WG II-4

test material

- 1 stereopair 1:10000 60%
Wild RC8 (1 cm reseau) 15/23
- camera calibration data
- 6 targeted XYZ-controlpoint

WG II-4

participants provided

- original orthophoto negatives from both photographs (1:2500)
- contour lines/drop lines
- recorded profiles

WG II-4

control data

XYZ for reseau points
measured in A7
(+ 40 natural points)

xy for control points
measured in mono-
comparator

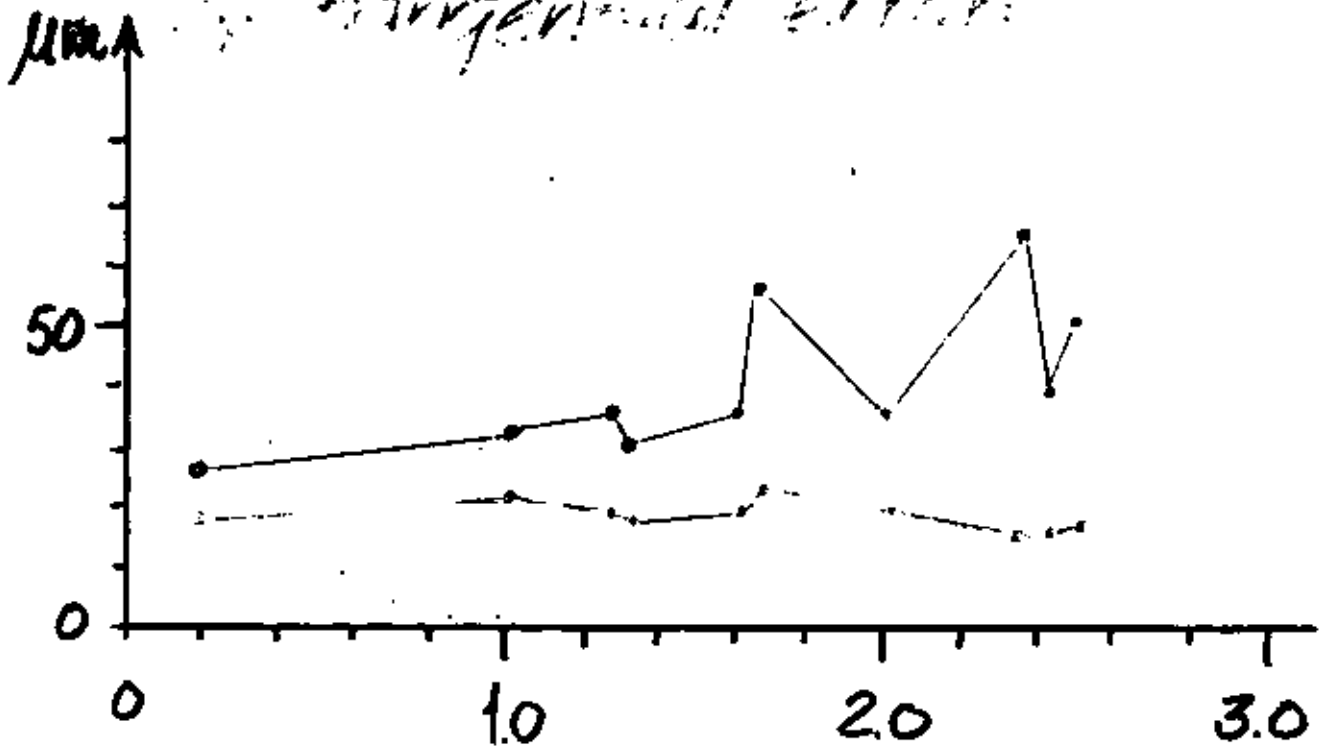
WG II-4

results

10 participants

s_r radial errors

s_t tangential errors



slit length, mm
at photo scale

orthophoto vs. conventional mapping

+

contains
all info

fast (5-10x)

semi-automated
process

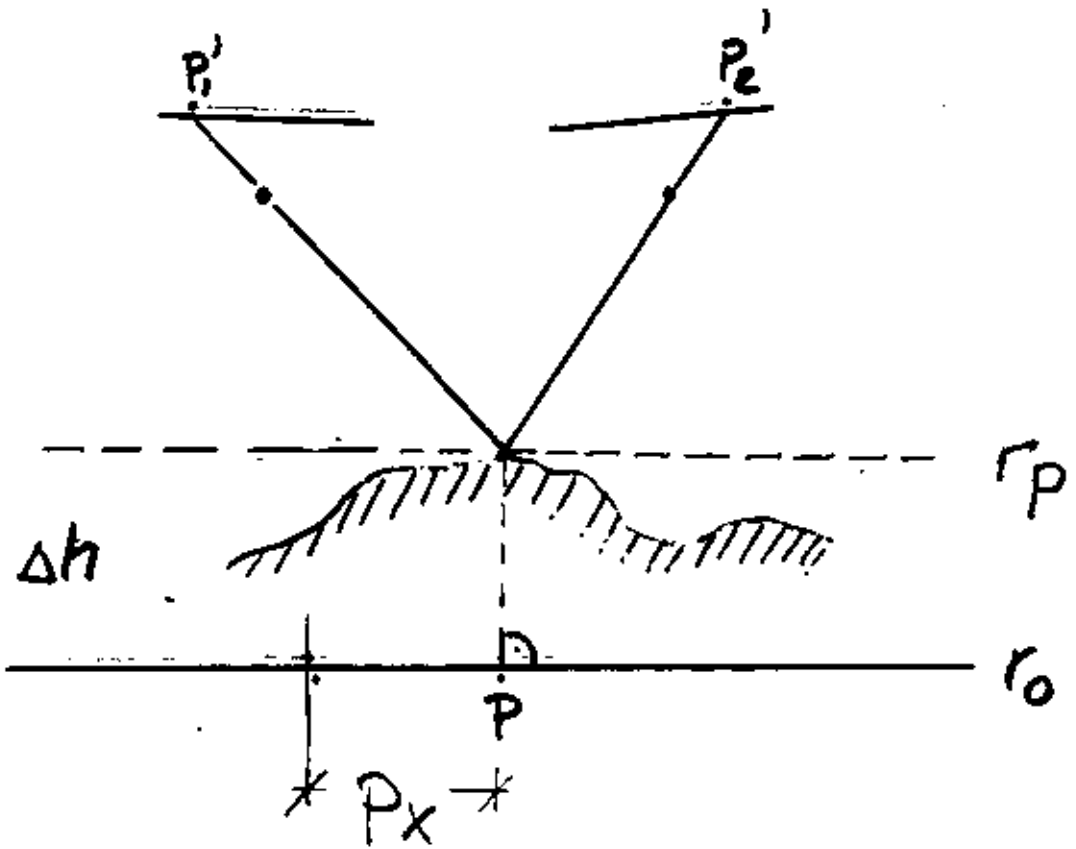
-

non-relevant info
interpretation
by user

radial displacement
of vertical
objects

restricted
vertical info

stereo-orthophotos



$$P_x = \text{const.} \cdot \Delta h$$

oblique parallel projection

orthophotos in Sweden

① the National Land Survey
land use map 1:10000

GZ1 1968

OR1 1978

② communities

orthophotomaps 1:5000

③ the National Road Adm.

trials with orthophotos
in 1:1000 and 1:2000

orthophotos in Sweden

the National Land Survey

a nation-wide DTM

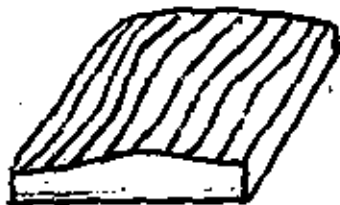
50x50m or 100x100

25%



contours

25%



stereo-
models

50%



GZ1-
profiles

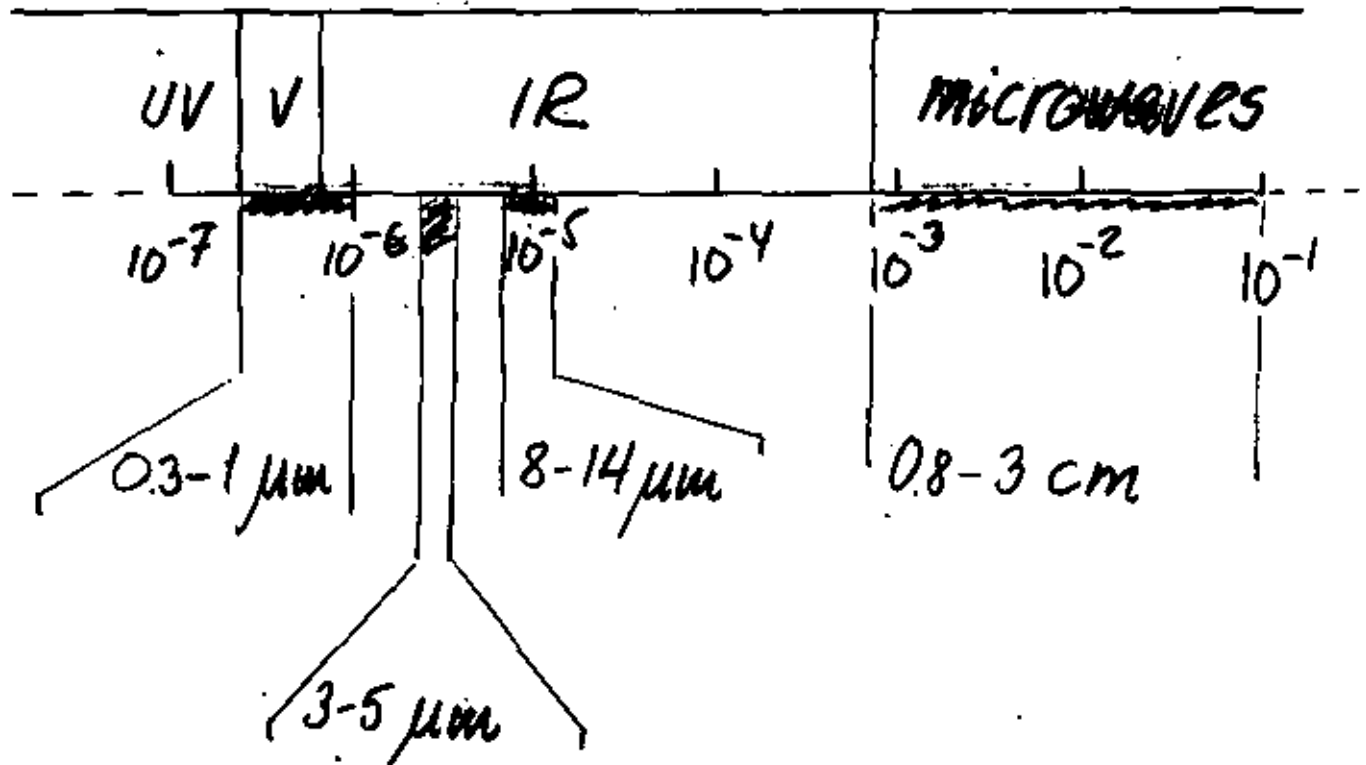
remote sensing

spectrum

UV = ultraviolet

V = visible

IR = infrared



Remote Sensing

spectrum, four windows, visible & near IR 0.4-1.0
 middle IR 3-5, far IR 8-14

H₂O CO₂
 water vapor carbon dioxide

}
}
}
 active passive sensors
 resolution: Landsat scanner 0.65 mrad
 Airborne - 11 - 2.5 mrad

TV visible - near IR central perspective effect
 scanners visible - near IR five scans at a time multispectral
 visible - IR

Resolution	SPOT/AS	Landsat 1	Landsat 2	Landsat 3
Year	1973	1972	1975	1978
Scanners	RBV	3 (3 bands)	3 (3 bands)	2 (1 band)
		same area		different area
		185 x 185 km		
		pixel	80m x 80m	60m x 60m
		1000	1000	1000
		2000	2000	2000
		2000	2000	2000
		6000	6000	6000

Data acquisition: receiving data from satellite on magnetic tape.

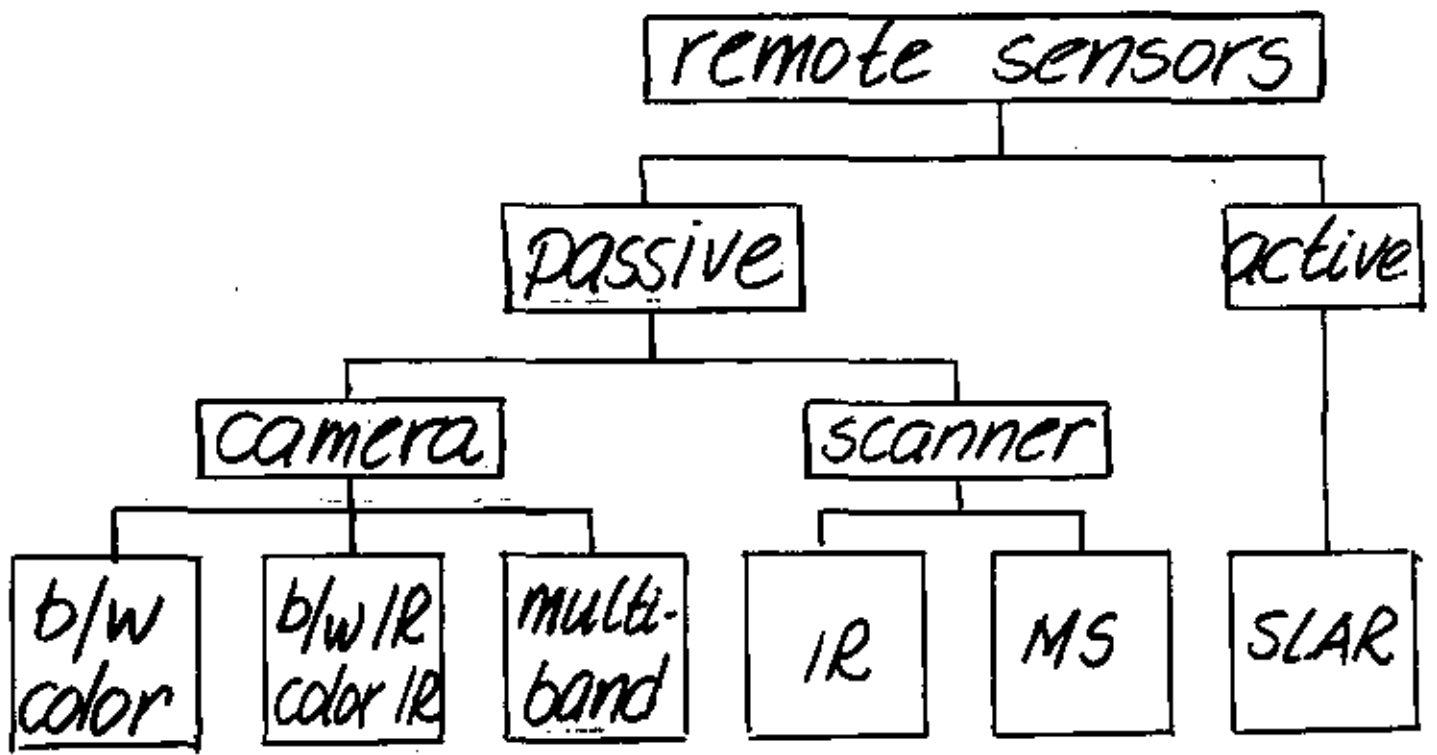
File processing: 3000 min pictures 134 min.

File processing: 2000 min pictures 134 min.

Map characteristics: large areas of land cover, multispectral, digital data, repetitive coverage

Interpolation

Local Global
 Digital



remote sensors

active

SLAR

passive

camera

TV

scanner (MSS)

platforms

aircraft

satellites

satellites

LANDSAT1 LANDSAT2 LANDSAT3

year 1972 1975 1978

sensors

RBV	3 (3 bands)	3 (3 bands)	2 (1 band)
MSS	0.5-0.6 μm	0.5-0.6	0.5-0.6
	0.6-0.7	0.6-0.7	0.6-0.7
	0.7-0.8	0.7-0.8	0.7-0.8
	0.8-1.1	0.8-1.1	0.8-1.1
			10.4-12.6

LANDSAT - SCENES

area $185 \times 185 \text{ km}^2$

time interval 18 days

pixel $80 \times 80 \text{ m}$ (40x40)

interpretation
visual
digital



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FOTOGRAMETRIA EN EL DISEÑO Y CONSTRUCCION DE OBRAS
DE INGENIERIA CIVIL

ACTIVITIES IN FINAL DESIGN

ING. BULMARO CABRERA RUIZ



activities in final design

%	
36	office work
9	miscellaneous
14	soil investigation
14	levelling
15	setting out
12	traverse measurement

Wednesday

final design

new aerial
photography (1:5000)

second order
traverse



products

large-scale maps (1:500 or 1:1000)

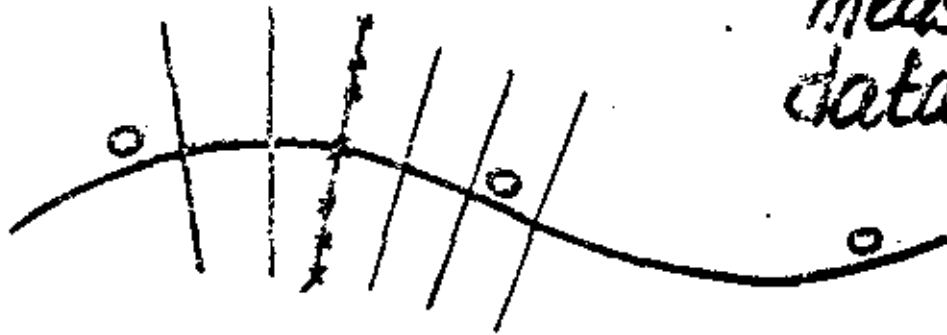
numerical measurements

longitudinal profiles

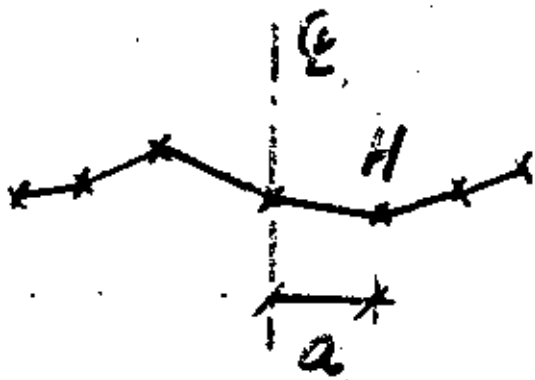
cross profiles

digital terrain model (DTM)

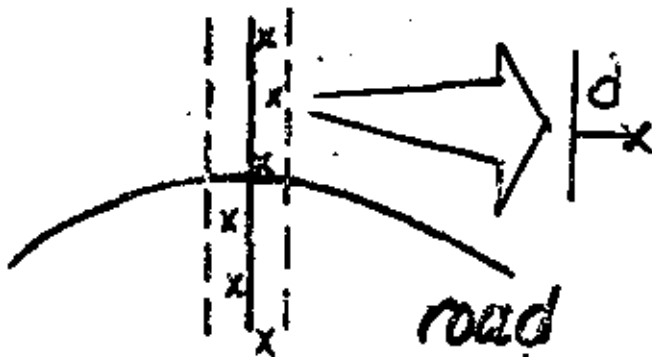
profile measurement



measured
data: $xyz(\text{model})$



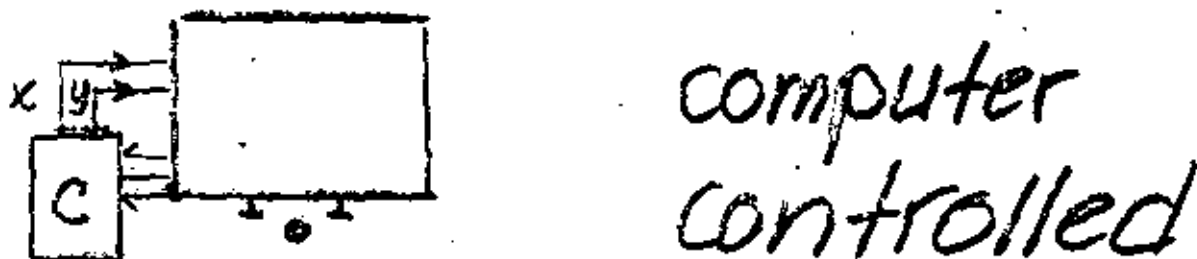
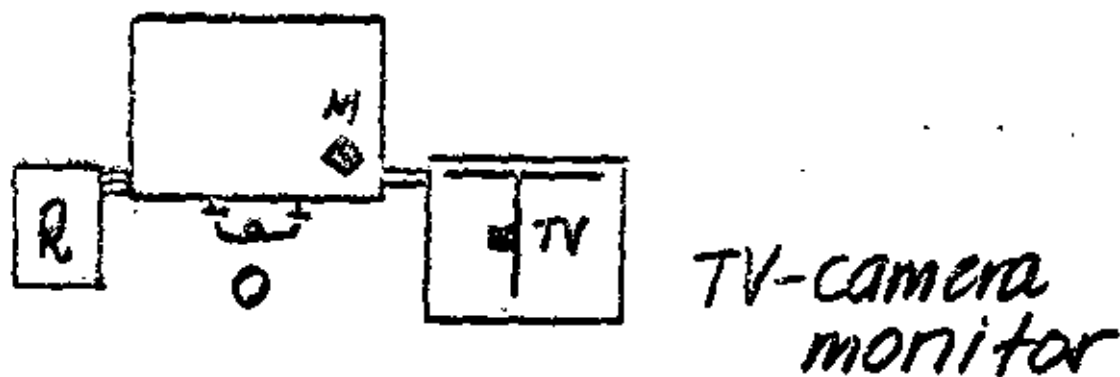
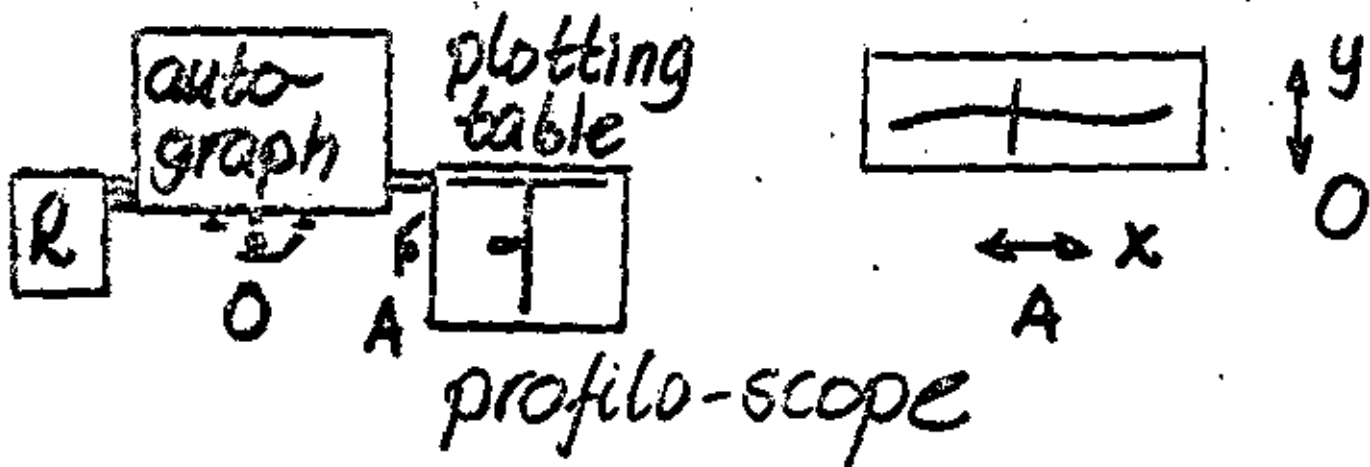
result: a, H



check: $\frac{\sum d}{n}$
 $\sqrt{\frac{\sum d^2}{n}}$

road
centre line.

operation

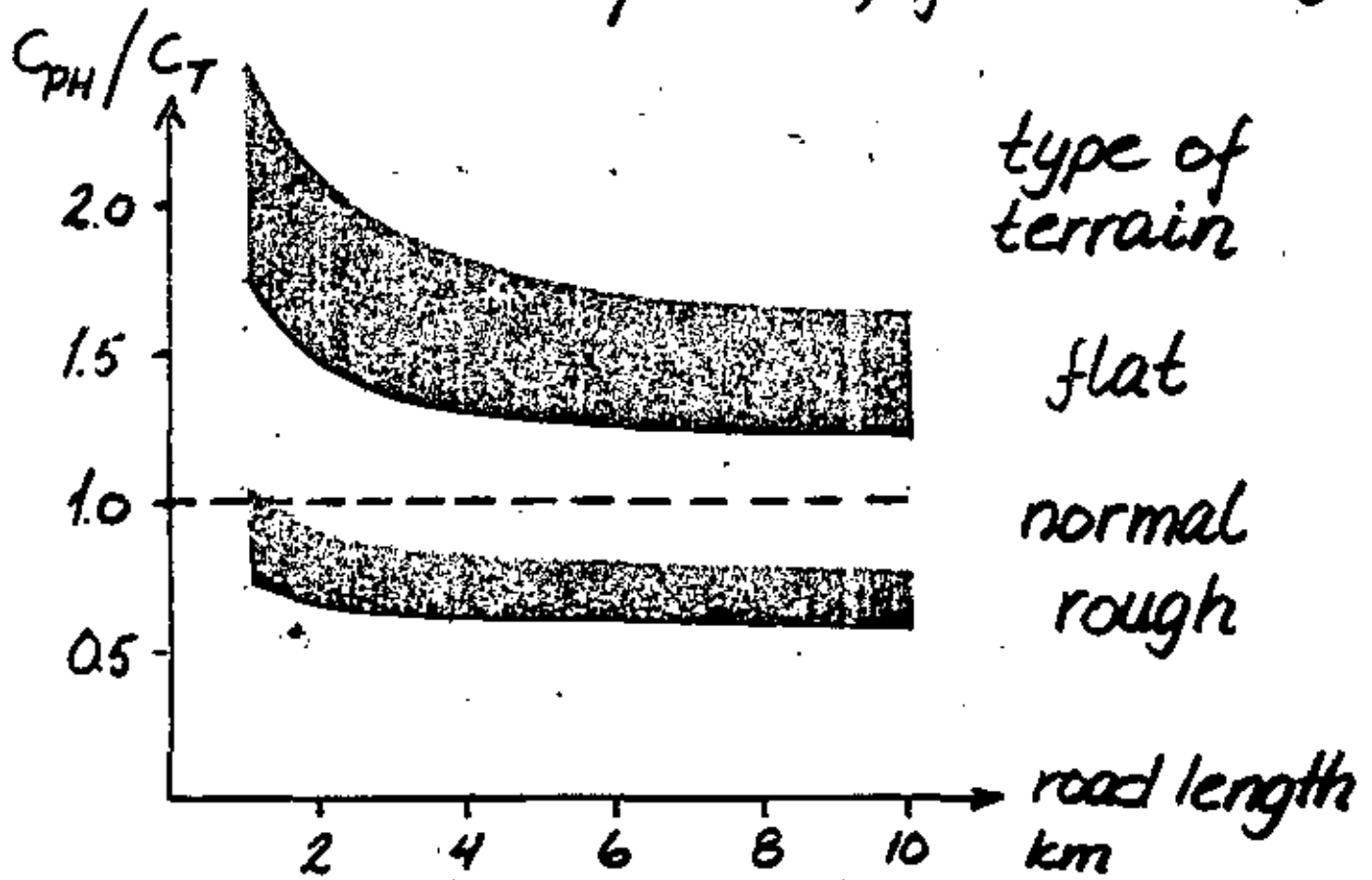


photogrammetric
cross-sectioning

- + fast measurement
- homogeneous quality
- less blunders
- season dependent
- systematic errors

cross profile measurement

economic aspects, final design



C_{PH} = costs, photogrammetric meas.

C_T = -||- terrestrial measurement

cross profile measurement

economic aspects,
results of a study

type of costs

- aerial photography
- geodetic control
- stereo measurement
- data processing

type of terrain	cross profile interval	no. of points per profile
flat	20 m	5
normal	20	10
rough	10	20

cross profile measurement

systematic errors

photos: distortion

refraction

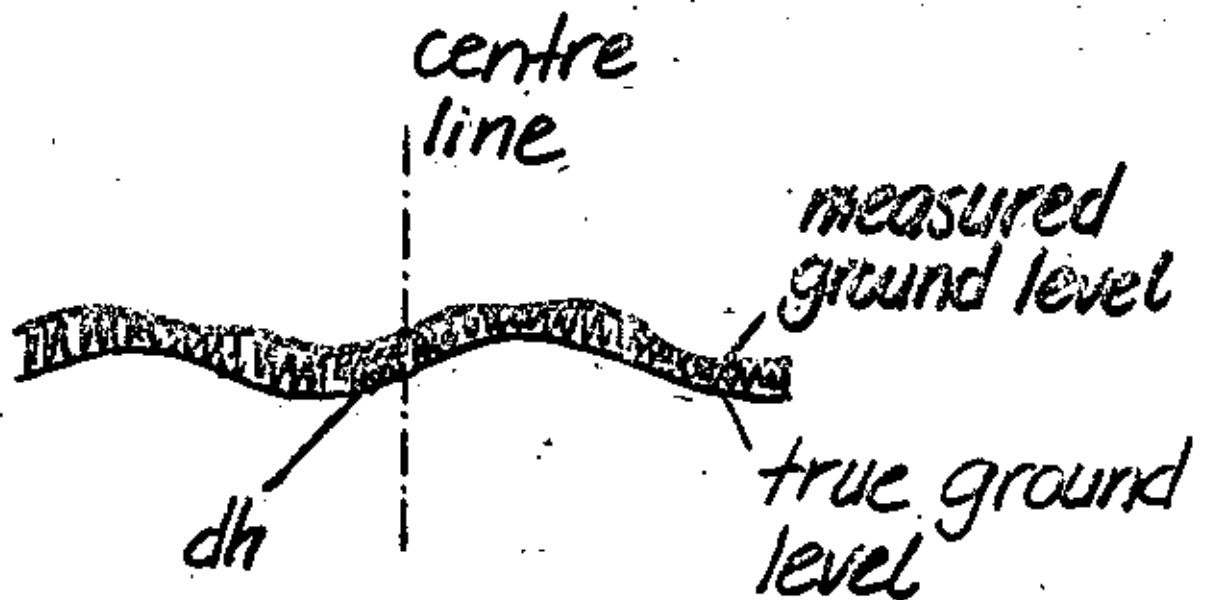
earth curvature

instrument

orientation

vegetation

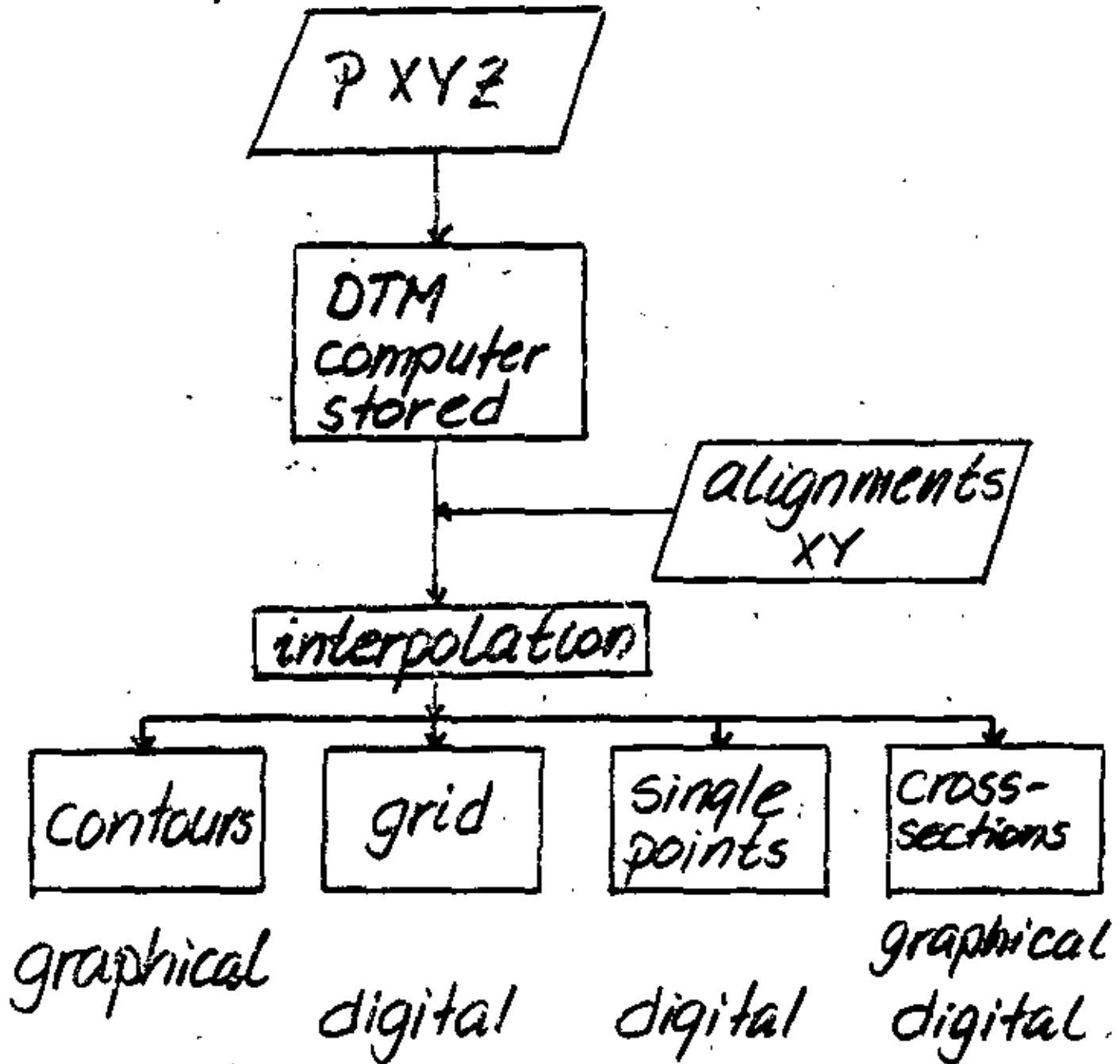
reduction of errors due to vegetation



dh from levelling in the field
and applied to the whole
cross profile

Digital Terrain Model (DTM)

concept

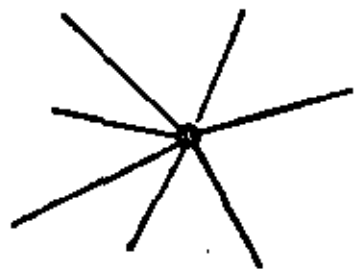


Digital Ground Model (DGM)

- ground surface
- max. 7 layers

primary data

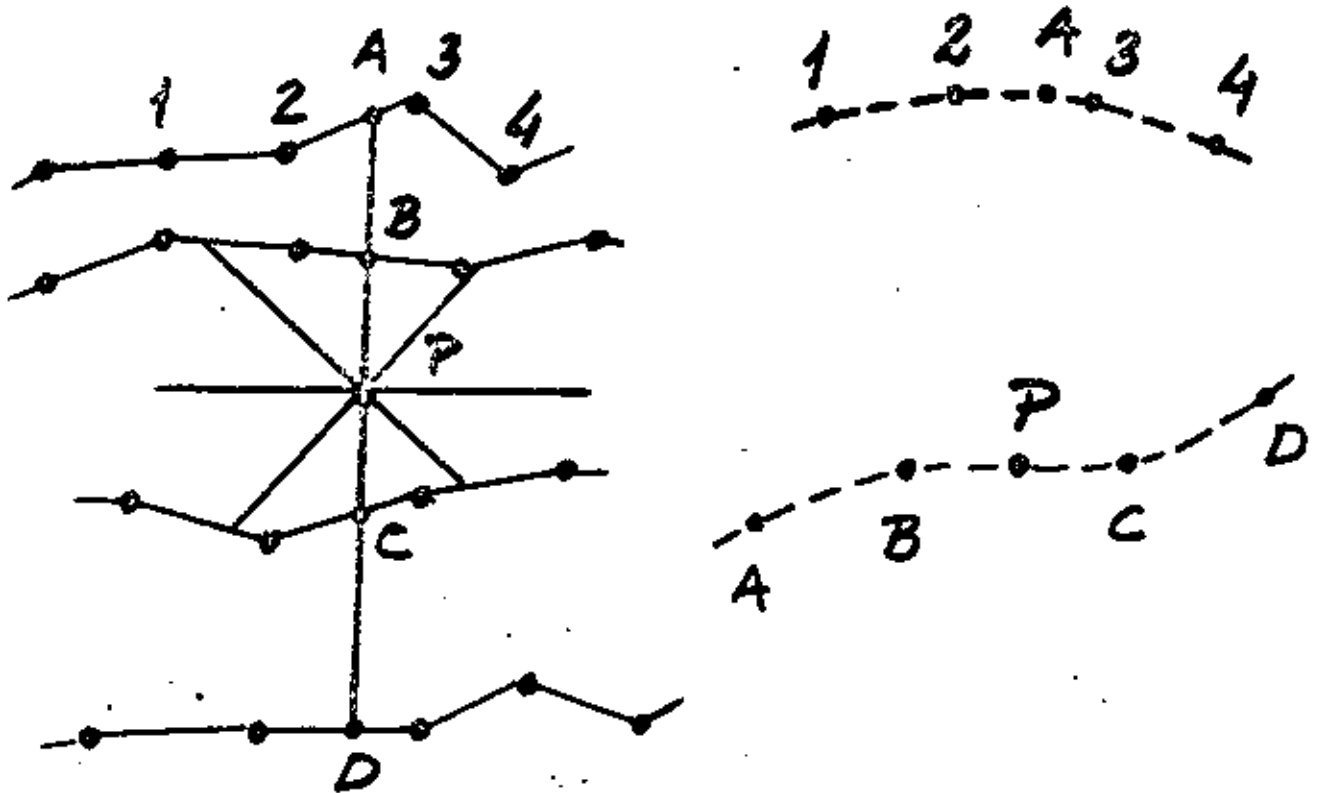
- terrain lines



- break lines



DGM interpolation

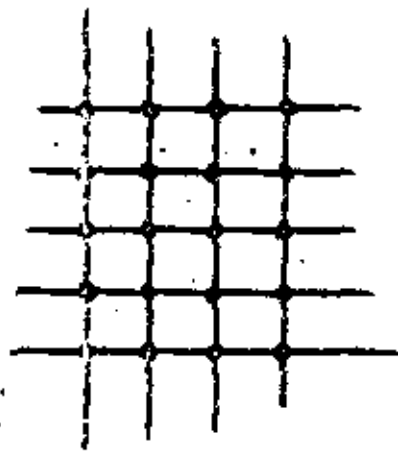


- 1) shortest "50° intersection"
- 2) A, B, C, D with 1st, 2nd or 3rd degree interpolation
- 3) P from A, B, C, D in the same way

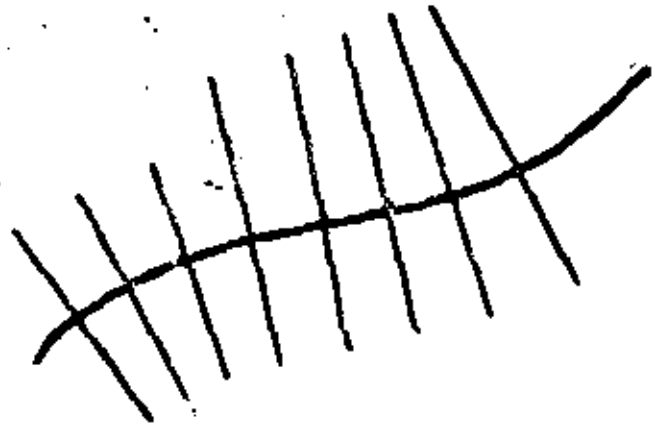
DGM

secondary data

regular
grid



cross
profiles



data acquisition

photogrammetry

geodesy

cartography

instruments

methods

photogrammetric instruments for DTM

type	info	operation	small scale	large scale
stereocomp.	$x'y'x''y''$	manual	-	-
analogue instr.	xyz	manual semi-automatic	+	+
analytical plotter	xyz XYZ	semi-automatic	+	+
correlator	xyz	automatic	+	-

interpolation

procedures

linear

bilinear

2nd degree functions

other functions

interpolation

principles

- A) I regular grid from primary data
 - II heights from grid
- B) I interrelations e.g. triangular facets
 - II heights within facets
- C) heights from primary data

methods

manual
computer assisted
computer controlled

selection

automated recording

random points	—
break lines ("strings")	—
contours	$\Delta S \Delta t \Delta x \Delta y$
parallel profiles	$\Delta S \Delta t \Delta x \Delta y \Delta z$
regular grid	$(\Delta x) (\Delta y)$
cross-sections	$(\Delta S) (\Delta t)$

results

Technical University
of Hannover, W. Germany 1979

aerial photography

test 1:4000

check 1:1800

instruments

Wild A10 / EK22

Zeiss Planimat / Ecomat II

-"- Planicart / PDP8

OMI AP/C-3

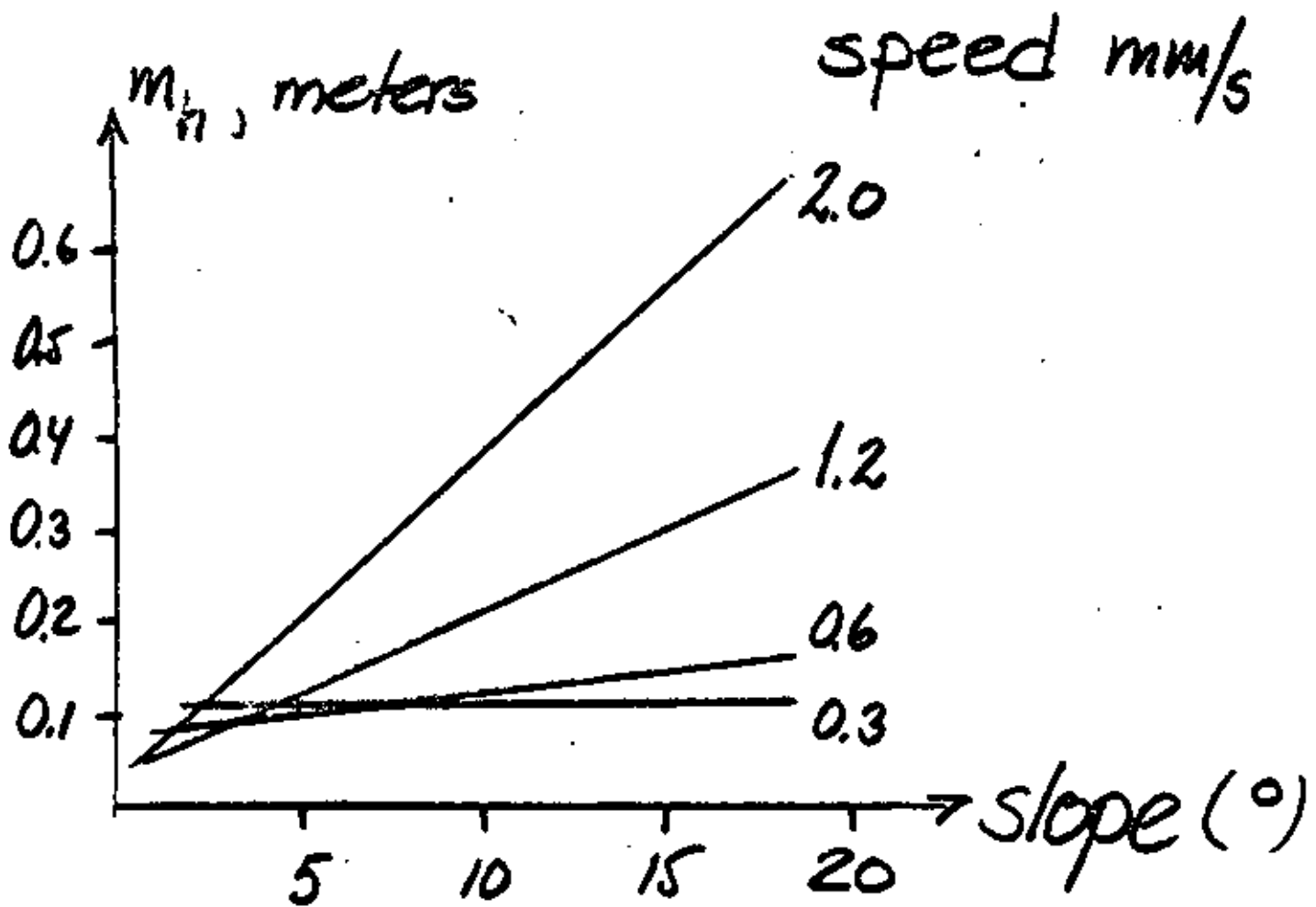
results

accuracy of measuring methods

random	0.07 m	(0.1‰H)
grid	0.07 m	
contours	0.13 + 0.4 land, m	

results

accuracy of continuous profiling



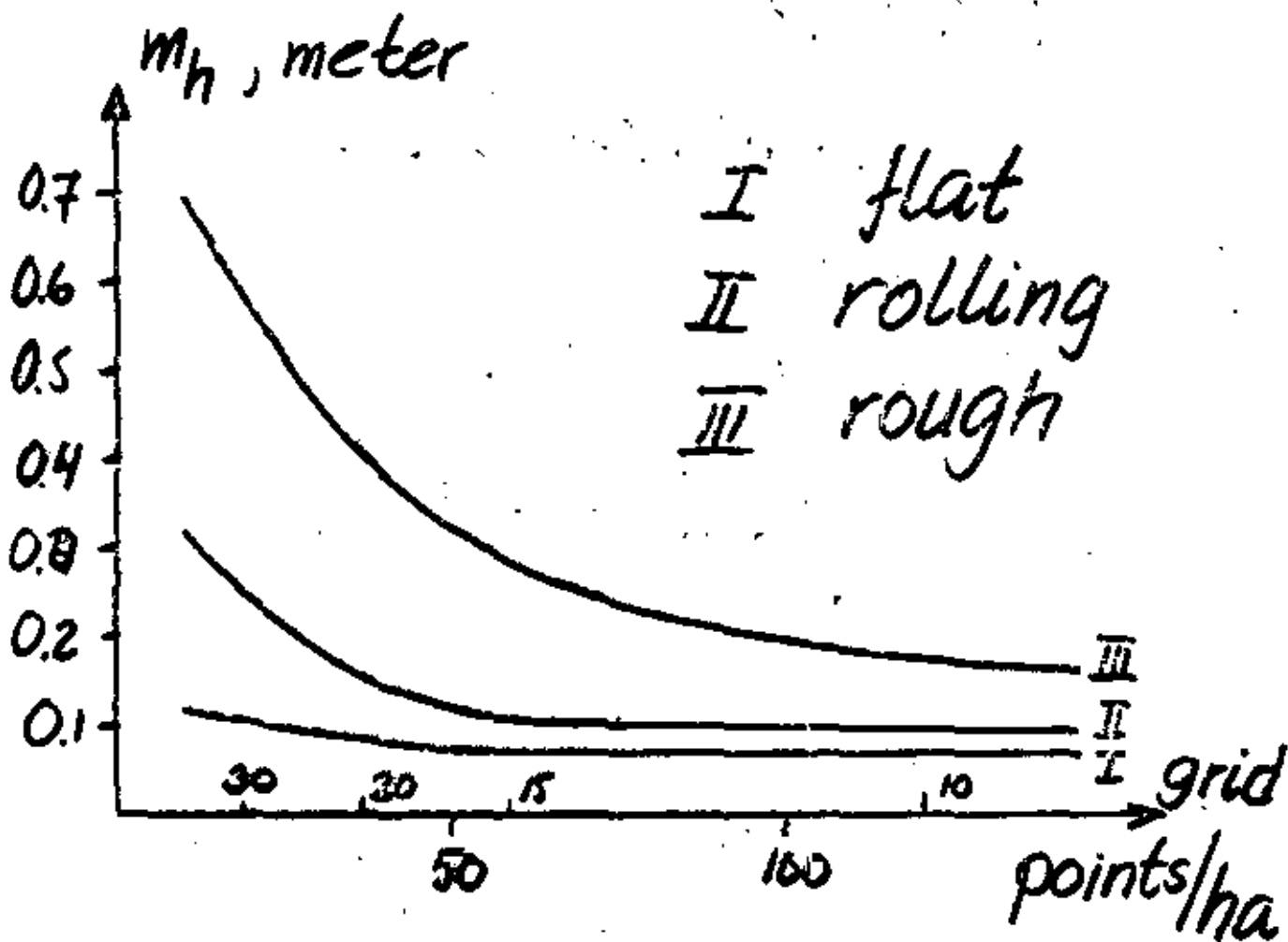
results

accuracy of measuring methods

random	0.07 m	(0.1‰H)
grid	0.07 m	
contours	0.13 + 0.4 tan α , m	

results

interpolated heights



DTM results

profiles

cross-sections

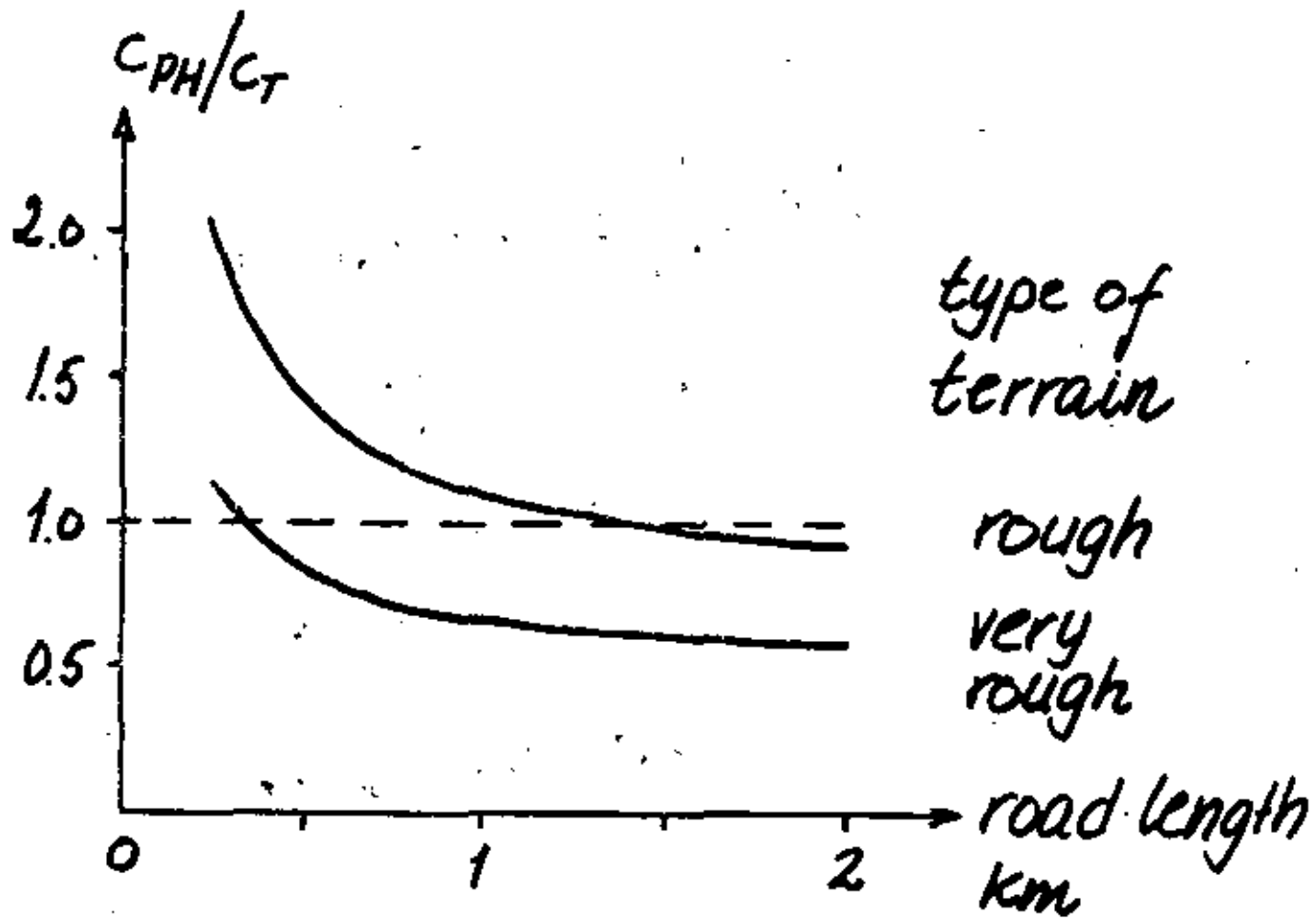
volumes

contours

perspectives

Construction stage

cross profiles



C_{PH} = Costs, photogrammetric meas.

C_T = — — —, terrestrial measurement

DTM application

design

highways

interchanges

railways

power lines

air ports

residential areas

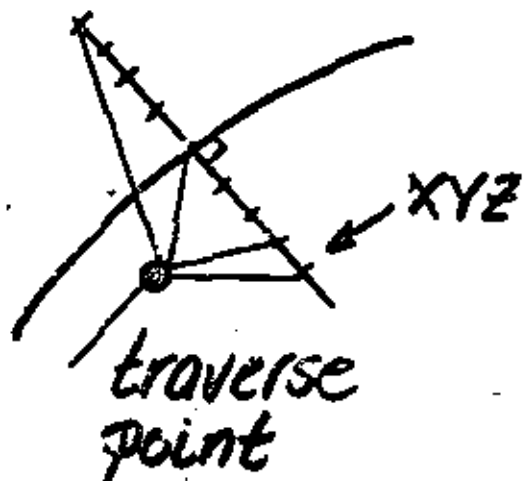
industrial areas

open mining

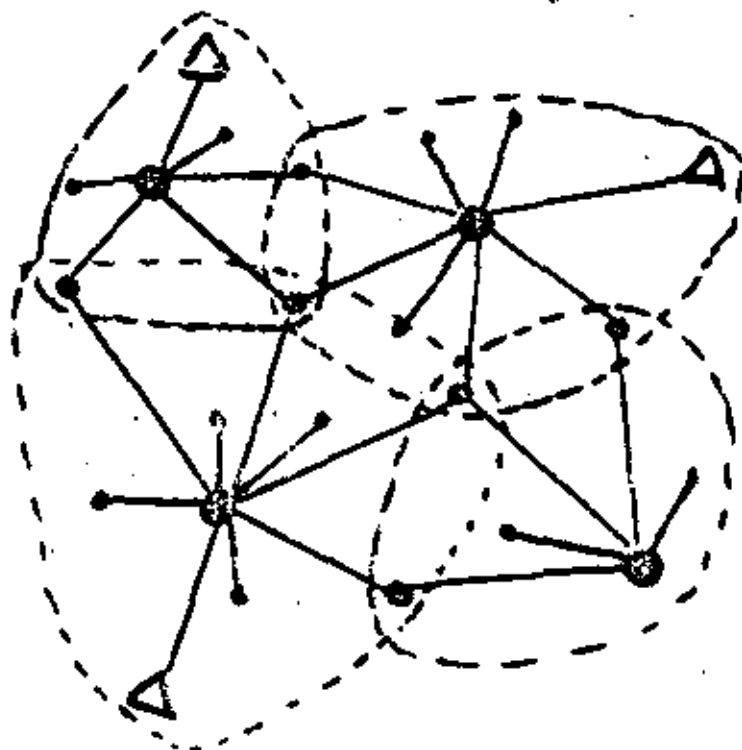
ortho photo-production

combination of photogrammetric and terrestrial surveys

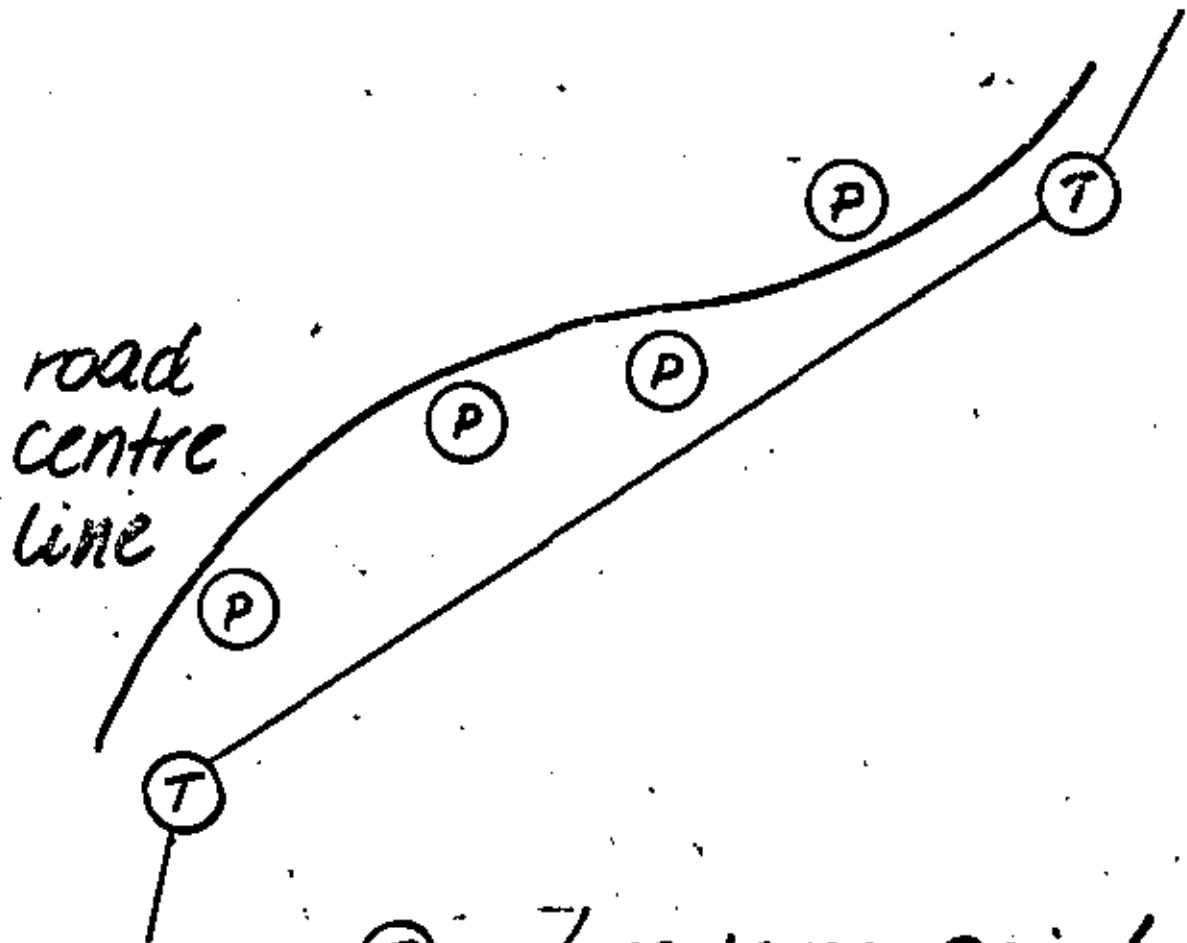
polar
cross profiling



terrestrial
blocks



photogrammetry and setting out



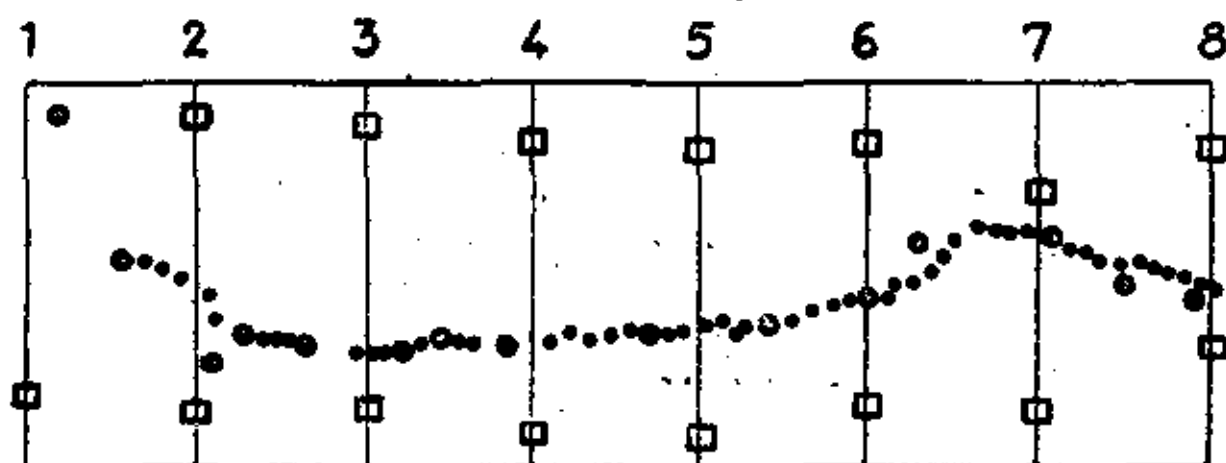
⊙ T = Traverse point

⊙ P = point with coordinates determined by photogrammetry

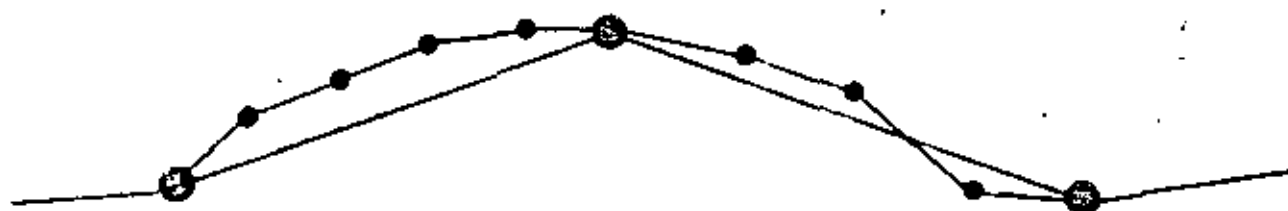
test area

Rv 32 Tranås—Sommen

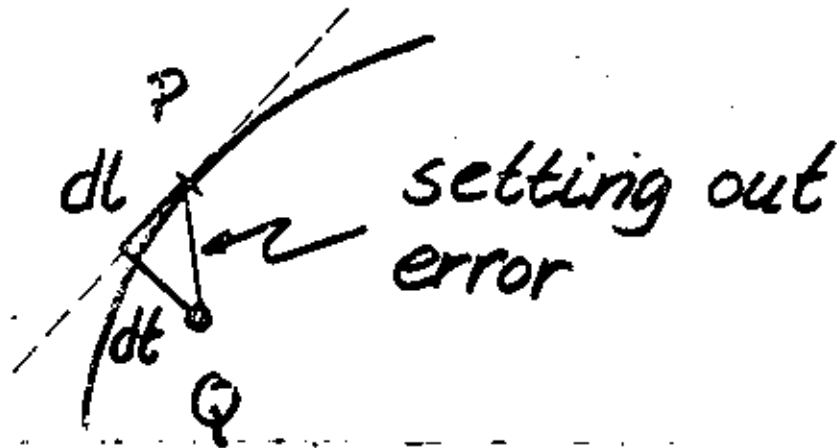
flying height: 15000 m (1:10 000)



- - XYZ-control
- - Z-control
- - photogrammetric point



photogrammetry and setting out



dl = longitudinal error

dt = transverse error

photogrammetry and setting out

results of a study

	No. of points	root mean square values, m			
		dx	dy	dl	dt
"photo" stations	51	0.04	0.05		
road centre points	320			0.07	0.05

photo scale 1:10000

autograph Wild A10

data processing

large computers

SABAB D22

UNIVAC 1100

desk top calculators

HP9820

HP9825

HP97

pocket calculators

HP45

HP25

HP65

HP67

data processing

computer programs

data handling

surveying

road alignment

ground data

road cross sections

setting out

design presentation

earthworks

photogrammetry

production planning

bridges

geotechnique

terrestrial photogrammetry

principles

photography

control points

evaluation

+/-

accuracy

planning

application

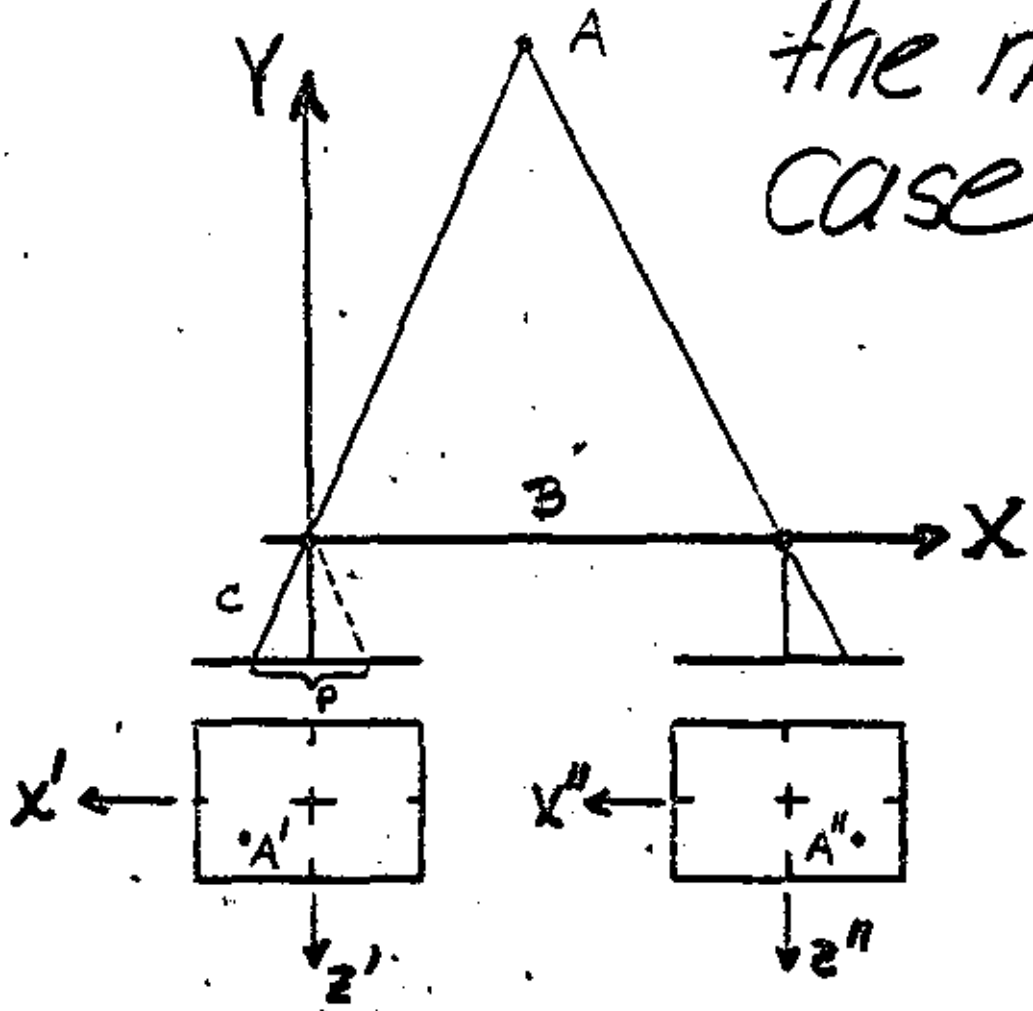
engineering

deformation

documentation

Thursday

the normal case



$$\frac{Y}{B} = \frac{C}{p}$$

$$Y = \frac{BC}{p}$$

$$X = \frac{Y}{C} X'$$

$$Z = \frac{Y}{C} Z'$$

photography

camera

{ metric
non-metric

{ single
stereo

emulsion
base

{ glass plates
cut sheet film
roll film

photography

normal case

fixed base

free base

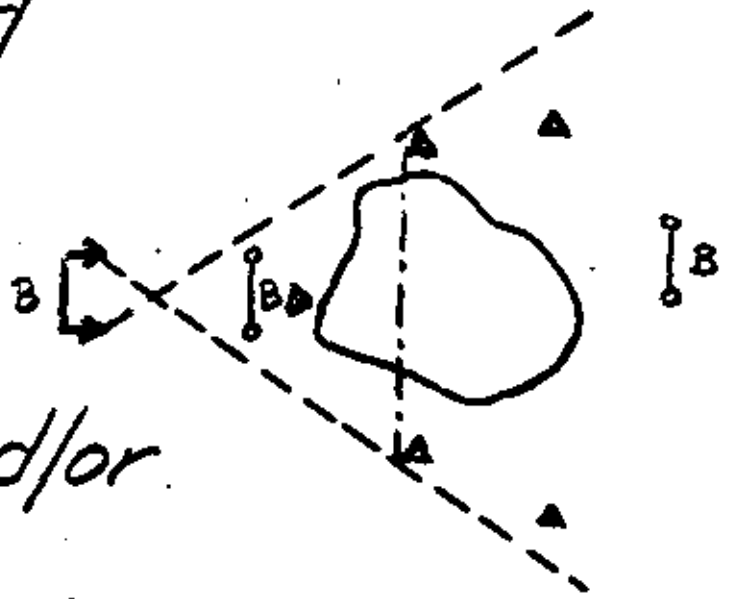
tilted base

convergent

control points

well distributed
(XYZ)

use 3-bars



use vertical and/or
horizontal
straight lines

terrestrial photogr. block adj.
simultaneous geod./photogr. adj.

evaluation

graphical

"normal case" - plotters
universal plotters
analytical plotters

numerical

plotters
comparators

photographic

rectification
orthophotography

characteristics of
terrestrial photogrammetry

+

flexible to requirements
on accuracy

fast recording

-

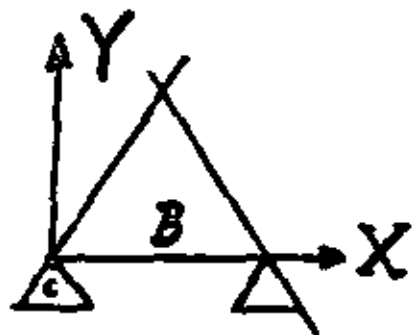
special requirements on
plotters

many models for complete
coverage

accuracy

$$Y = \frac{3c}{P}$$

$$dY = \frac{Y^2}{3c} dp$$



"thumb rules"

$$dp = 10 \mu\text{m}$$

gives $dY = 10 \text{ mm}$

for $c = 10 \text{ cm}$

$$B = 10 \text{ dm}$$

$$Y = 10 \text{ m}$$

planning

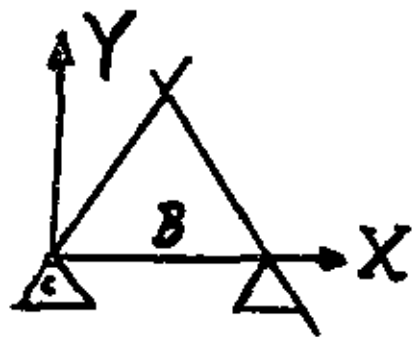
decisive factors

- available camera(s)
- — " — evaluation instr.
- analog/analytic evaluation
- graphical/numerical/photographic products
- size of object
- moving/non-moving object
- movable object
- single or repeated photogr.
- accuracy requirements
- economy

accuracy

$$Y = \frac{3c}{P}$$

$$dY = \frac{Y^2}{3c} dp$$



"thumb rules"

$$dp = 10 \mu m$$

gives $dY = 10 mm$

for $c = 10 cm$

$$B = 10 dm$$

$$Y = 10 m$$

planning

decisive factors

- available camera(s)
- — " — evaluation instr.
- analog/analytic evaluation
- graphical/numerical/photographic products
- size of object
- moving/non-moving object
- movable object
- single or repeated photogr.
- accuracy requirements
- economy

application of close-range photogrammetry

engineering

highways

railways

buildings

bridges

dams

geology

rock mechanics

soil studies

application of close-range photogrammetry.

industry

mining

cars

aircraft

ships

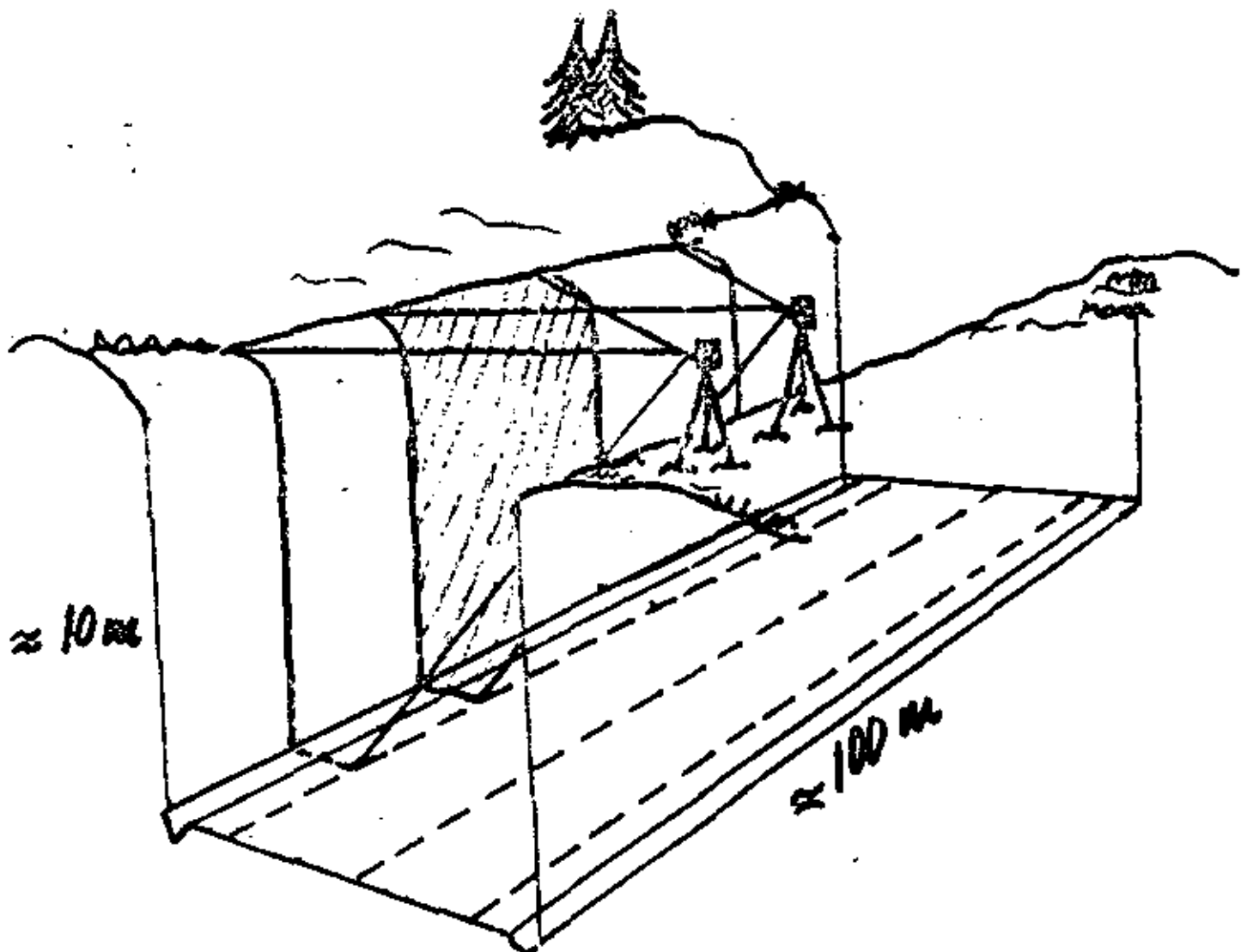
architecture

archeology

medicine

⋮

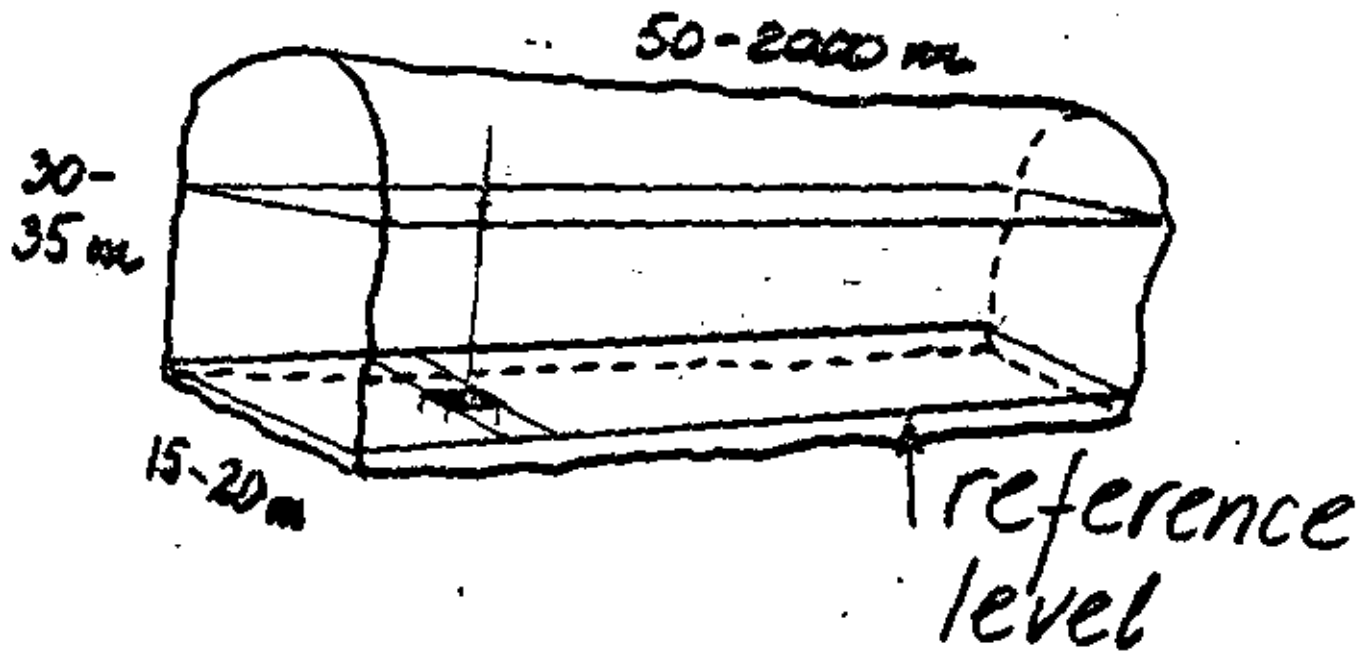
TERRESTRIAL PHOTOGRAMMETRY



DETERMINATION OF THE VOLUME OF
 A ROCK EXCAVATION USING
 DIFFERENT METHODS

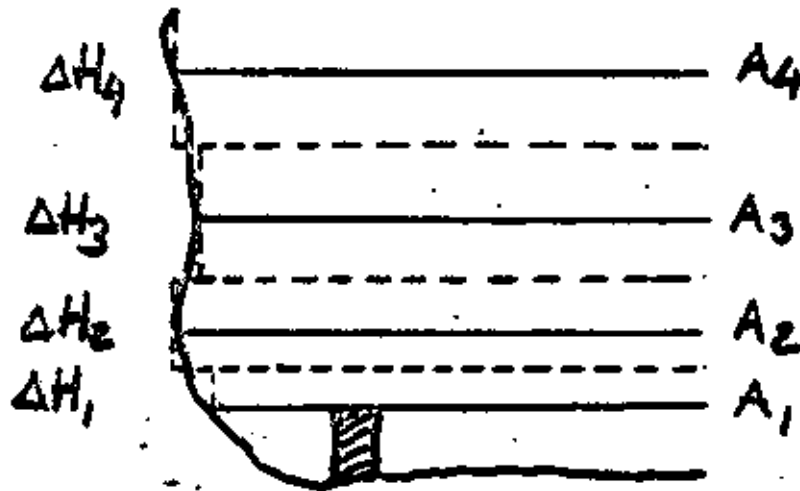
METHOD	VOLUME M ³	DIFFERENCE	
		M ³	%
TERRESTRIAL TACHEOMETRY	21418	-	-
TERRESTRIAL PHOTOGR CROSS SECTIONS	21877	+459	+2.1
TERRESTRIAL PHOTOGR DTM	21925	+507	+2.4

oil storage



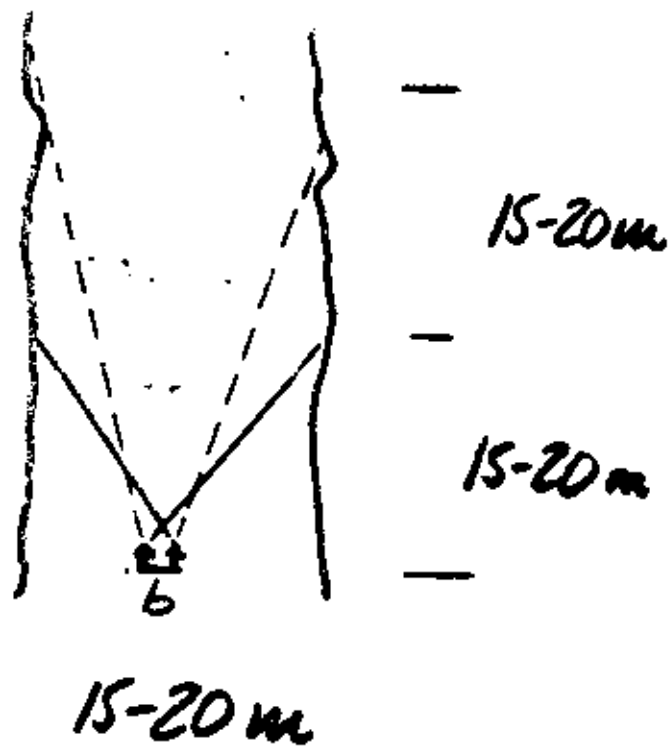
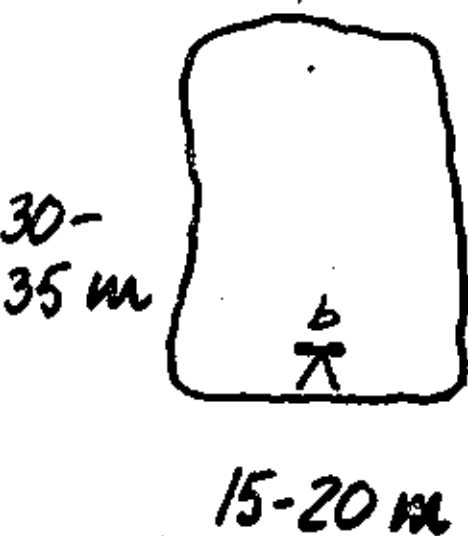
depth readings \Rightarrow
volumes from table

horizontal sections



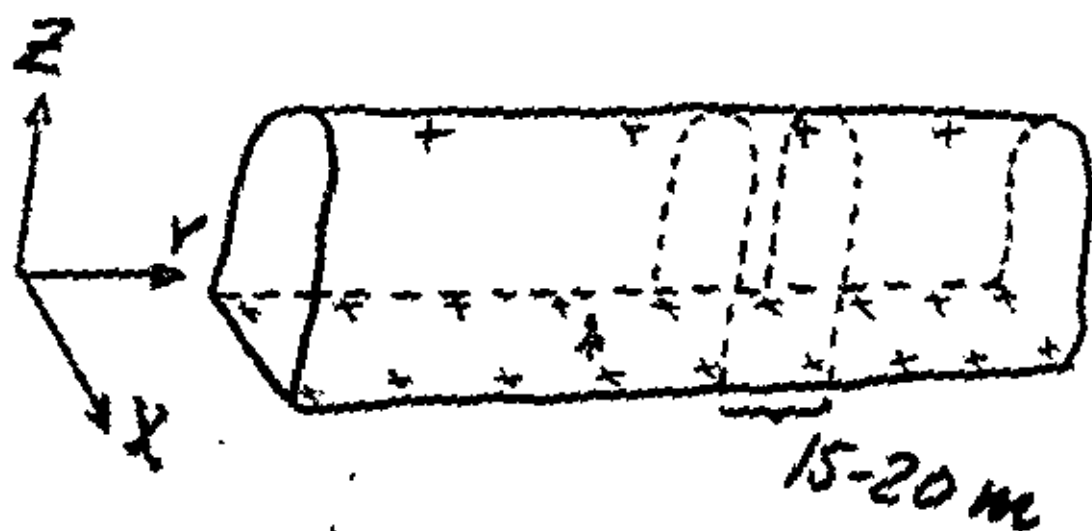
$$V = \sum A_i \times \Delta H_i$$

photography



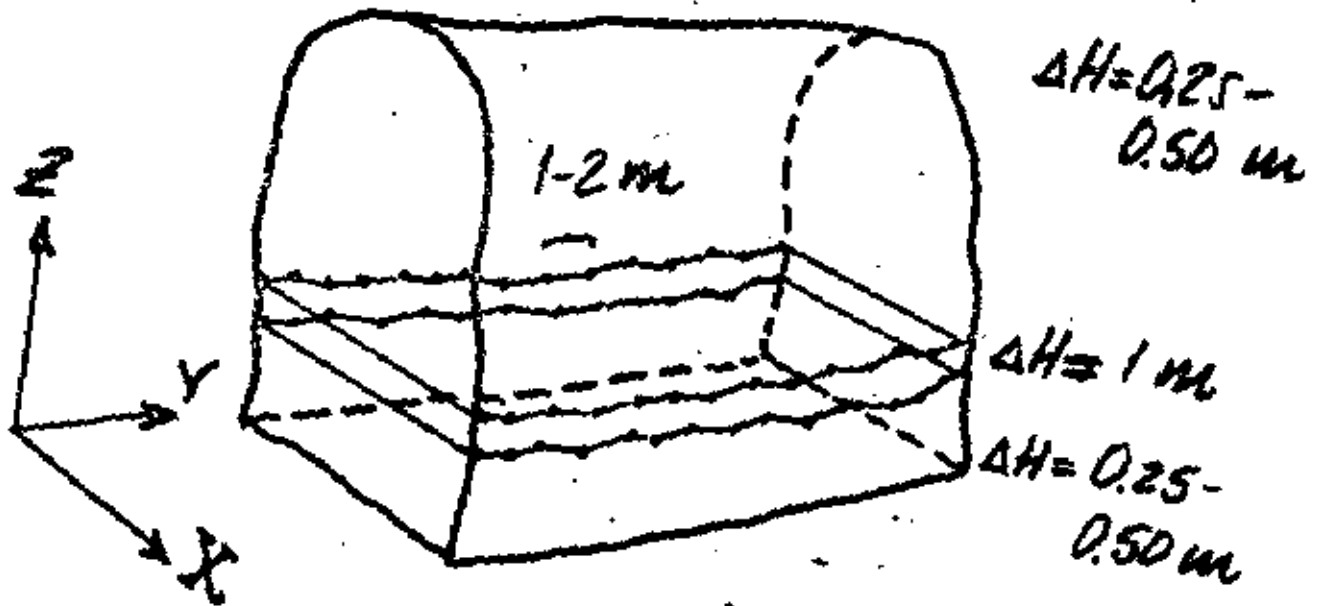
stereo-camera
 $b = 120 \text{ cm}$

control points



+ XYZ

evaluation



- x, y measured
 z given

accuracy

0.1-0.2% of volume

vertical sections ($\approx 500 \text{ m}^2$)

systematic errors ‰

light slit orientation 0.7

scale 1.1

end sections 0.5

camera/film 0.7

irregular errors

operator $0.3/\sqrt{n}$

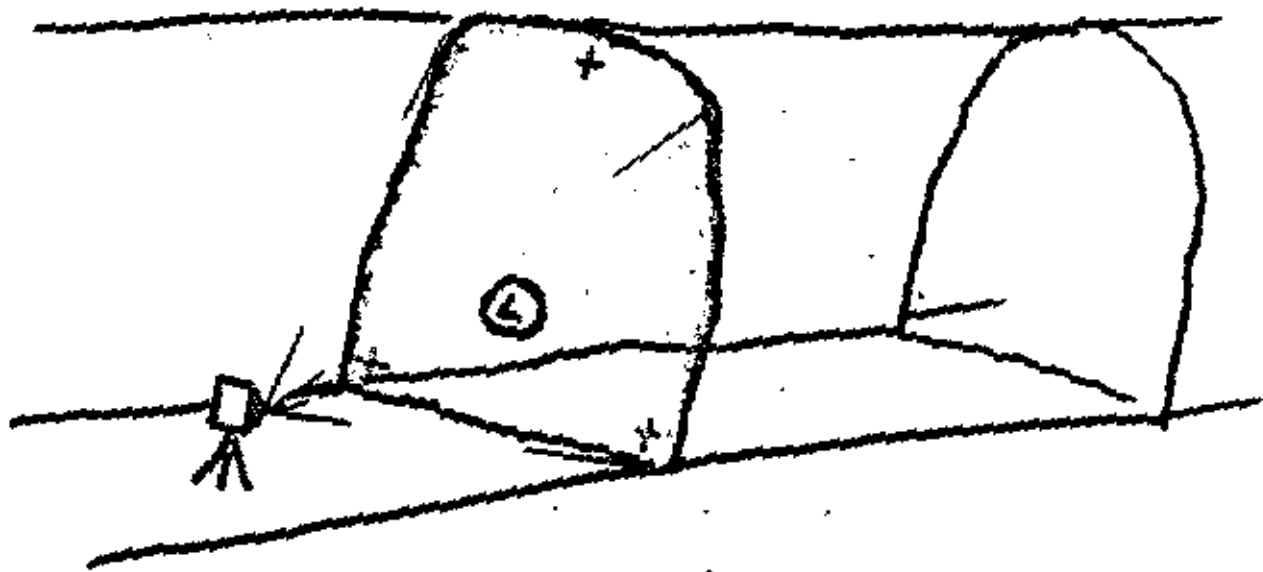
camera/film $1.8/\sqrt{n}$

interpolation
("shape") $(9.3 + 1.1D)/\sqrt{n}$

D = section interval

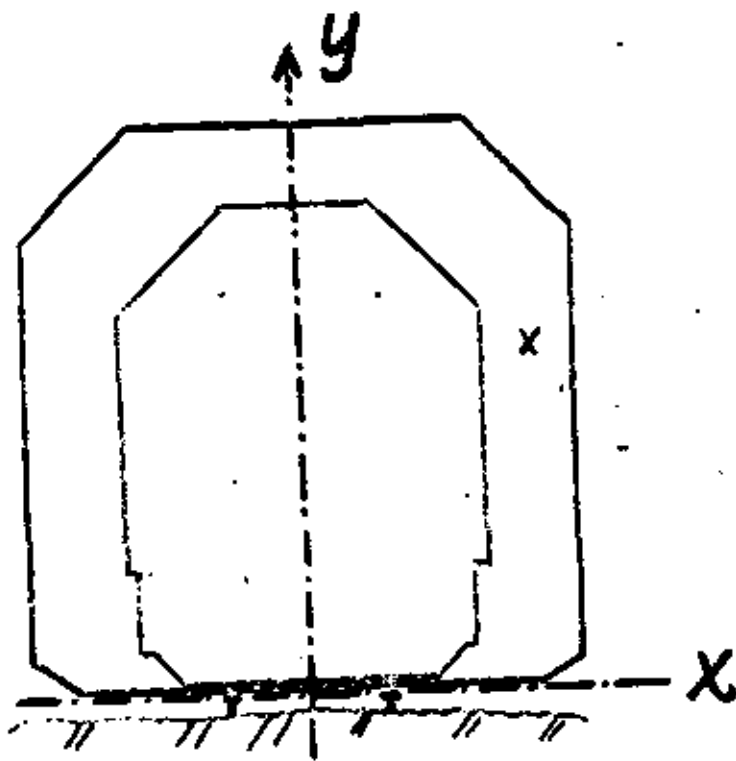
n = number of

vertical sections



L = light slit
generator
+ = control
points

free space along railways
for large cargoes

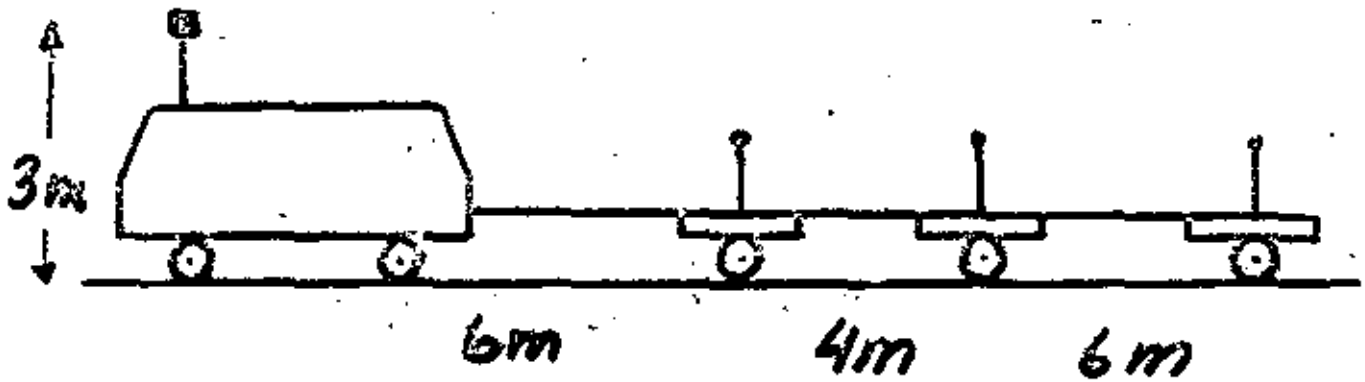


x "FOMUL"

normal load section 3400x4650 mm

investigation section 5200x5400 mm

FOMUL - photography

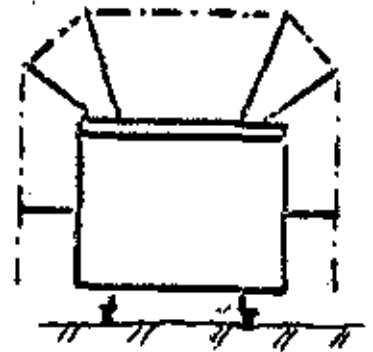


Hasselblad MK70



53x53 mm $c=60\text{mm}$

base = 1.80 m



7 reference points

foldable pointers

FOMUL - evaluation

computation

- image coordinate refinement
- model coordinates in camera system.
- FOMUL coordinates

FOMUL

accuracy: 10-40 mm

capacity: one vehicle (2 men)
= eleven vehicles
(44 men!) with
previous method

production: 80 000 objects
5000 obj./year

FOMUL - evaluation

measurement in Wild Stk
and Zeiss, Jena Stecometer

image coordinates and
parallaxes

≥ 4 reseau points

7 reference points

FOMULS

deformation measurements

- change in geometry
- period of time
- size of object
- application

mechanical engineering
civil —||—

deformation photogrammetry

flat objects

rectification

stereoscopic vision

3D-objects

stereo photography

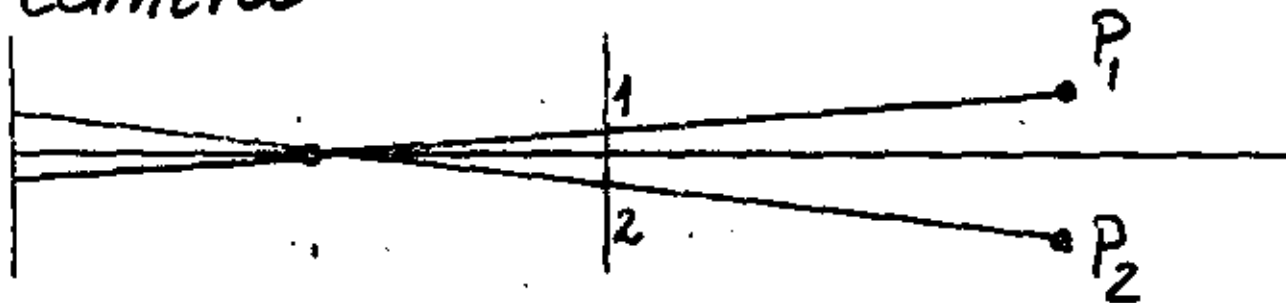
stereoscopic meas.

in comparator

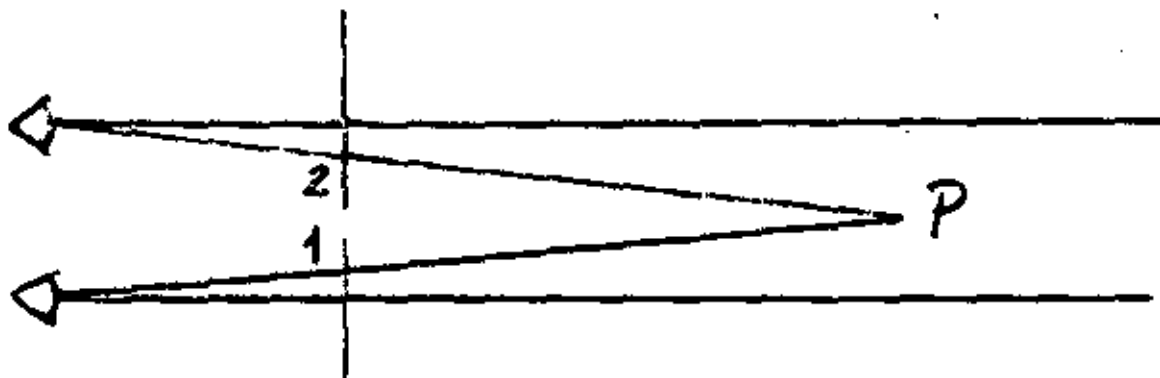
method	duration	object size m	relative accuracy
aerial phot.	month	10^2-10^5	$10^{-5}-10^{-4}$
geodesy	month	10^2-10^7	$10^{-6}-10^{-5}$
workshop measuring	minute	$10^{-3}-10^1$	$10^{-5}-10^{-3}$
close-range photogr.	week	$10^{-1}-10^2$	$10^{-5}-10^{-2}$
hologrammetry			

false parallaxes

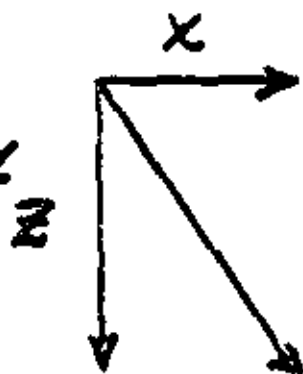
camera



observation

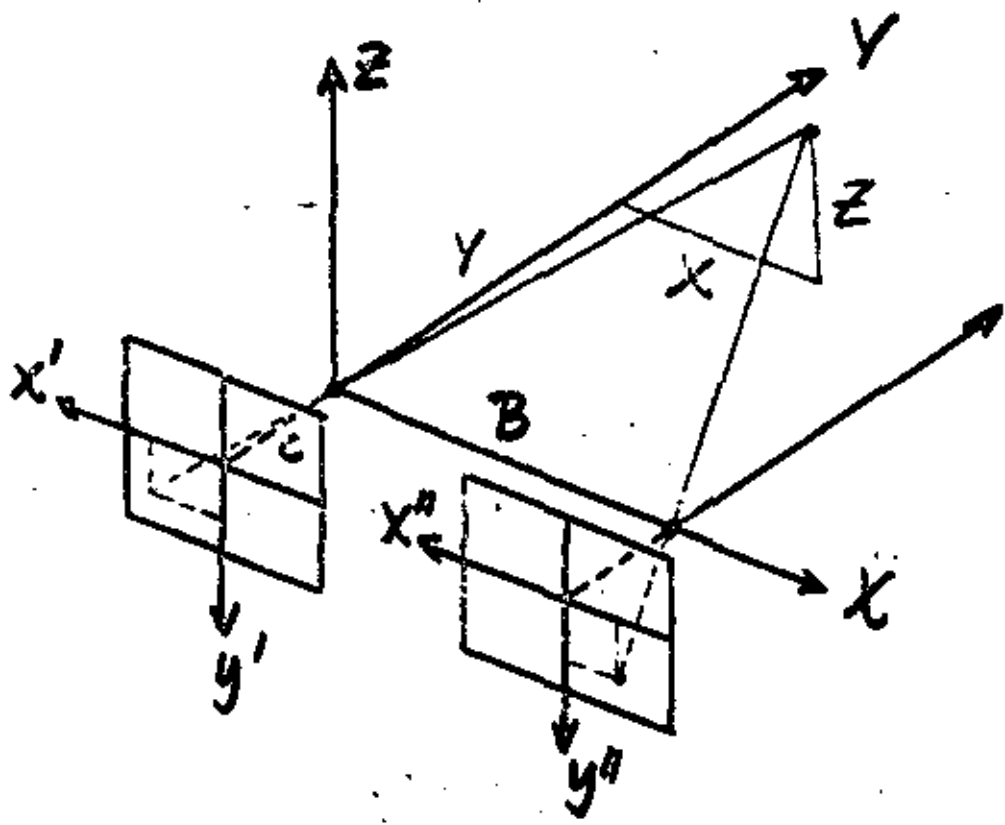


z-parallax



x-parallax

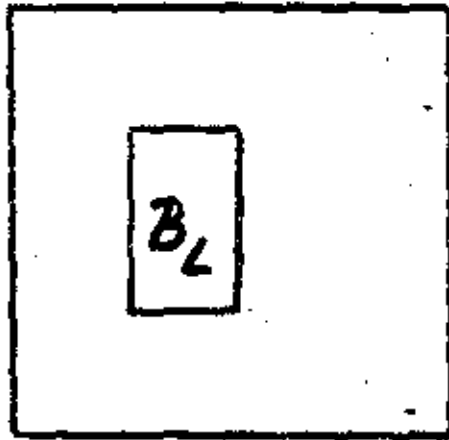
the time parallax method



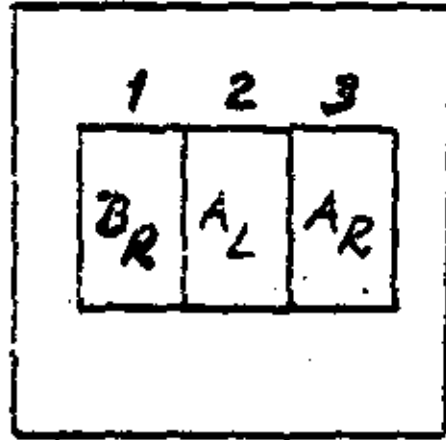
$$\begin{aligned} X &= \frac{B}{\rho'} X' \\ Y &= \frac{B}{\rho'} C \\ Z &= \frac{B}{\rho'} Y' \end{aligned} \quad \rho' = X' - X''$$

the time parallax method

stereocomparator



B = before
A = after



L = left
R = right

model

1 (real)

$$(XYZ)_B \quad x'_B \quad y'_B$$

2 (fictitious)

$$x'_B, y'_B, x'_B - x'_A, y'_B - y'_A \Rightarrow x'_A, y'_A$$

3 (- " -)

$$x'_B, y'_B, x'_B - x''_A, y'_B - y''_A \Rightarrow x''_A, y''_A$$

$$(XYZ)_A$$

orthophotography in architectural photogrammetry

photography

- narrow-angle camera
- low $\Delta s/s$ ratio
- protruding parts
off border

orthoprojection

- Y-scanning
- small scan width
- interpolation between profiles
- slow, stoppable scanning

products

- orthophoto
- line map on overlay from orthophoto
- combination of orthophoto and line map

application

- + • objects, curved or extended in depth
 - especially when painted or decorated
 - mosaics, frescos, cupolas etc.
- objects composed of staggered planes and protruding elements which cover other details
(temples, cathedrals etc)

production time

stereoplotting : orthophoto
5-10 : 1

stereoplotting : line map from
orthophoto
3 : 1

accuracy (true scale)

control points	1-10 mm
image/model	1 mm
orthoprojection	10 mm
copying	1 mm
assembling	7 mm
<hr/>	
in total	15 mm

analytical plotter
in close-range photogr.

+ orientation of
photographs

orthogonal projections
in different planes

improved stereo-vision

non-metric photographs

close-range photogrammetry

state-of-the-art

metric cameras

> 30 types

c-values: 56 — 190 mm

format: 55x55 — 130x180 mm

cone angle: 33 — 88 gon

exp. time: $\geq 1/500$ sec

aperture: 3.5 — 64

{ glass plates
cut sheet film
roll film

reseau (Hasselblad MK70)

non-metric cameras

- + flexible focusing
- easy to handle
- cheap
- lenses have high distortion
- instability of interior orient.
- lack of fiducial marks
- no means for orientation

non-metric cameras	
complete calibration	
partial	— " —
self	— " —
on-the-job	— " —
no	— " —

state-of-the art

evaluation instruments

- plotters for "normal case"
- universal first order plotters
- mapping plotters
- analytical instruments

state-of-the-art

results

graphical
digital

prel design

- photography
- block triangulation
- evaluation of photos
- map specifications

prel design

aerial photography

photo scales 1:8000-1:15000

b/w

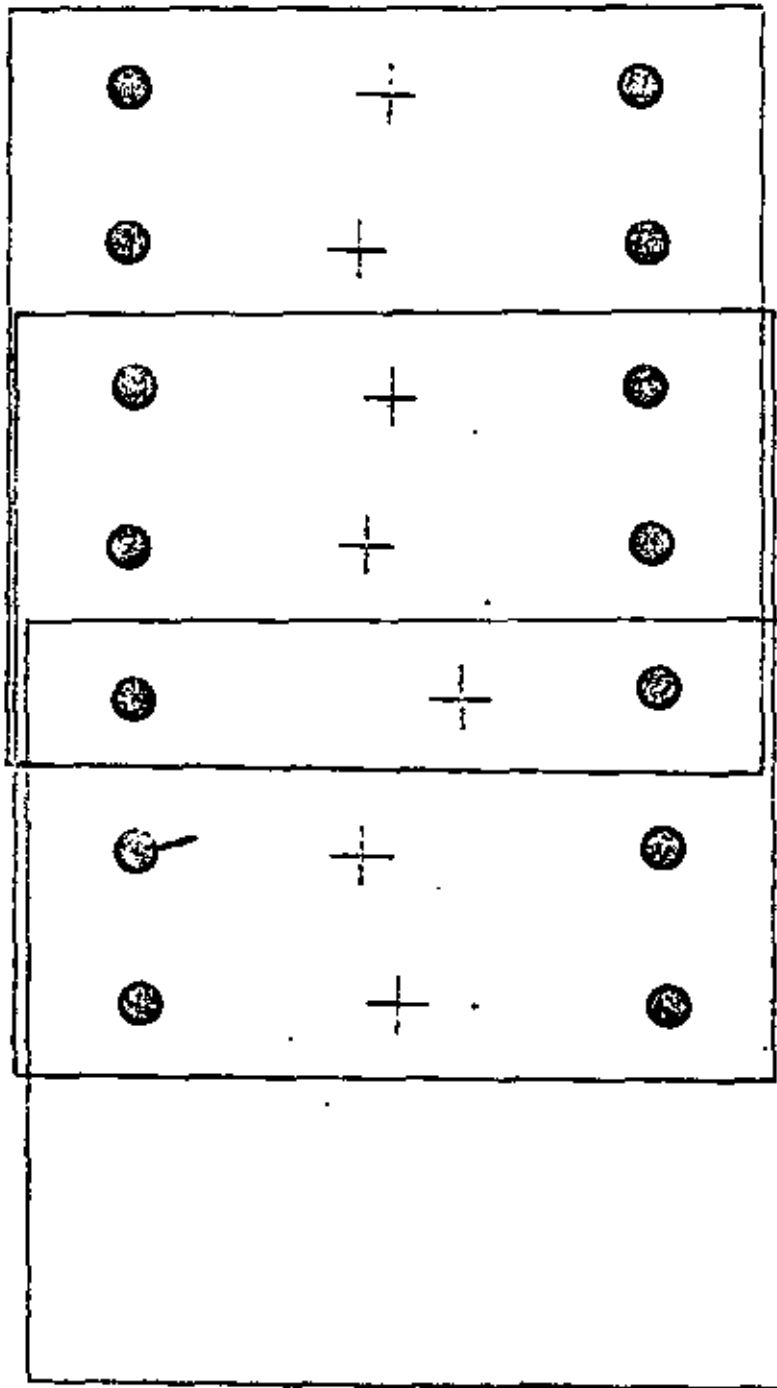
colour

ground control

planimetric

elevation

geodetic control



⊗ = Planimetric and elevation (XYZ)

+ = Elevation (Z)

aerial triangulation

strips - blocks
size

analogue - analytic
mono -
stereo -

bundle - independent model

systematic errors

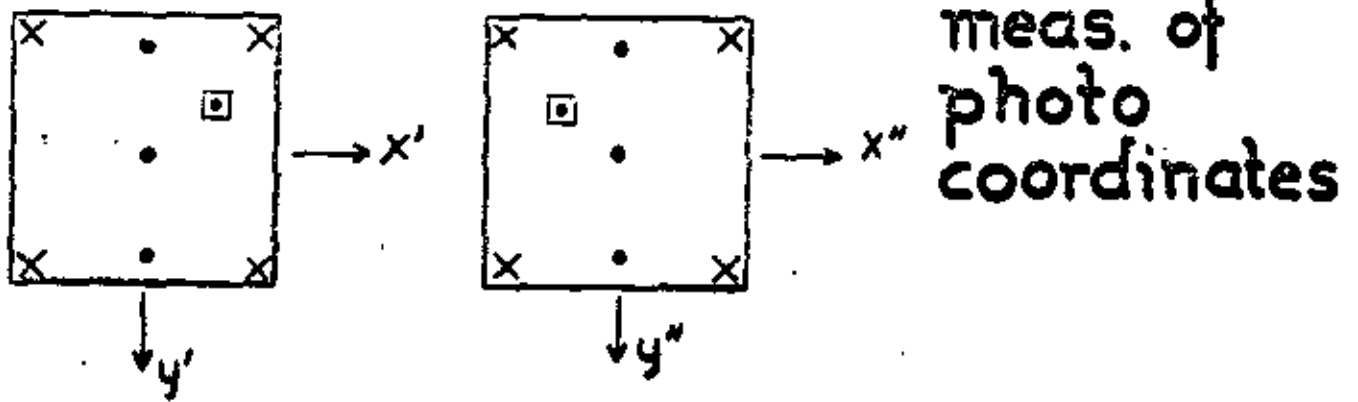
tie-points

aerial triangulation

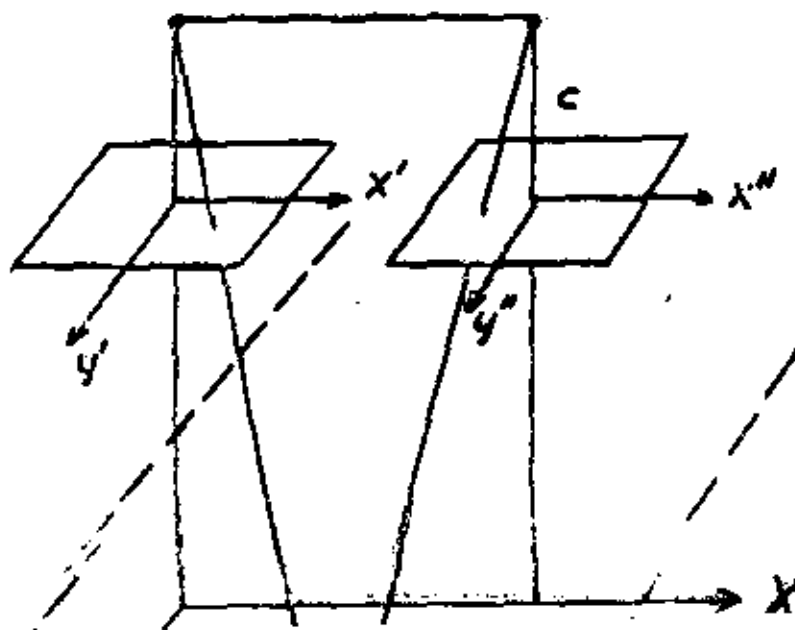
decisive factors

- accuracy requirements
- state of superior triangulation net
- topography and vegetation
- field surveying technique
- personnel and instrument costs

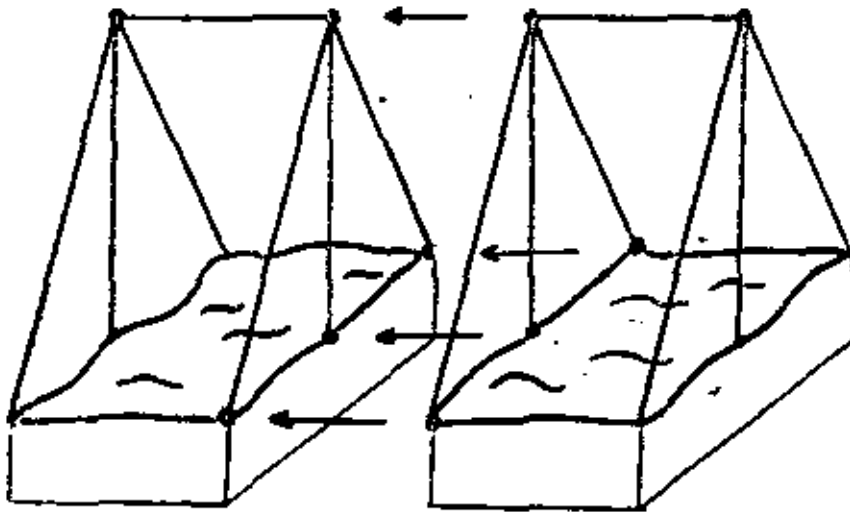
three dimensional analytic model triangulation



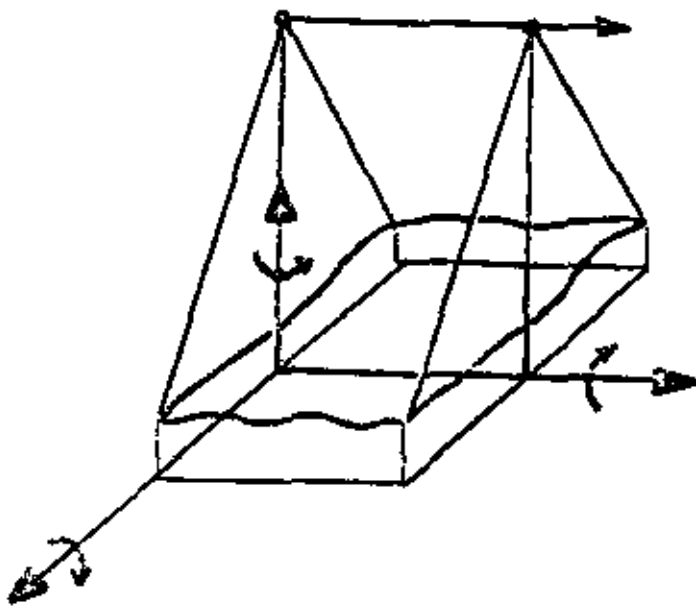
- x = fiducial marks
- = tie points
- ◻ = control points



numerical
relative
orientation

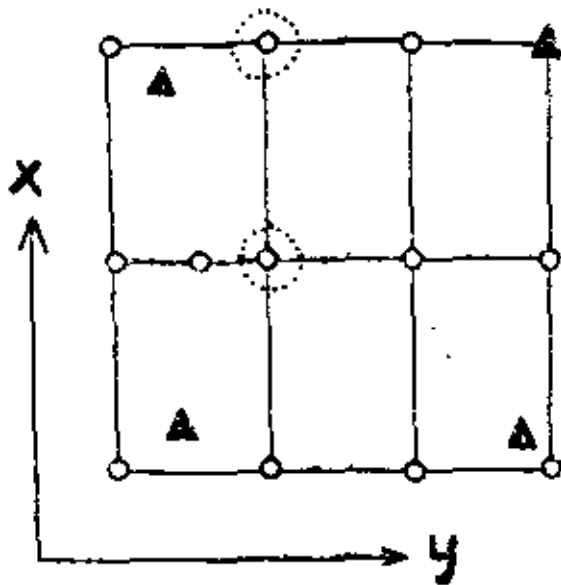
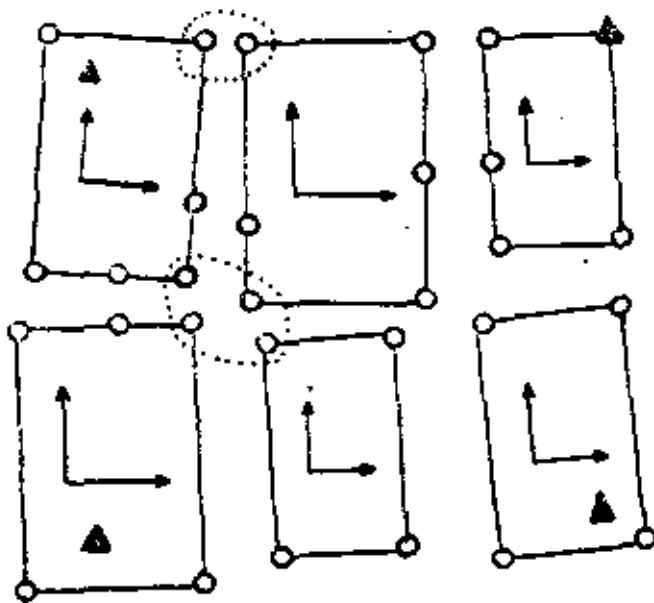


connection
of models



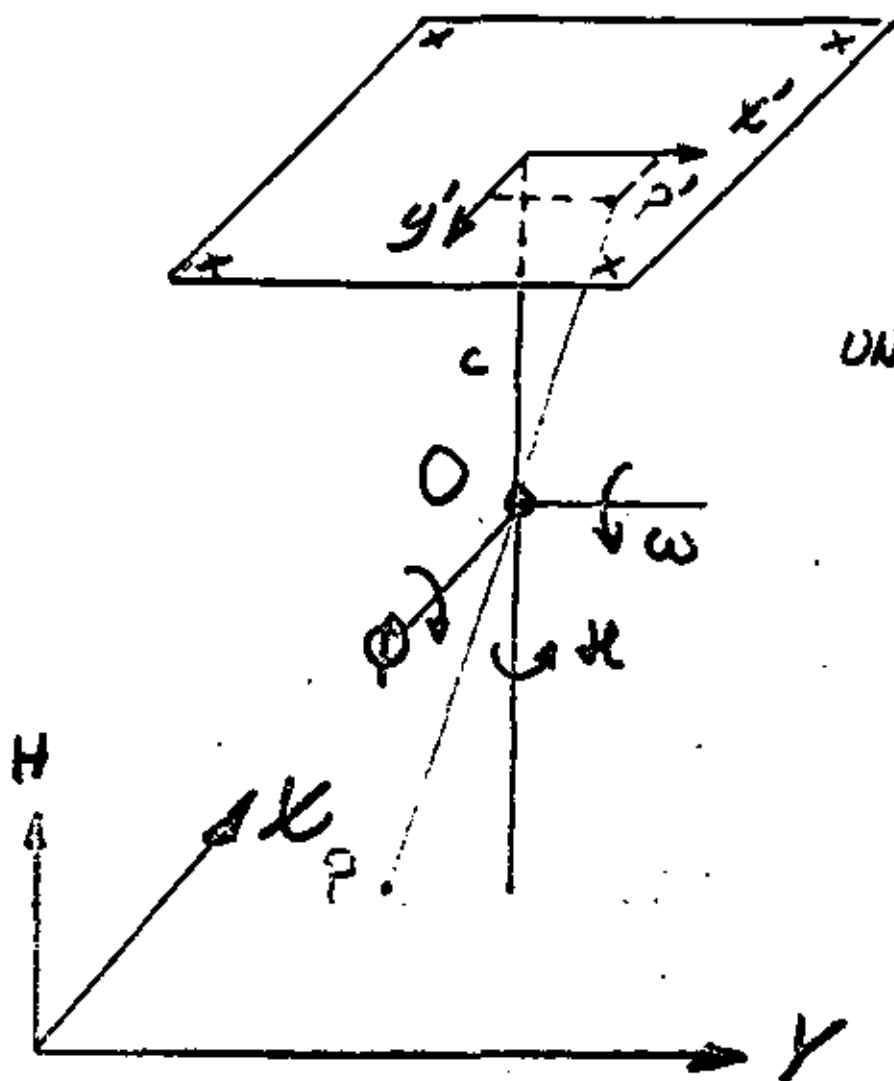
final
adjustment

photogrammetric
block adjustment



AERIAL TRIANGULATION

BUNDLE ADJUSTMENT



UNKNOWN

$X_0 Y_0 P_0$

$\kappa \phi \omega$

$X_p Y_p H_p$

method of adjustment

number of unknowns

independent models

model $\begin{cases} dX_0 & dY_0 & dZ_0 \\ d\eta & d\xi & d\alpha \\ S \end{cases}$

bundle adj.

photos $\begin{cases} X_0 & Y_0 & Z_0 \\ \kappa & \phi & \omega \end{cases}$

tie points X Y Z

elevation control X Y

planimetric control Z

block adjustments

accuracy studies

1. theoretical

algebraic

numerical

matrix inversion

simulation

2. empirical

test field

controlled experiments
(repeated measurements)

analytic independent
model triangulation

empirical results of
sub-operations

- 1) transformation on
fiducial marks $10 \mu\text{m}$
($30 \mu\text{m}$)
- 2) relative orientation $7(15) \mu\text{m}$
- 3) model connection $13(30) \mu\text{m}$

systematic error correction

I. directly

system calibration
on test field

II indirectly

compensation of effects
= self calibration by
additional parameters

- proper choice
- correlation
- significance
- automatic operational

block adjustment, results

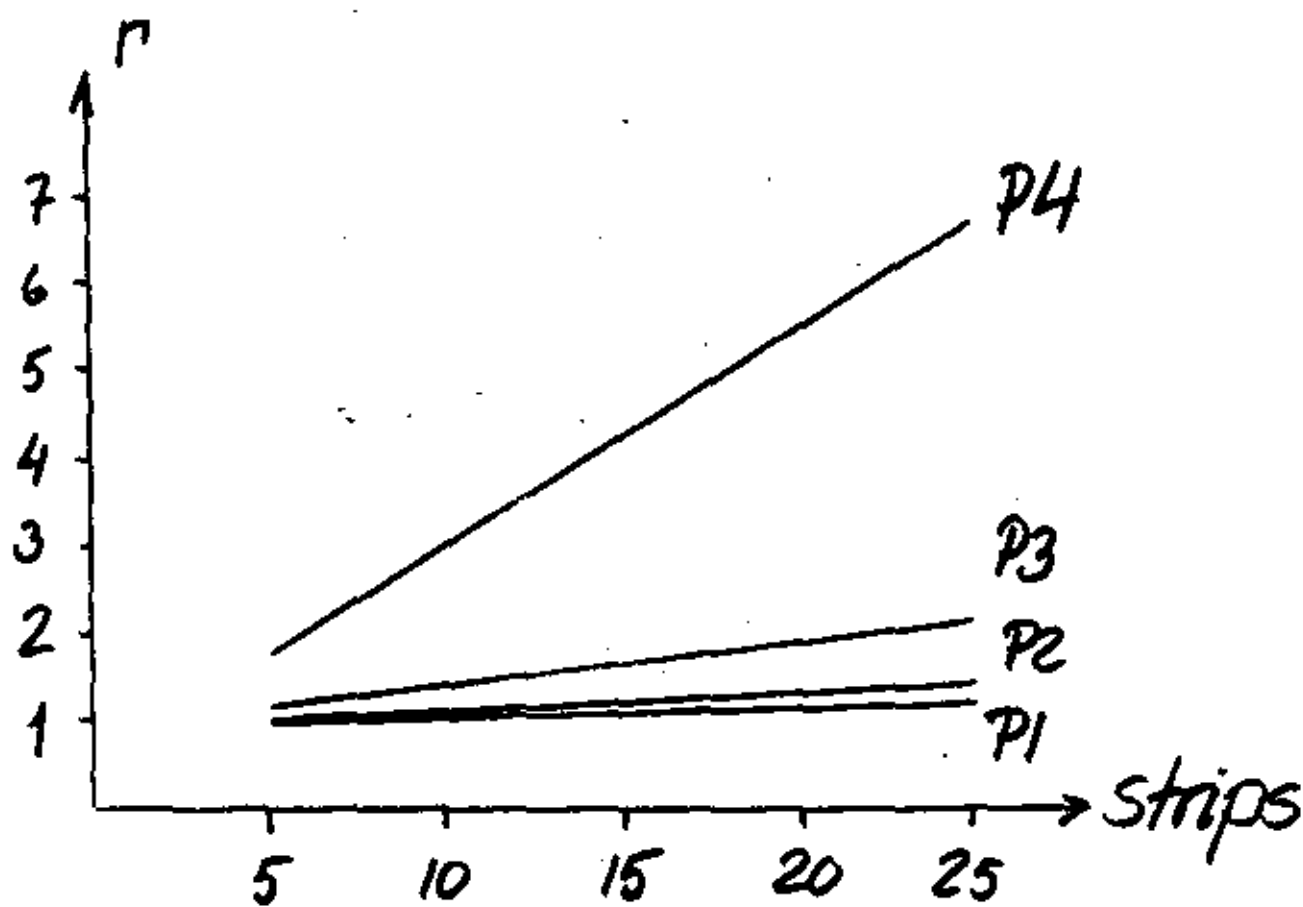
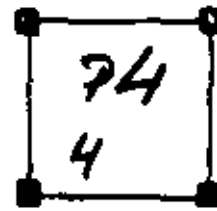
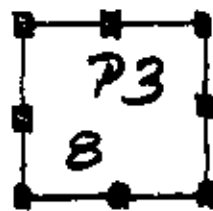
2) Oberschwaben independent models

control		rmse, μm			
x, y	z	x, y	z	x, y	z
$i=2$	$i=4$	10	15	6	14
4	8	13	19	7	17
8	12	20	22	7	19
11	25	22	65	8	27

without with
self calibration

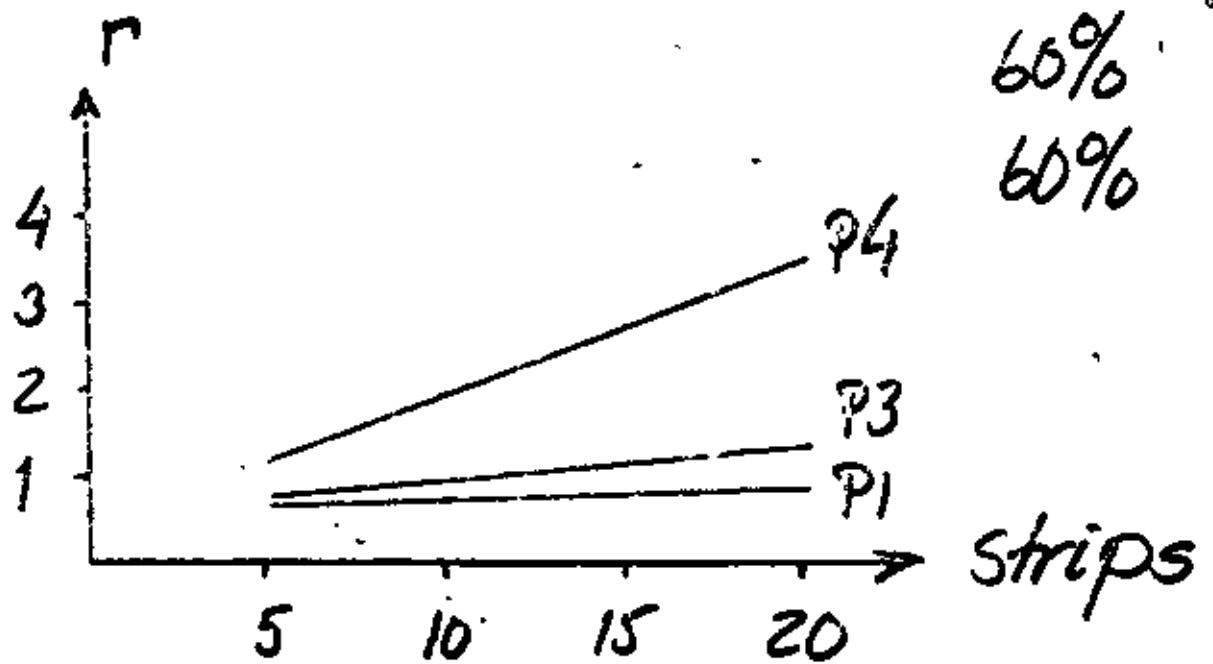
planimetric accuracy

60%
20%



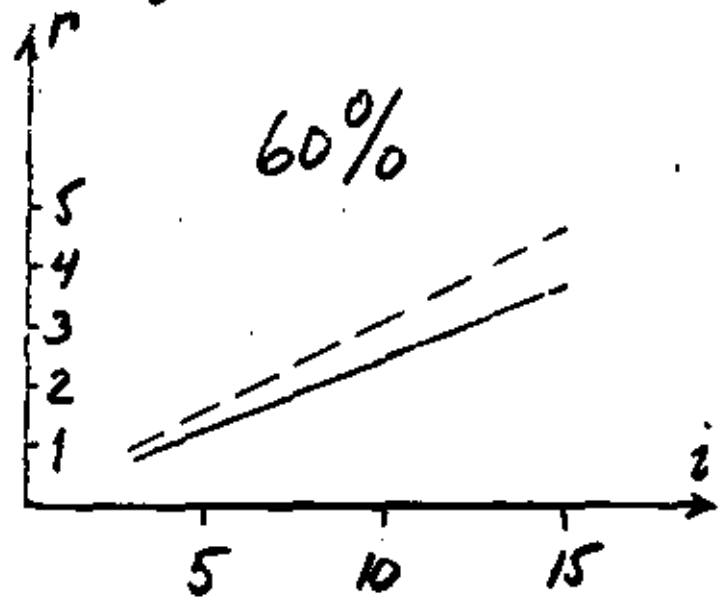
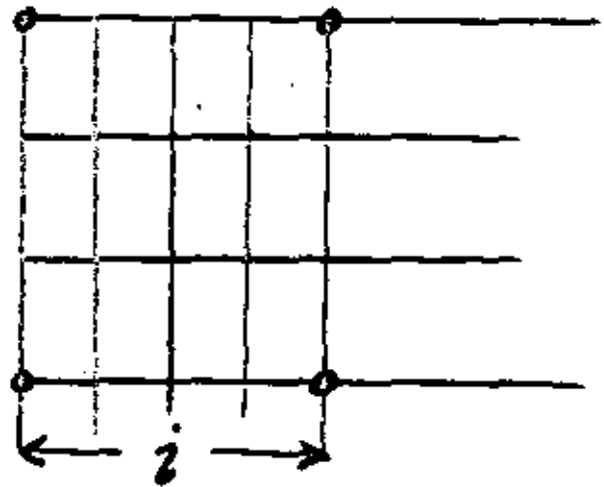
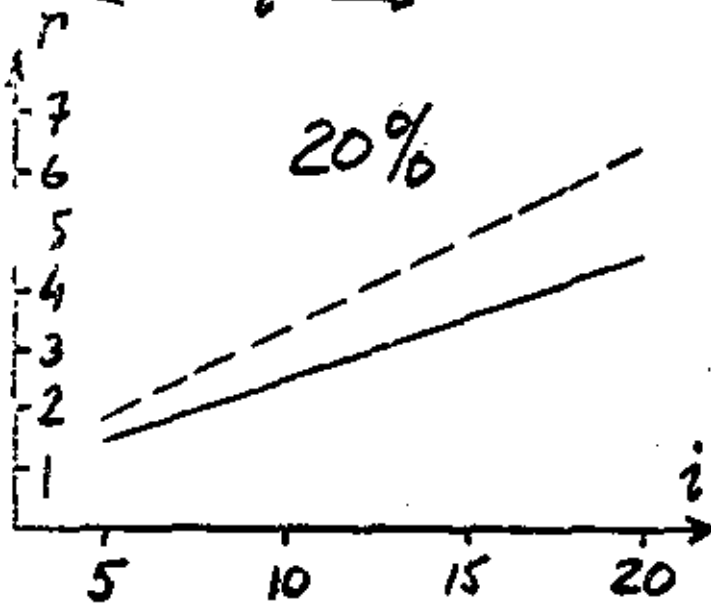
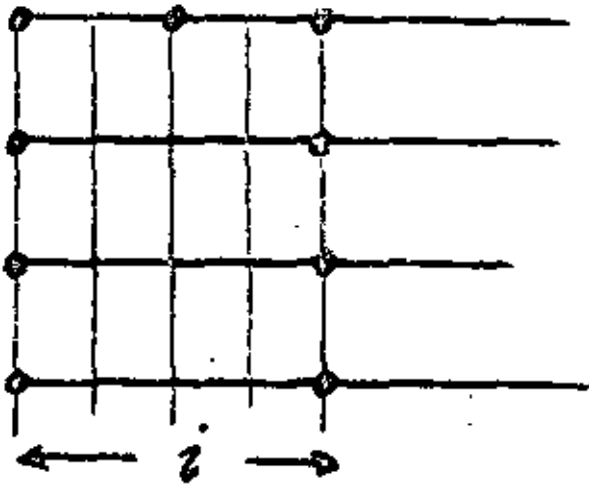
$$r = \frac{\text{"block adj."}}{\text{"single model"}}$$

planimetric accuracy



$$\frac{r_{20\%}}{r_{60\%}} = 1.4 - 1.6$$

height accuracy



block adjustment, result

1) Oberschwaben bundle
1:28000 $q=20\%$ 104 photos

Control		rmse, μm			
x, y	z	x, y	z	x, y	z
$i=2$	$i=4$	9	16	5	12
4	8	14	22	6	15
8	12	24	28	7	16
11	25	25	44	8	19

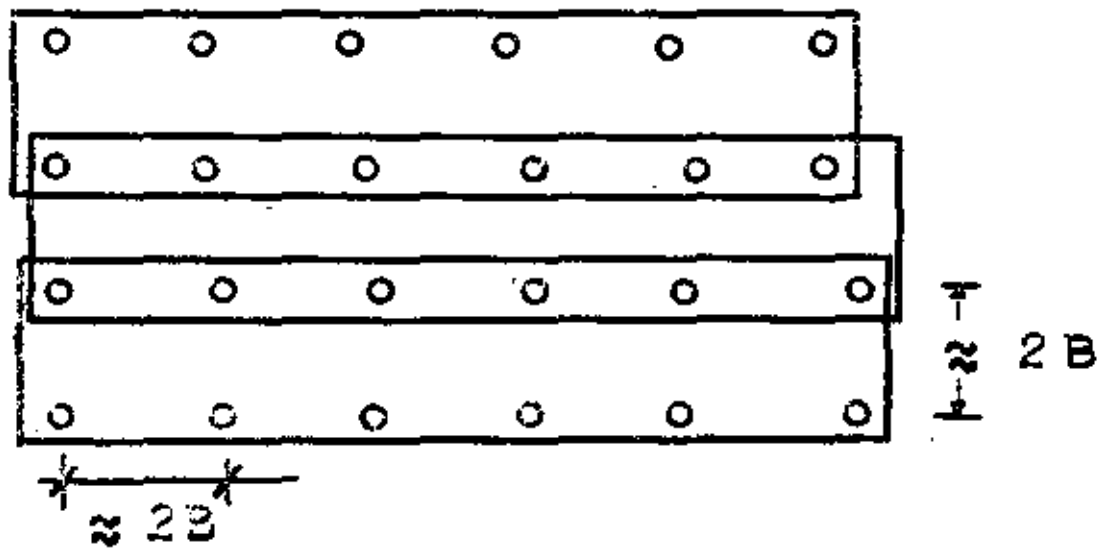
without self-calibration | with self-calibration

bundle adjustment

$X, Y \approx 0.65 \cdot$ "independent
model"

$h \approx 0.75 \cdot$ "independent
model"

geodetic control in blocks



- planimetric control
- elevation control in every model

prel design

evaluation of photos

maps 1:1000 - 1:5000

contours 1-5 m

cross-sections, profiles

DTM

3D-design

analog

computer-aided

instruments

analog

optical projection

mechanical projection

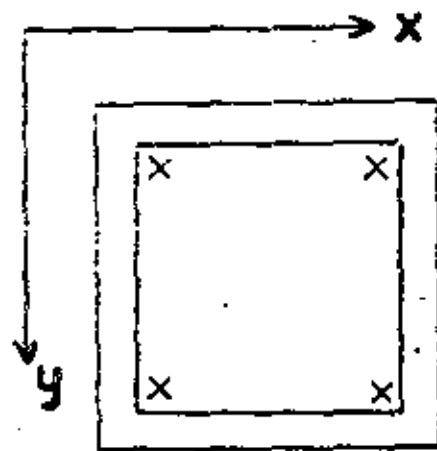
analytic

comparators

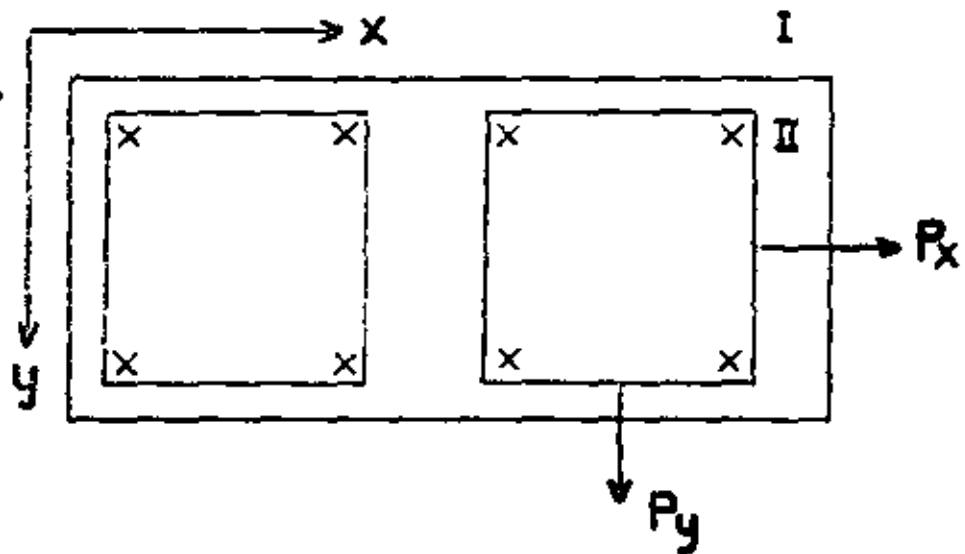
analytic plotters

comparators

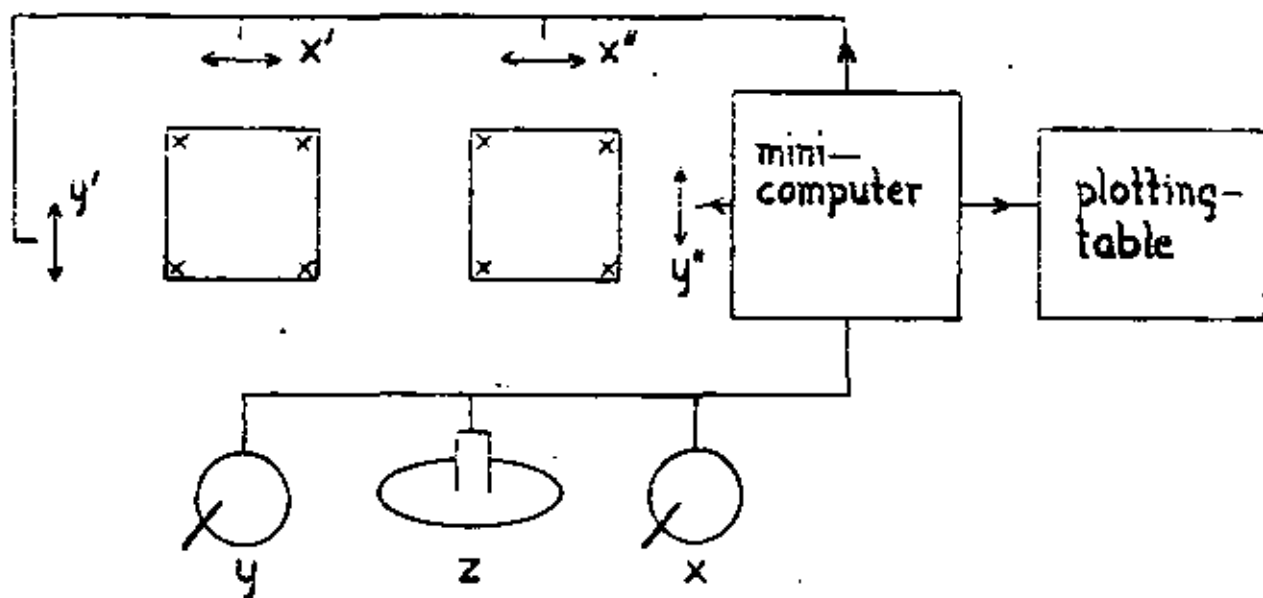
mono-



stereo-



analytic plotter



prel design

aerial photography

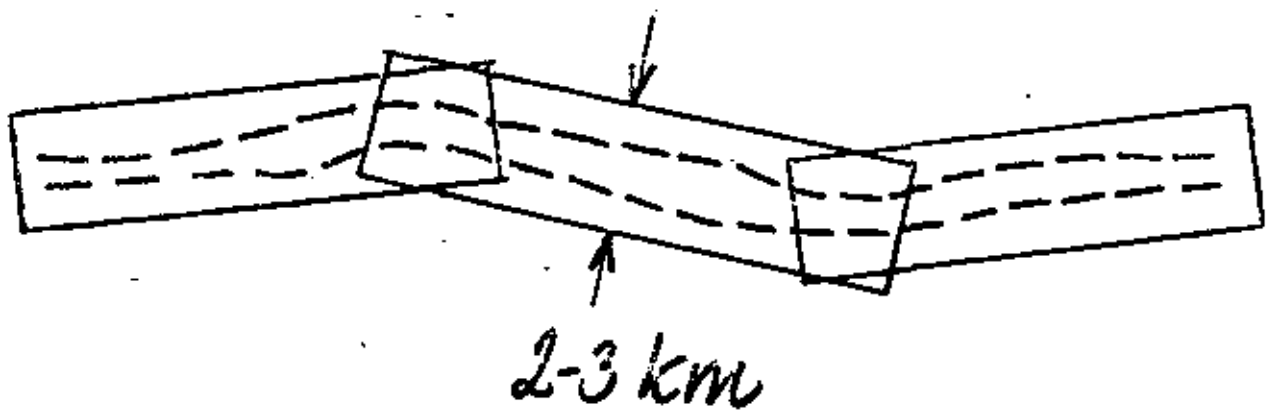


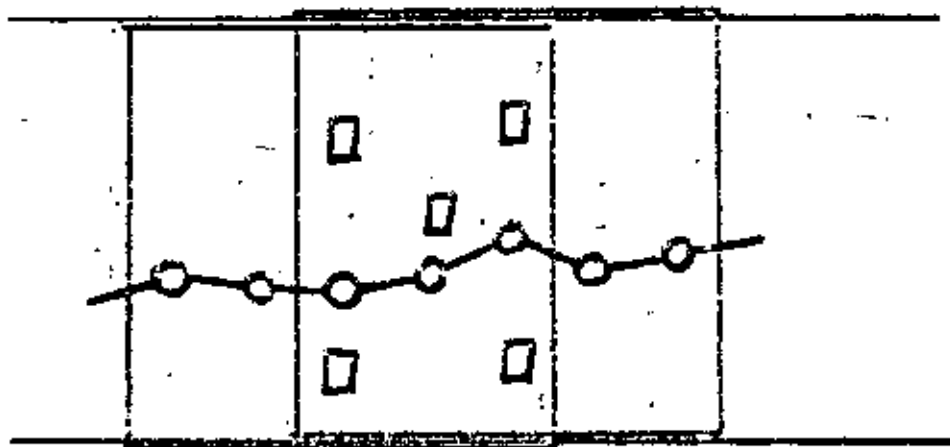
photo scale 1:10000 - 1:13000

altitude 1500 - 2000 m

panchromatic
or
coloured film

prel design

ground control



○ planimetric control

□ elevation control

aerial triangulation

basic situation



- single strip.
- photo scale 1:10000
- appr. 10 models.
- narrow area of interest
- basic traverse necessary
- levelling will always be made within the area of interest

Test area Örebro

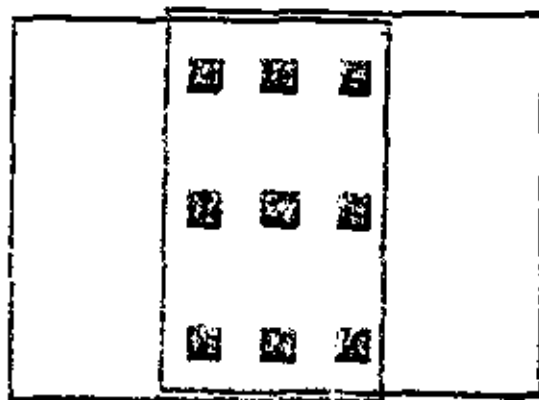
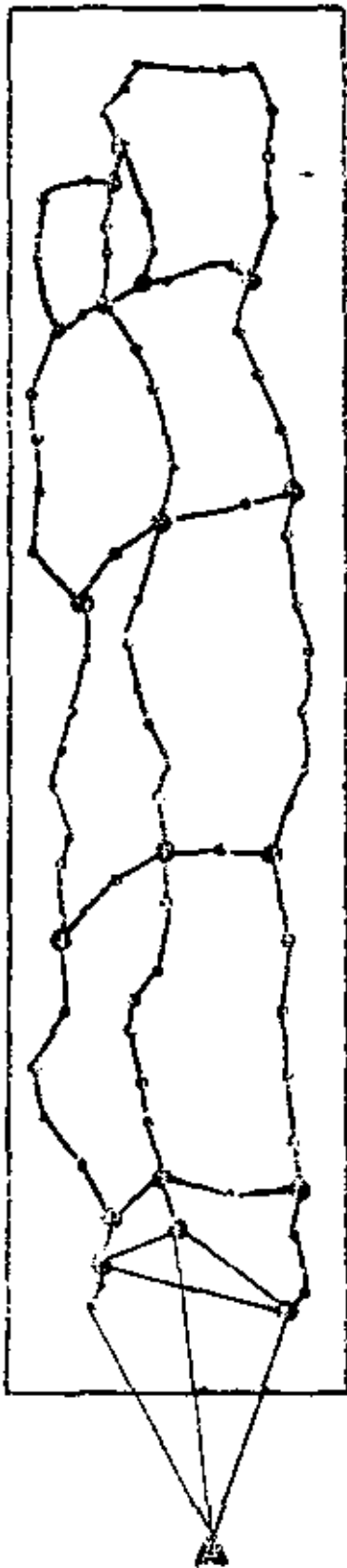
flying height: 2000 m

photo scale: 1:13000

strip length: 10 mod

number of
sign. points: 87

number of
natural points: 63

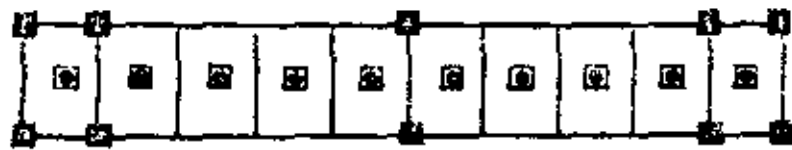


Results

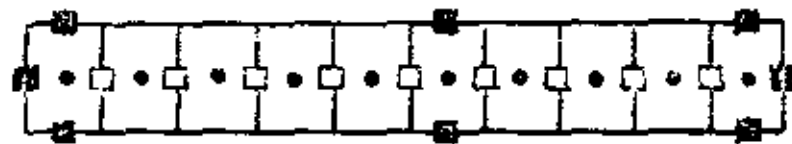
\hat{f}_x \hat{f}_y \hat{f}_n \hat{f}_{nn}
 cm



11 14 16 19



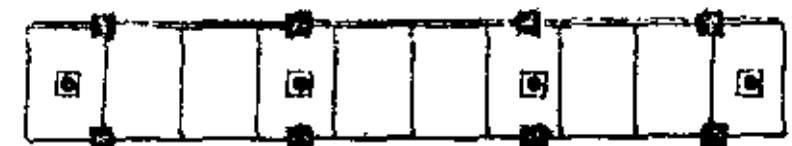
11 14 14 18



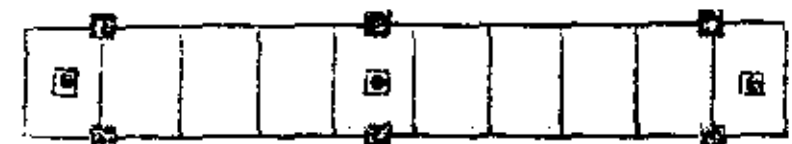
11 14 20 23



11 14 14 17



10 17 13 18



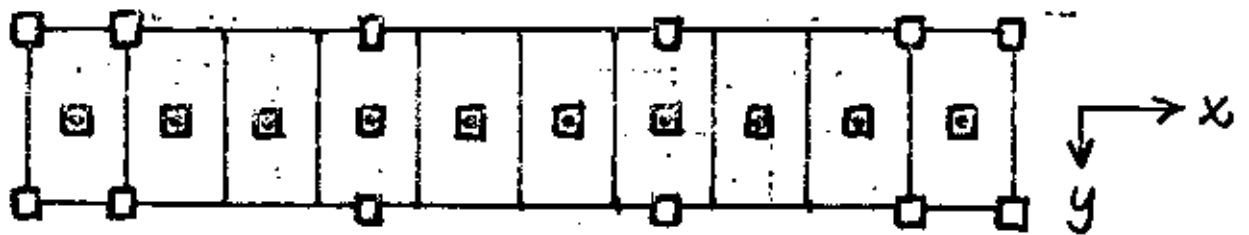
18 33 15 20

○ = Signalized elevation control

● = Signalized elevation control

■ = Natural elevation control

test area "Örebro"

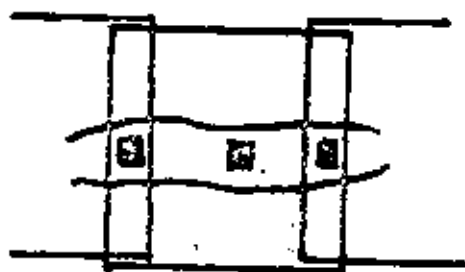
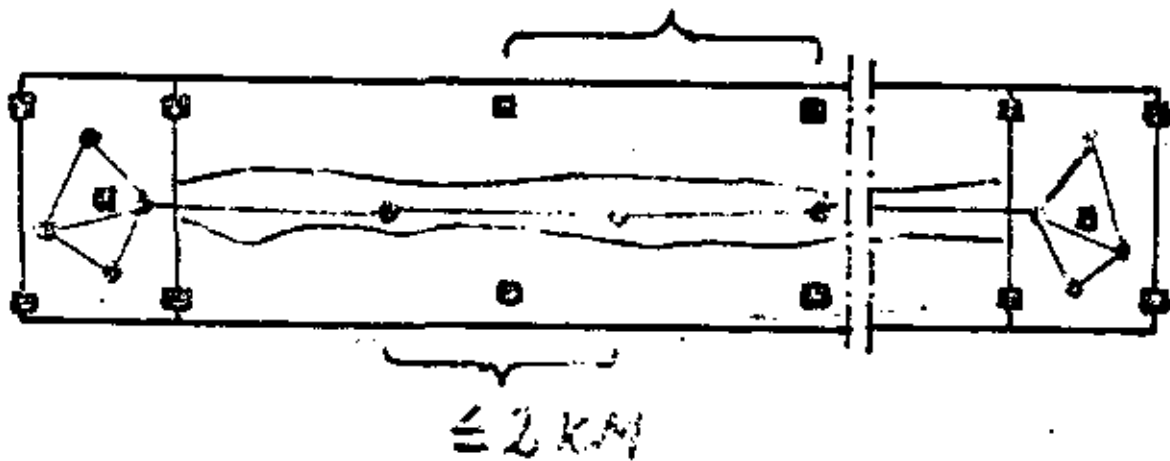


	x sign.	y sign.	z sign.	z nat.
No. of test points	47	47	47	41
aerial triang. rmsq errors, cm	11	14	16	19
separate models rmsq res., cm	8	9	10	14

AERIAL TRIANGULATION

recommended distribution of geodetic control

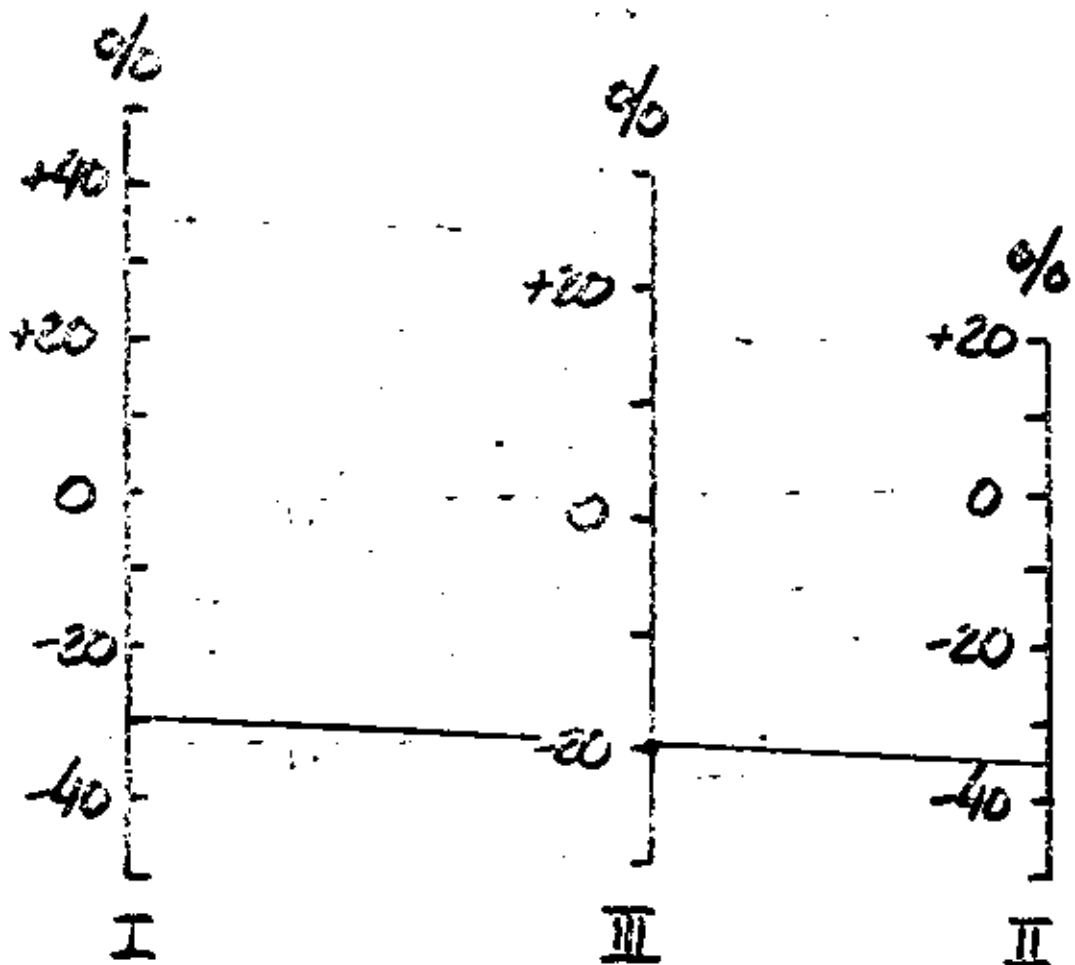
$\leq 3 \text{ km}$



ϕ
dH

aerial triangulation

economic aspects

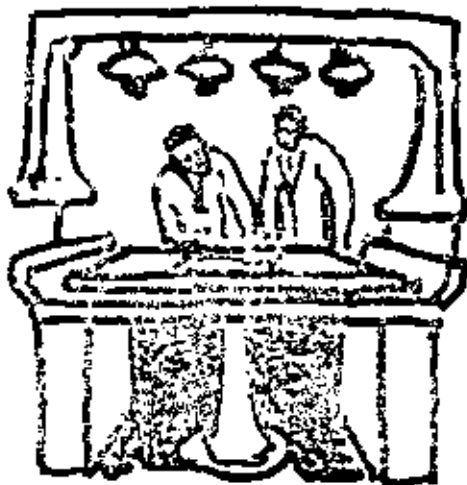
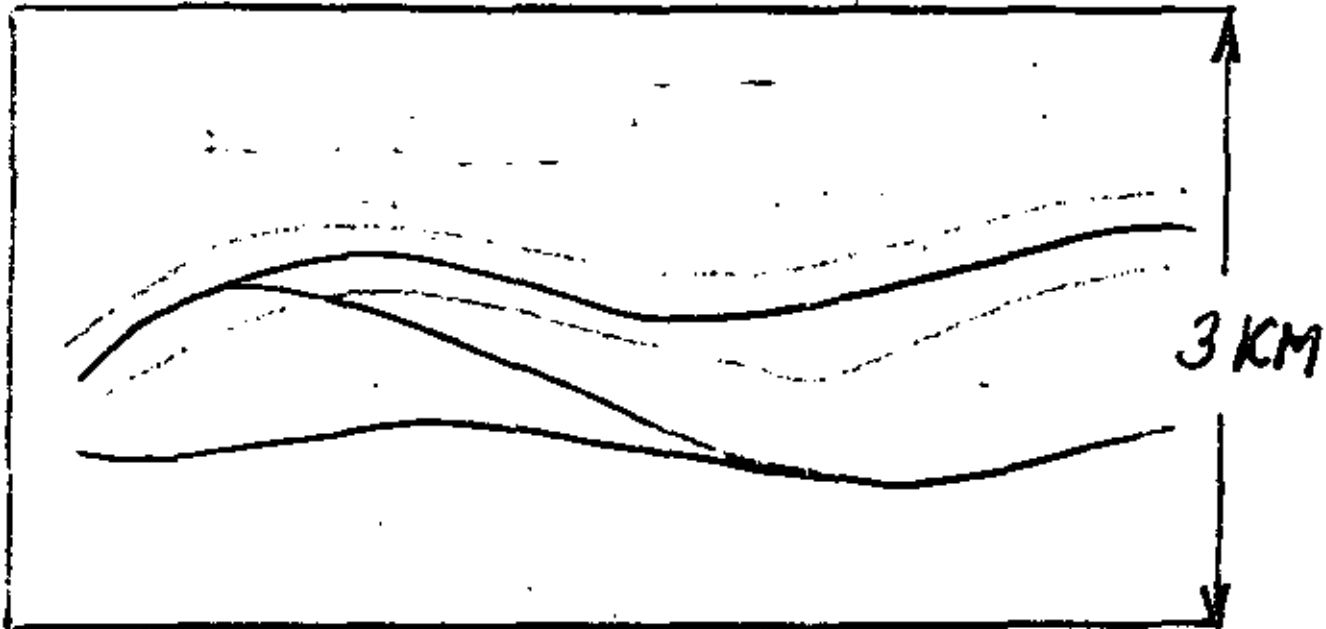


estimated changes in costs
when using aerial triangulation

- I reconnaissance and bench marks
- II measurement of traverse
- III total costs

PRELIMINARY DESIGN

DETERMINATION OF FEASIBLE ROUTES

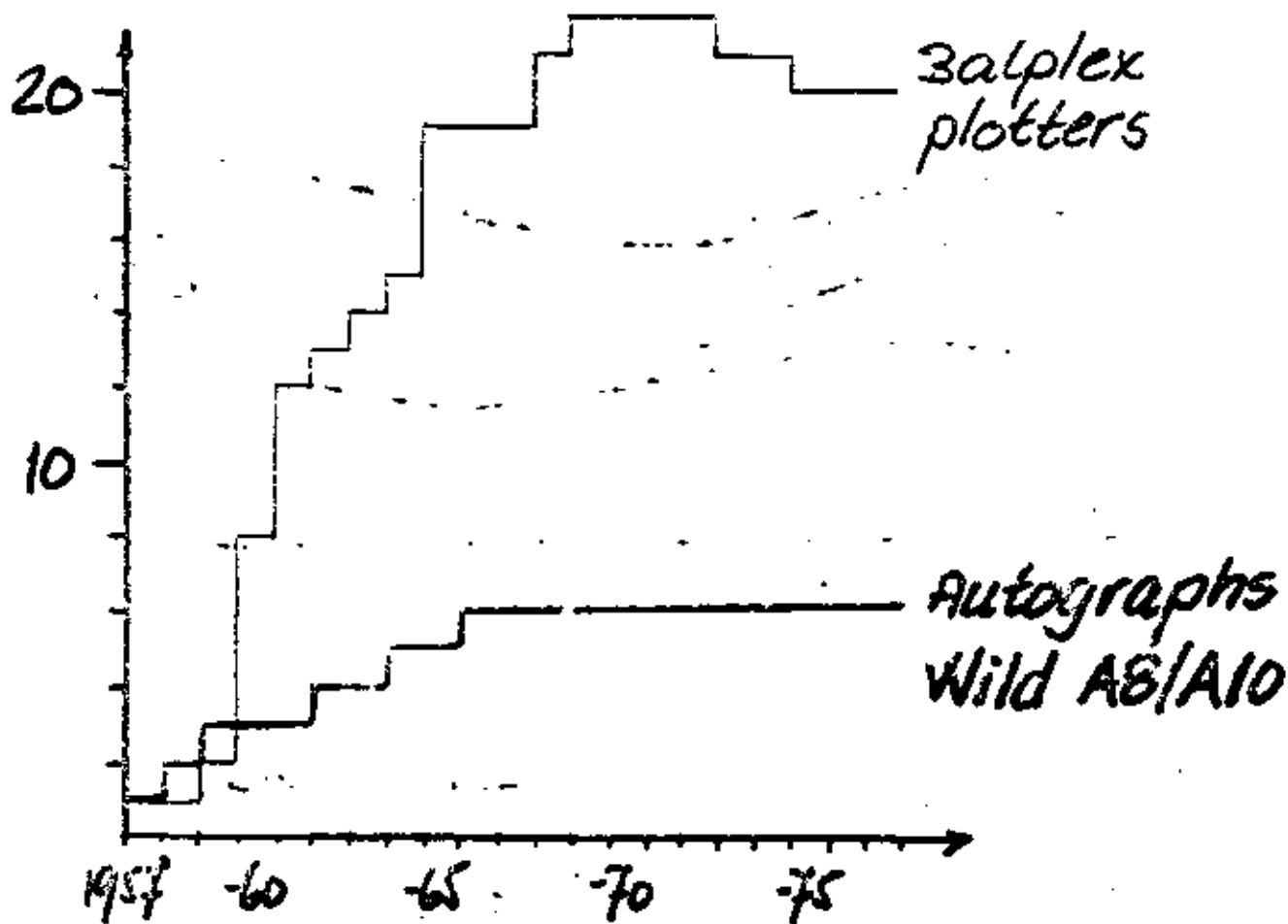


BALPLEX PLOTTER

1:4000

map production

instruments



map production

instruments

coordinate
recording
device

1 Wild A10

EK 8

2 Wild A8

LOGIK 5000

1 Wild A8

SAAB UE-211-1

1 Wild A8

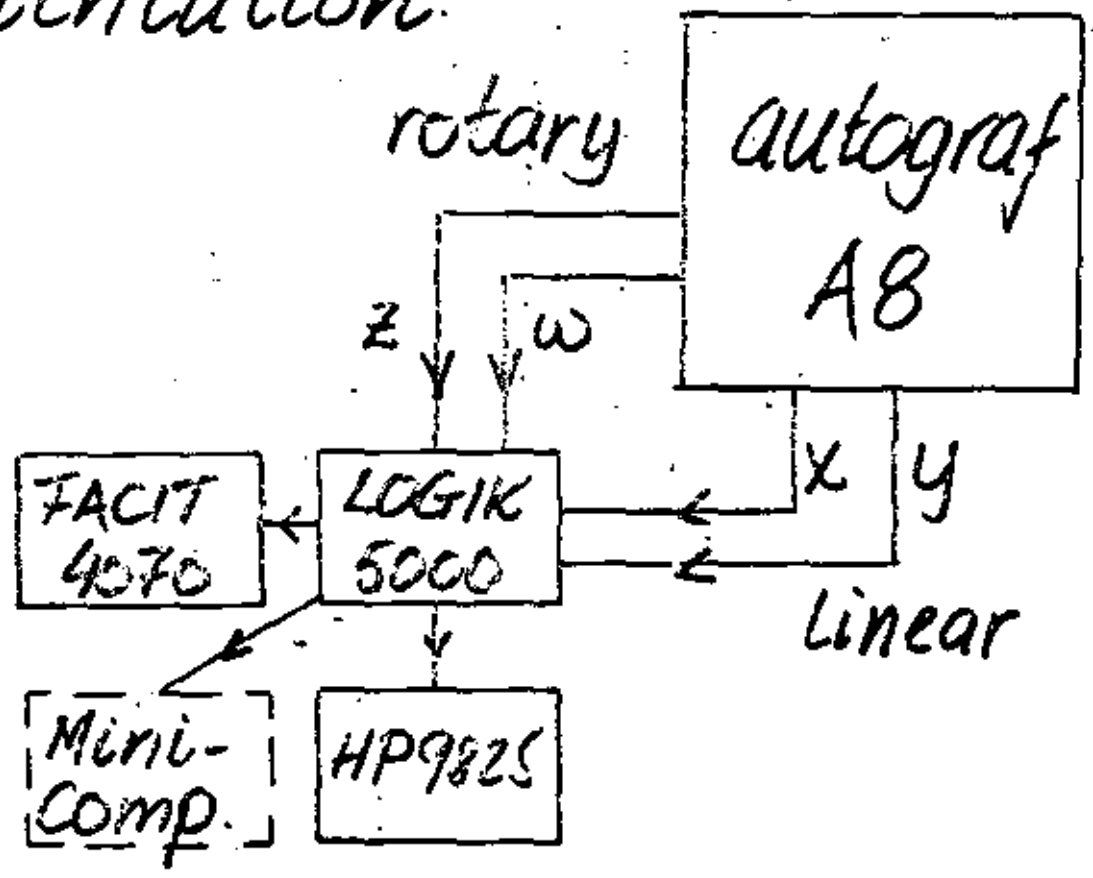
EK 20

1 Wild A8

20 Balplex Plotters

map production

numerical
orientation.



map production

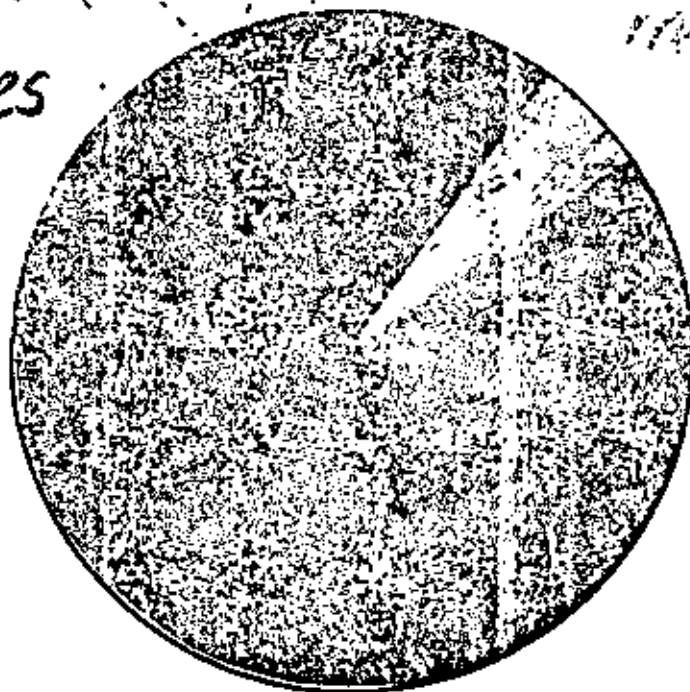
map scale %

1:2000 90

1:1000 10

cost distribution

salaries
80%

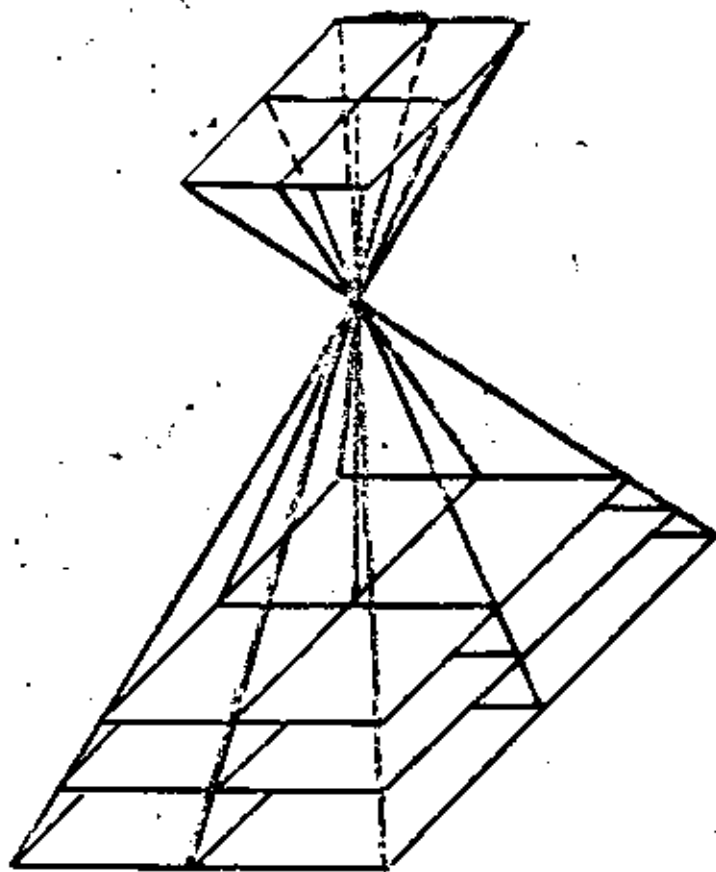


materials
5%

instrument
15%

map production

instrument
tests



standard errors

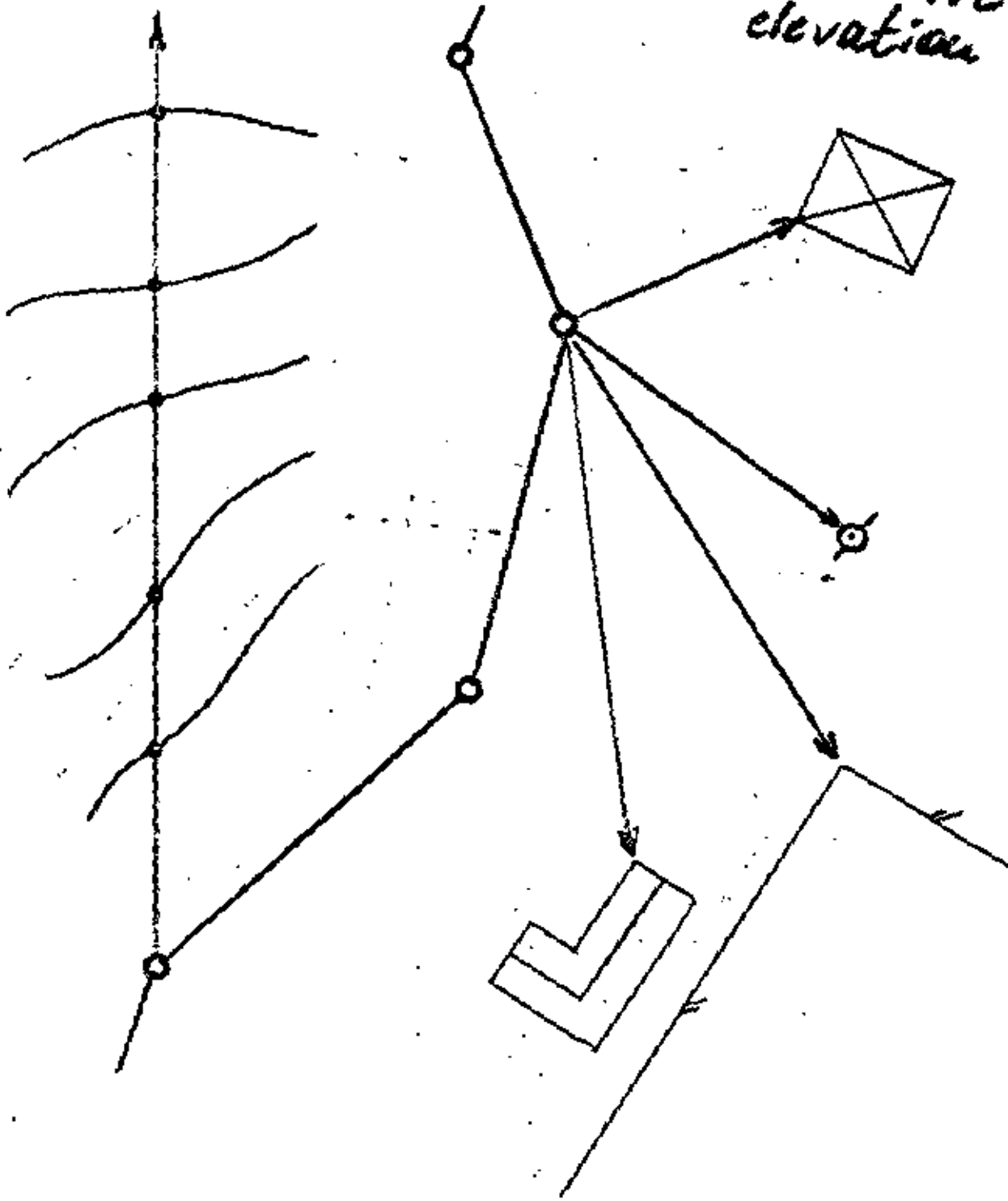
A8 : 3.5 - 7.0 μm (1967-1977)

A10 : 2.5 - 3.7 μm (1972-1977)

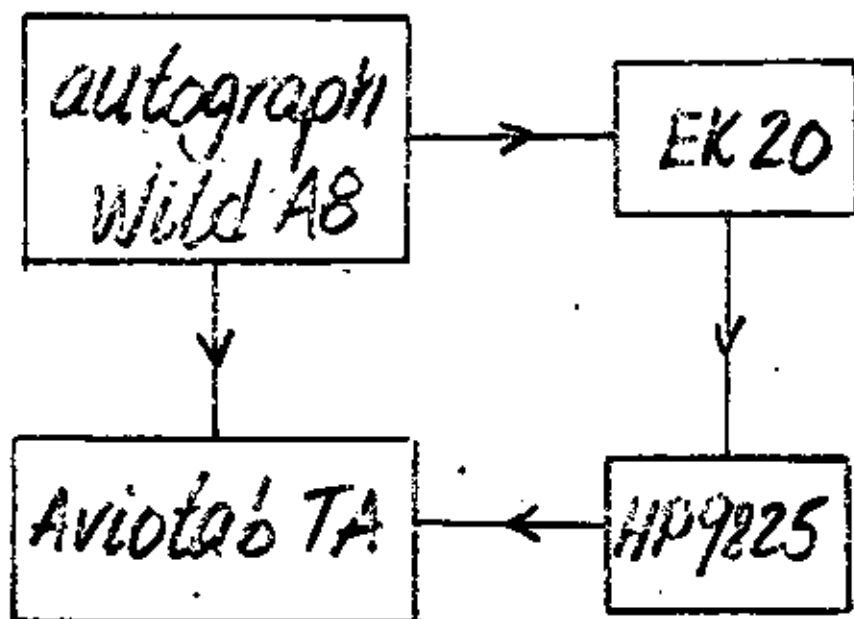
map production

field check

position
content
elevation



computer assisted mapping



map production

specifications

accuracy application
level

I special projects

II city areas

III towns and rural
areas with high
land values

IV other rural areas

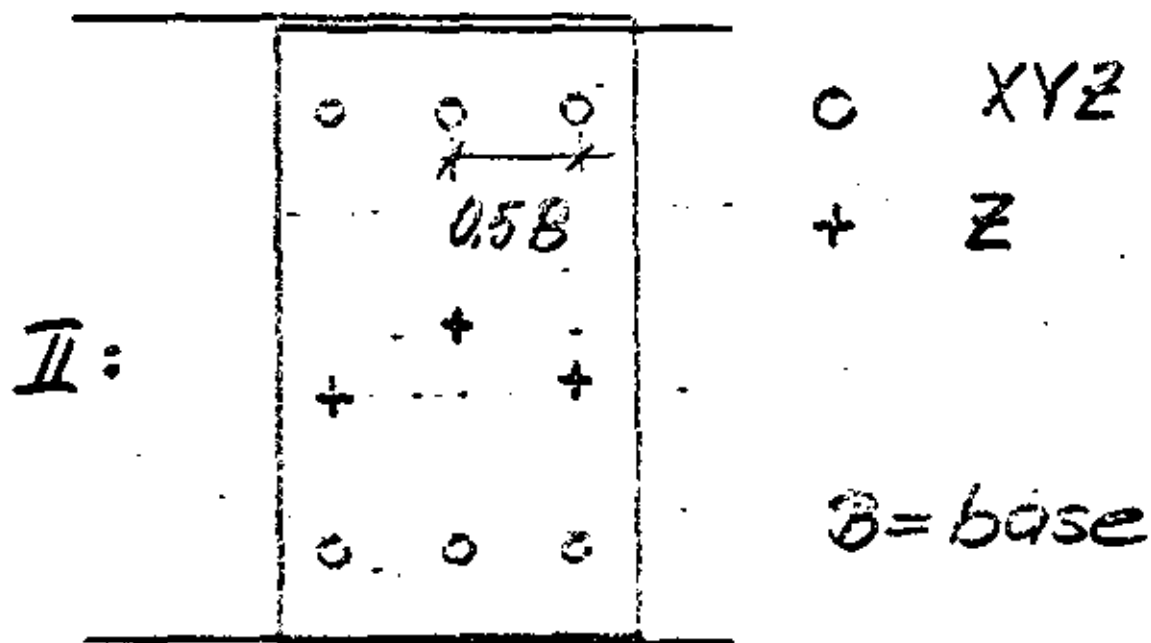
map specifications

examples

accuracy level	mapping		field survey closing errors	
	map scale	photo scale	traverse	levelling
<u>II</u>	1:500	1:4000	$0.125\sqrt{L}$	$0.015\sqrt{L}$
<u>III</u>	1:1000 1:2000	1:8000 1:10000	$0.250\sqrt{L}$	$0.030\sqrt{L}$
<u>IV</u>	1:1000 1:2000	1:10000 1:30000	$0.600\sqrt{L}$	$0.060\sqrt{L}$

L = total length
in km

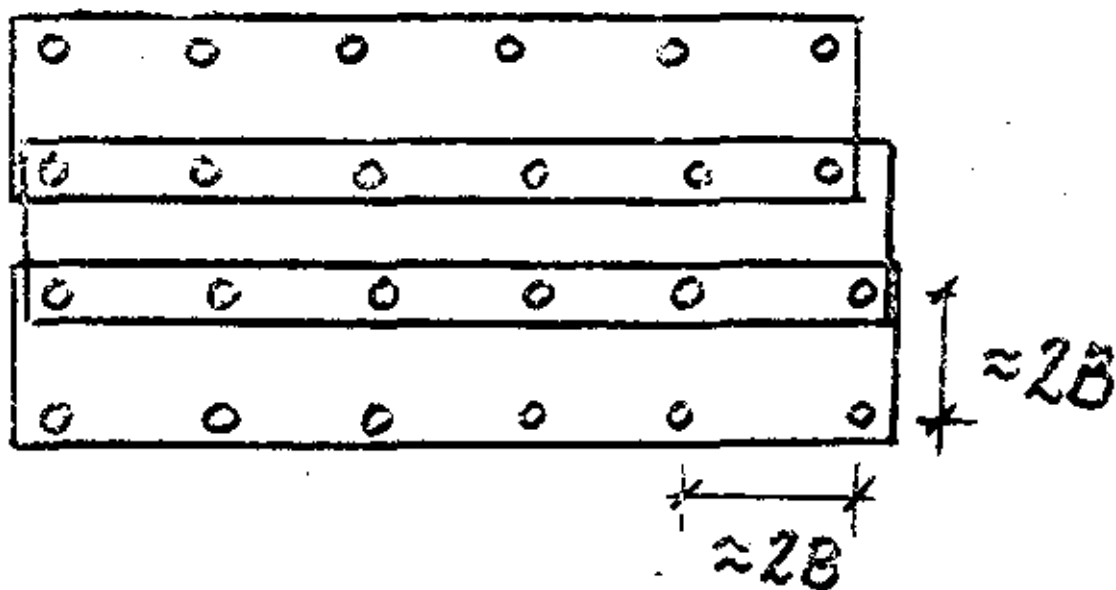
geodetic control; no a.t.



III: as in II but with less +
(1/3)

IV: 4 o and 6 +

geodetic control, block triang.



II-III o XY
 + Z 5-9 in each model

IV o inside block can
 be left out

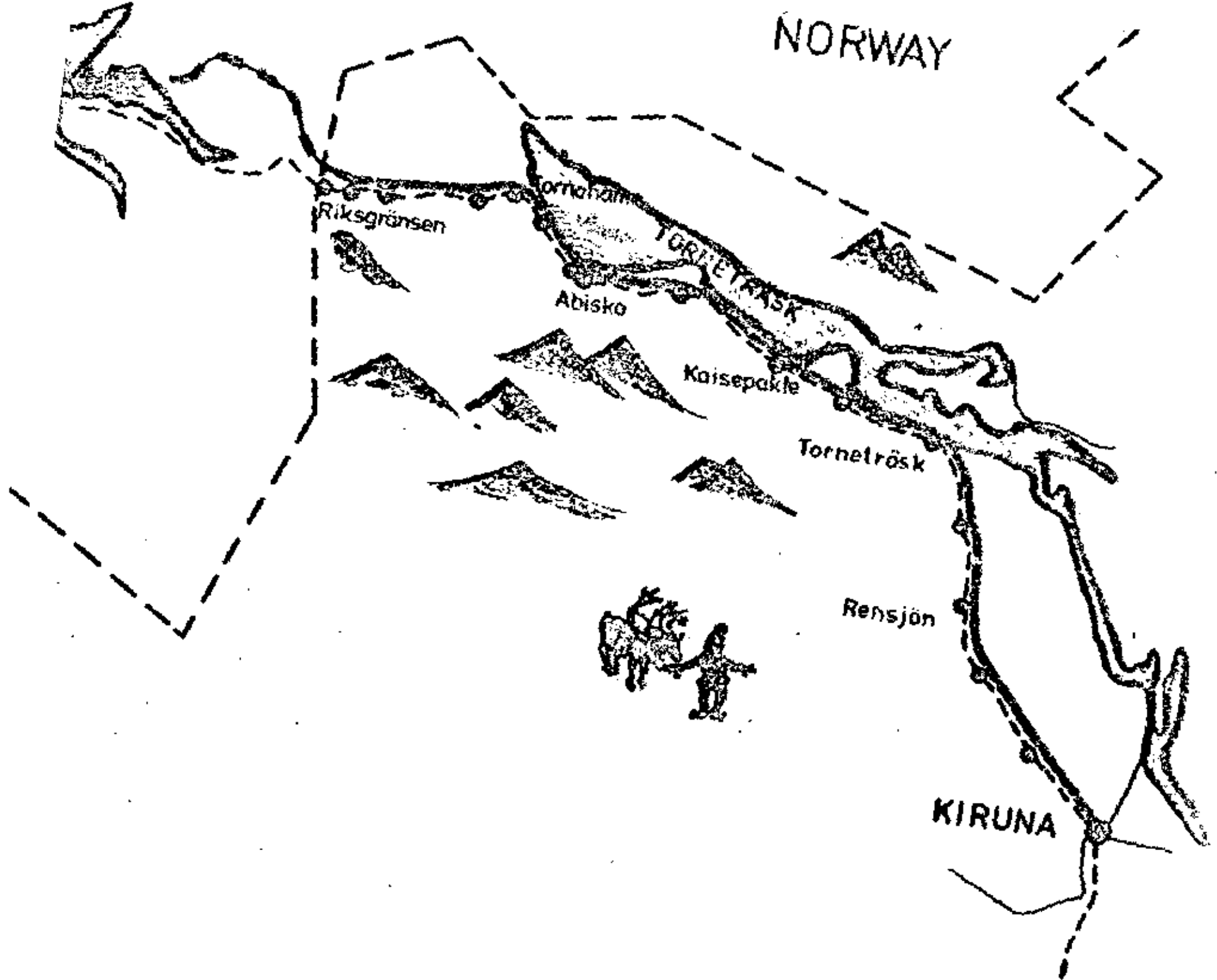
maps for airports
in Sweden

Photo scale 1:4000

Map scale 1:500

Contours 0.5 m

DTM



KIRUNA - RIKSGRÄNSEN

Some project data

total length: 130 km

aerial photography:

1:13000 130 km

1:5000 90 km

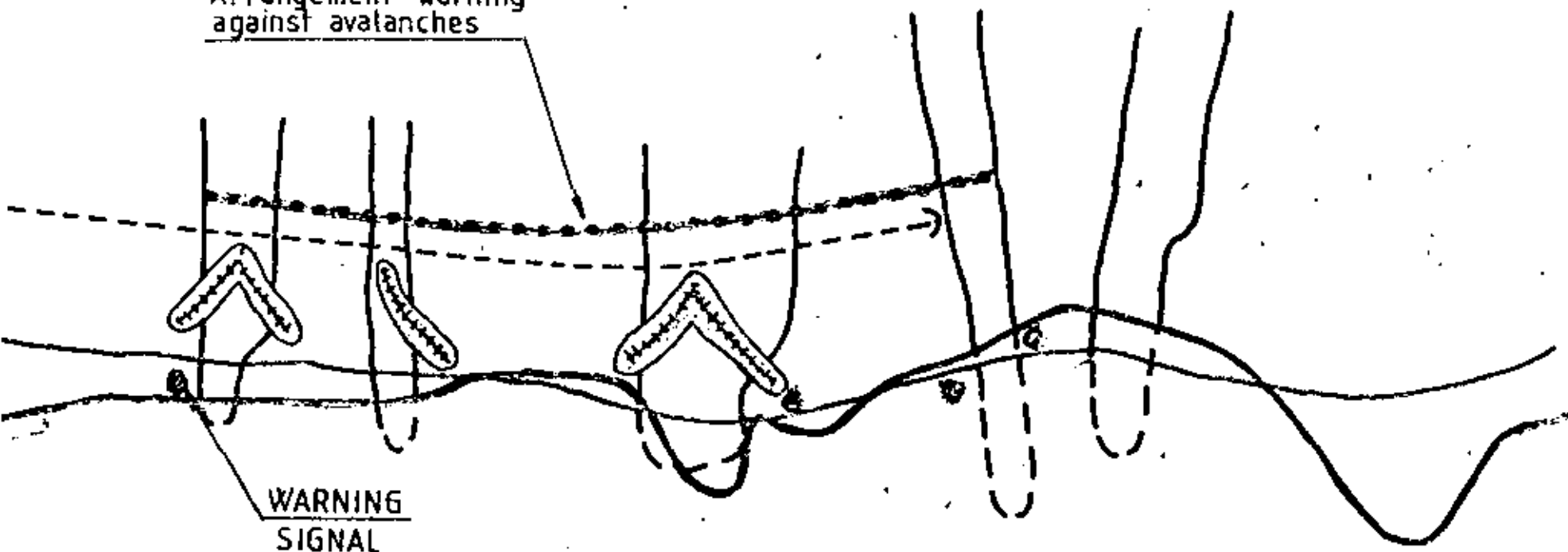
maps: 1:2000 65 km²

cross-sections: ≈ 10000

≈ 250000 points

AVALANCHE ARRANGEMENT

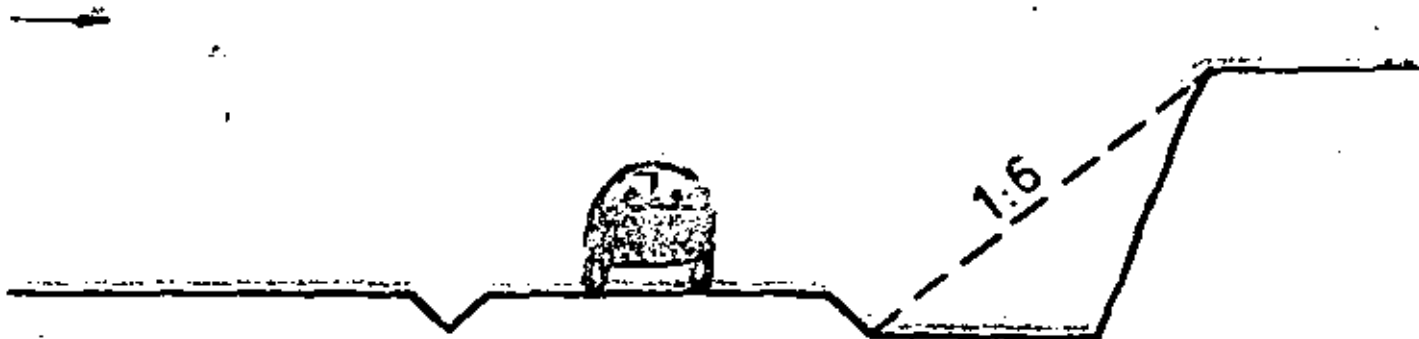
Arrangement warning
against avalanches



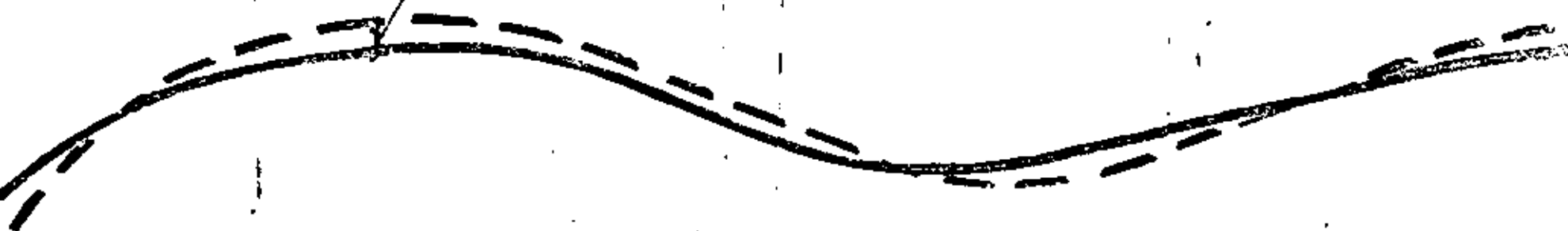
WIDEN SECTION



WIND
DIRECTION



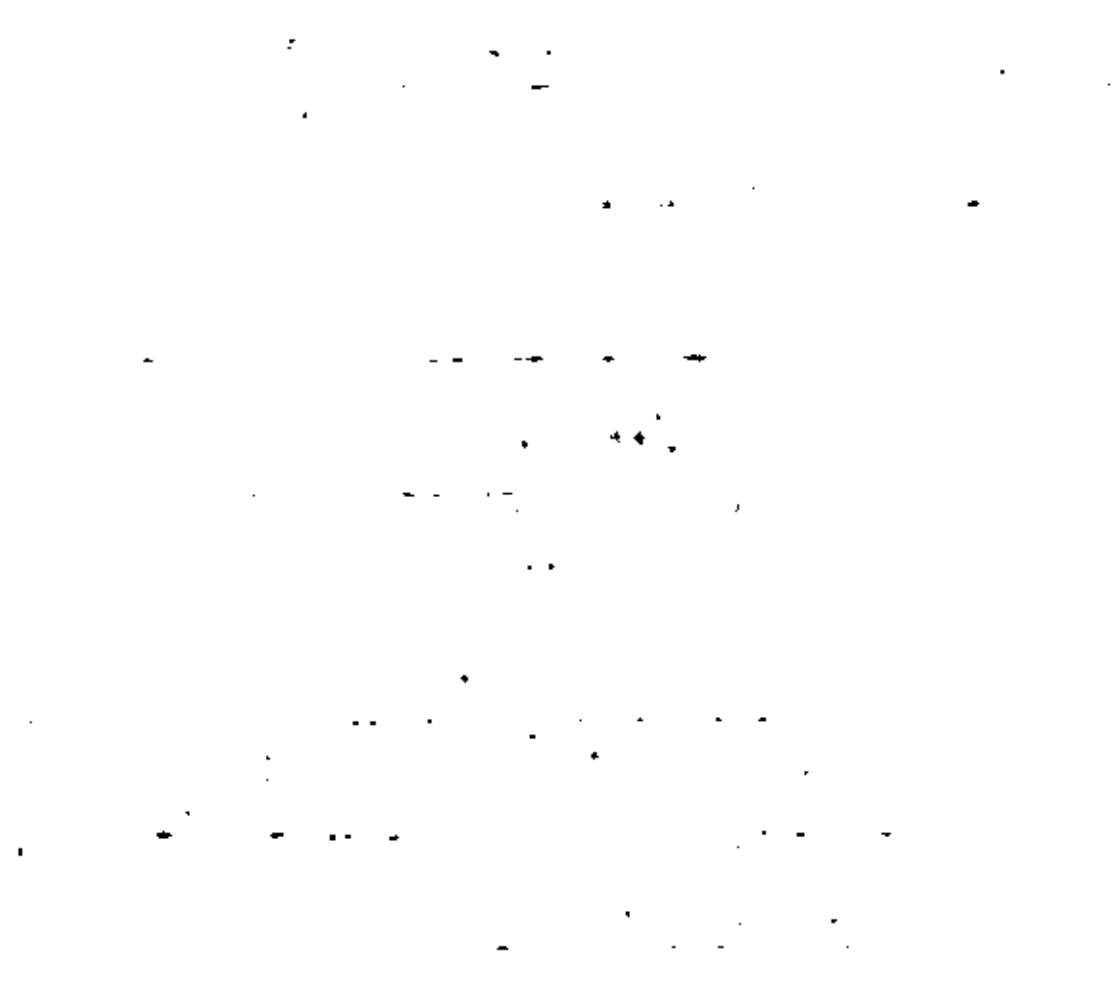
MAX. DIFFERENCE CA: 30 CM



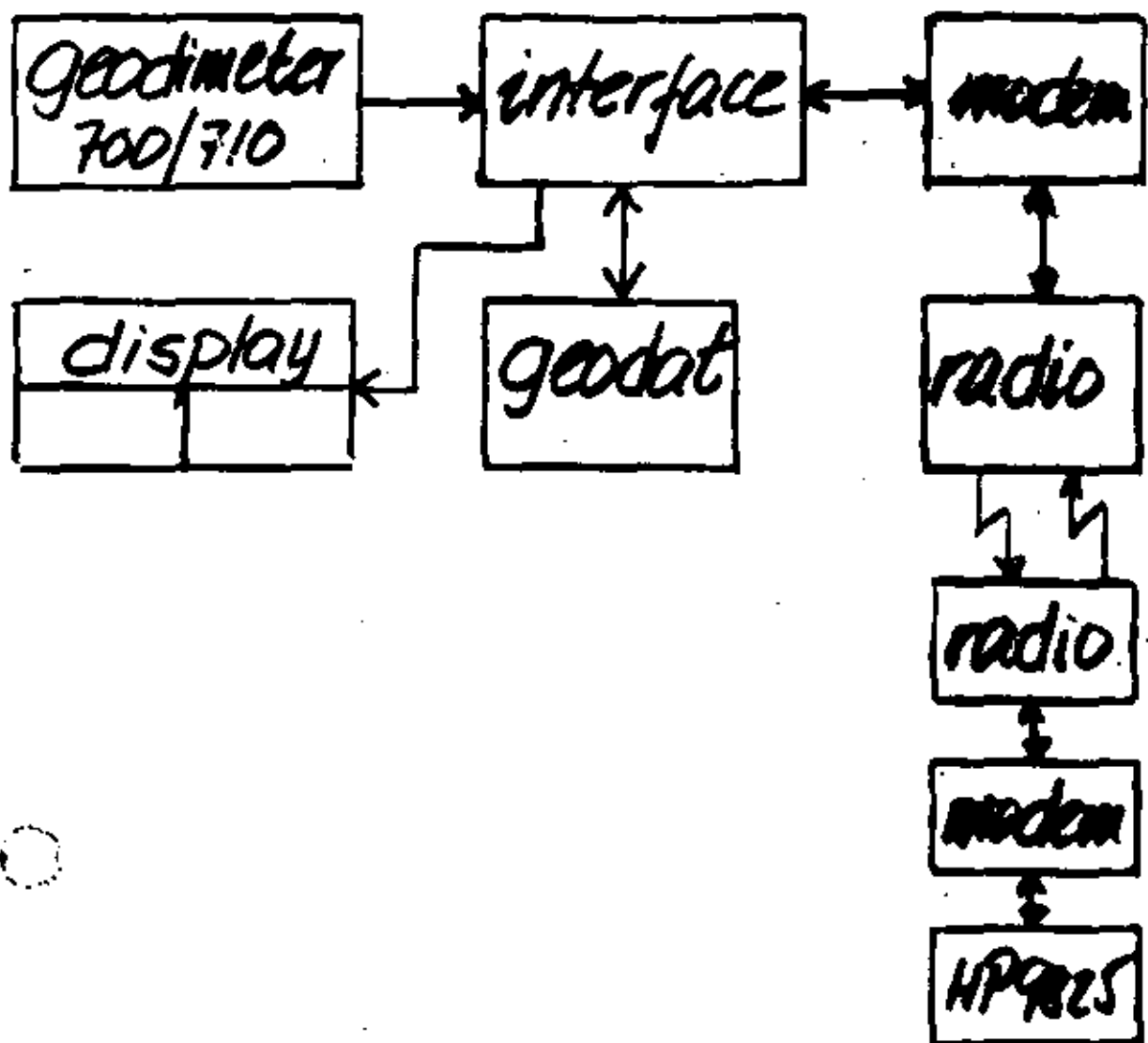
3 KM 30 P +2 CM
2 KM 20 P -6 CM

Empirical accuracy of
a stereo model

	%00 of flying hight	
	point by point	mapping
S _{xy}	0.10	0.25
S _z	0.15	0.20



an interactive field station



field surveying

data acquisition

solid state

electro optical tacheometer

radio transmitted data

computing + solid state

setting out

distance display ~~etc~~

at reflector. ~~etc~~ (Kern)

field surveying

electro-optical tacheometry
data acquisition

- solid state memories
- wireless transmission

setting out

- computer supported
- distance display at reflector station

GIS facts

joint conference ICA/ISP Zürich ^{Summer} 1979

Major trends ⁱⁿ GIS

manual digitizing is operational in many countries

interactive editing increases

interactive 2D digitizing in progress

raster scanning / laser line following = research and development stage

data base management = primary concern

- types of data to store
- structuring of data for optimum use
- storage medium
- ~~availability of data~~
- national policy of availability of cartographic data bases
- up-dating procedures

displays

selective retrieval
generalization

color ink on paper

scribing

light head

raster plot = in development

DETENAL



- investigate the variety needs and demands, ~~now~~ and present and future
- study existing ~~processors~~ systems in operation
- survey ~~use~~ of equipment, implementation and handling
- be prepared of large initial investments and a great organizational change (education)

System

Application
 MGS
 Computer Vision
 Huntings, England
 SYNERCOM (Wild)
 ARISTO

digitization

key-board
 menu
 "coordinate coding"
 voice recognition

digital mapping

activities in Sweden

- National Land Survey

- city of Malmö

 - Göteborg

 - Stockholm

- private firms

 - K-Konsult

- Technical University

- National Road Administration

- National Building

 - Research Council

feature coding

structure of codes

code setting

key-board

menu

"coordinate coding"

voice recognition



data base concerns

- types of data to store
- structure for optimum use
- up-dating procedures
- national policy of availability of map data banks



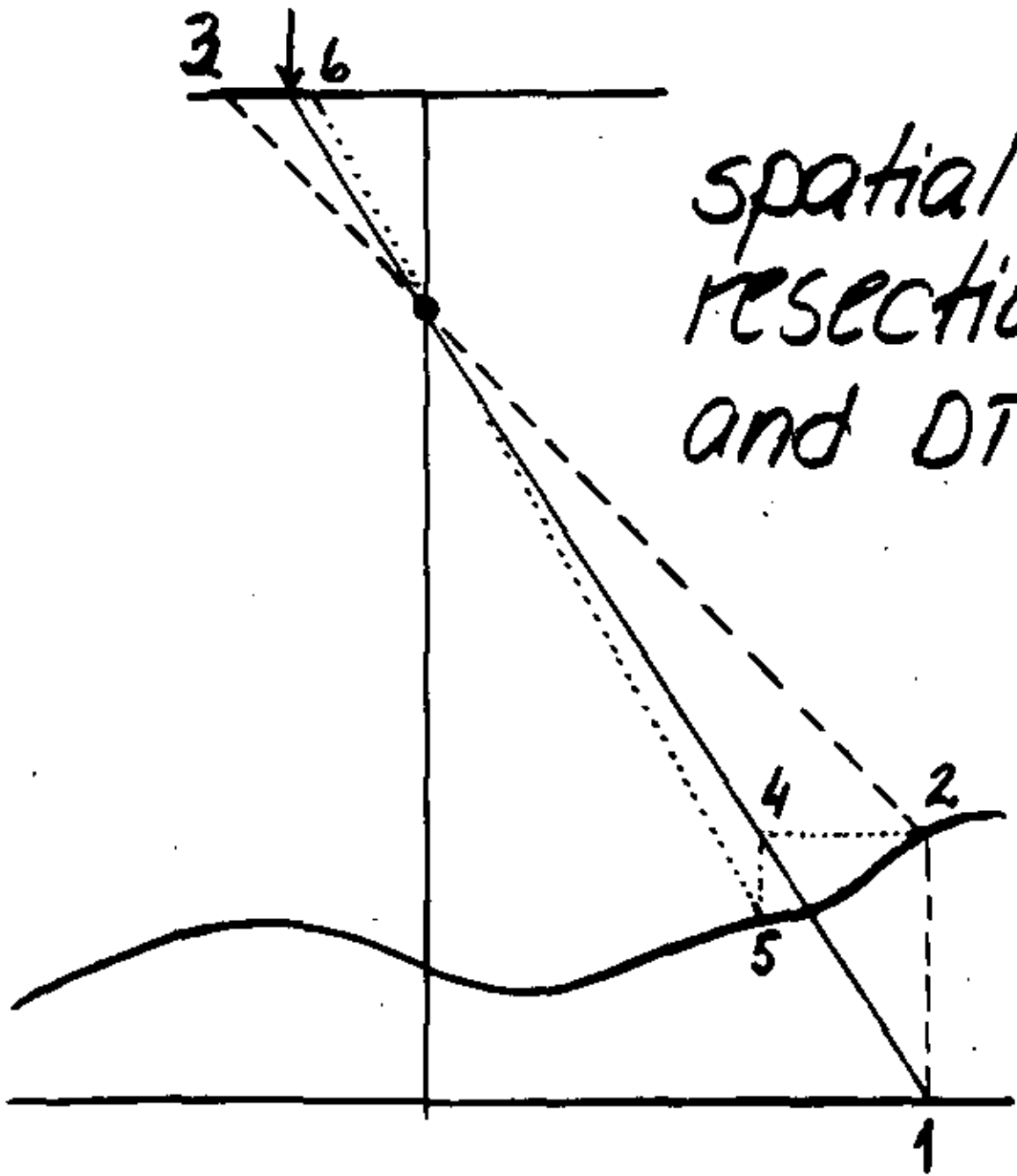
Interactive Graphic Systems

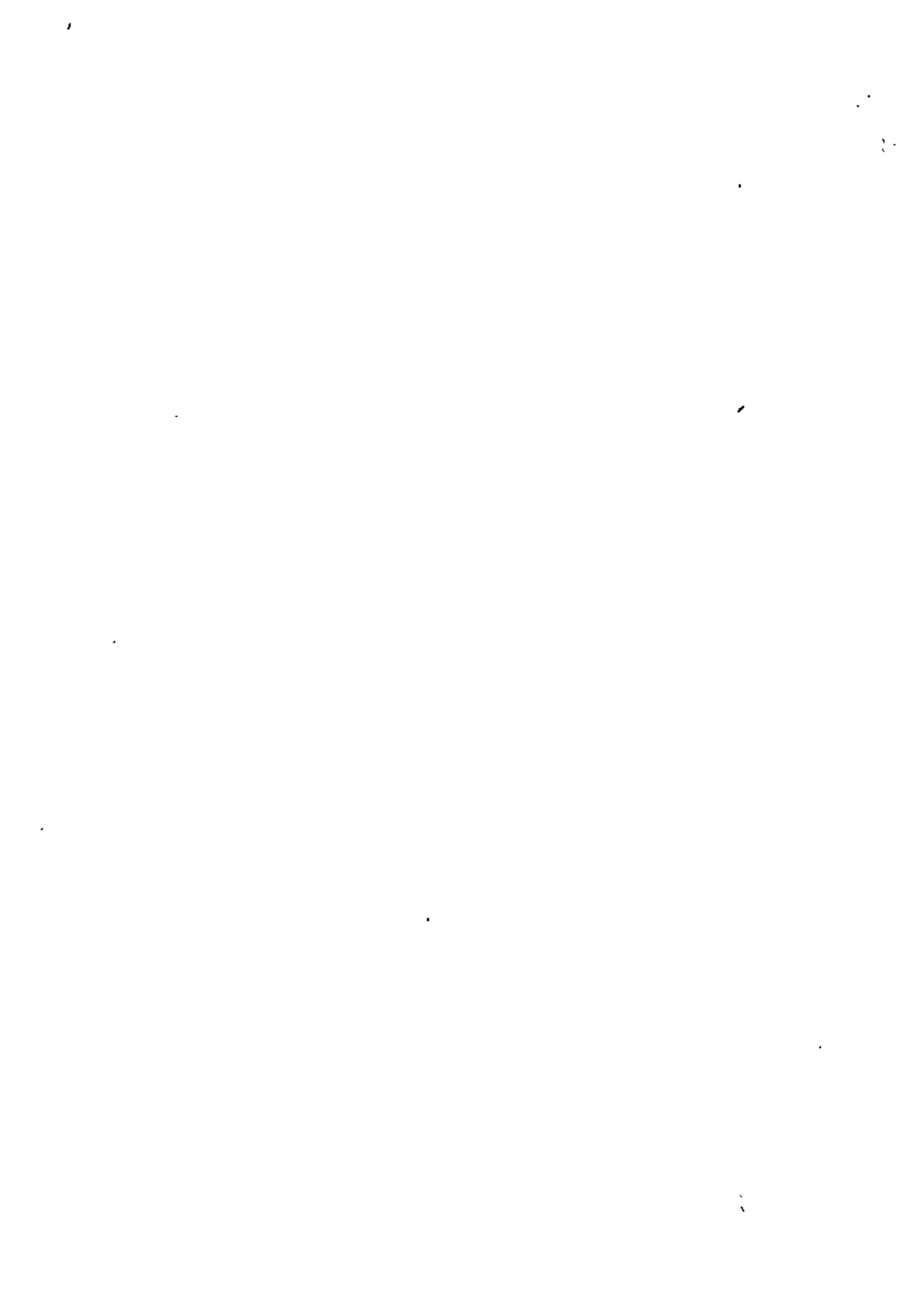
IGS

major trends

- 2D-digitizing mostly used
- 3D-digitizing in progress
- interactive editing increases
- raster scanning/plot in development
- data base management is a primary concern

digital mono plotting





Digital Terrain Models

interpolation

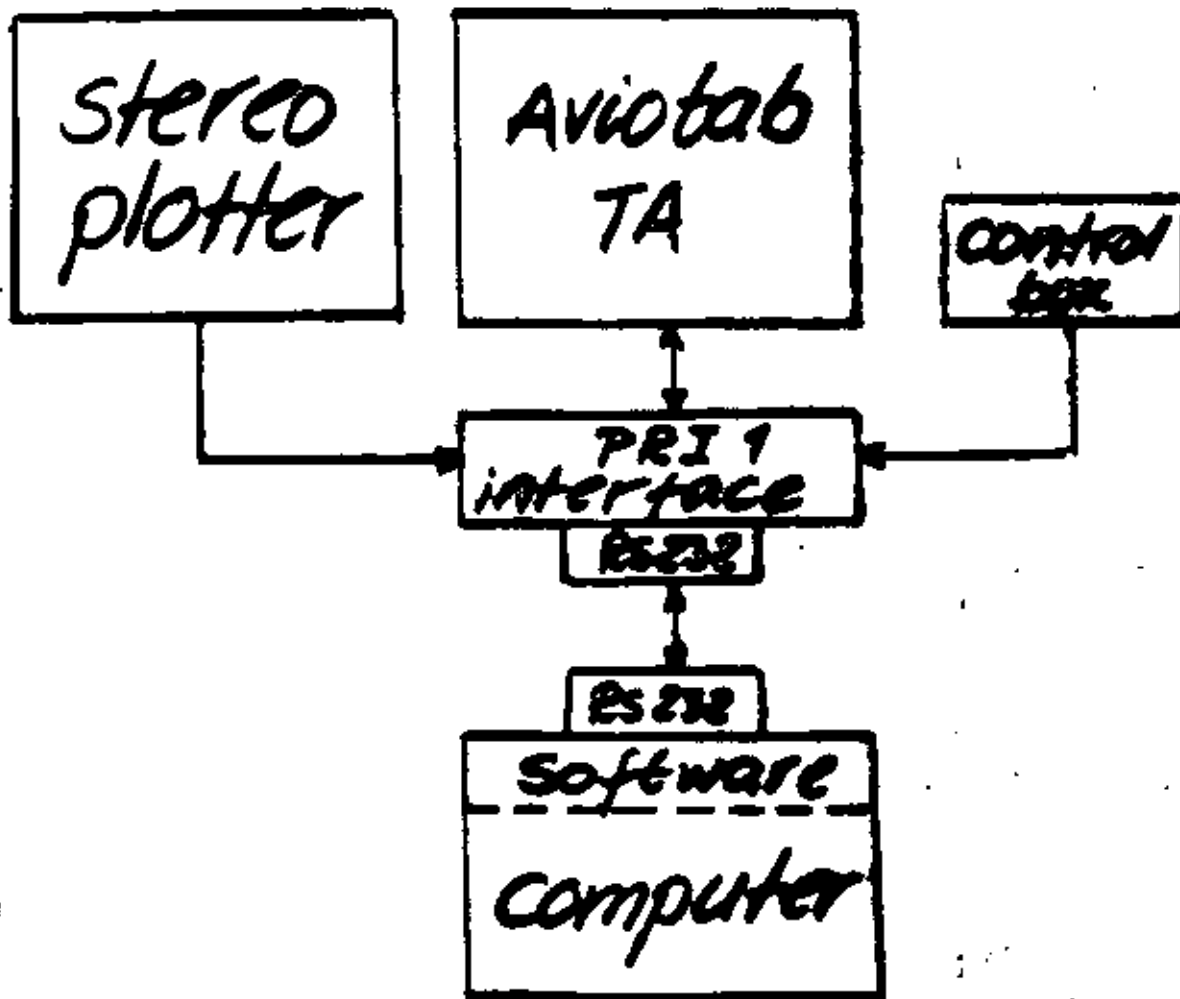
progressive sampling

on-line control

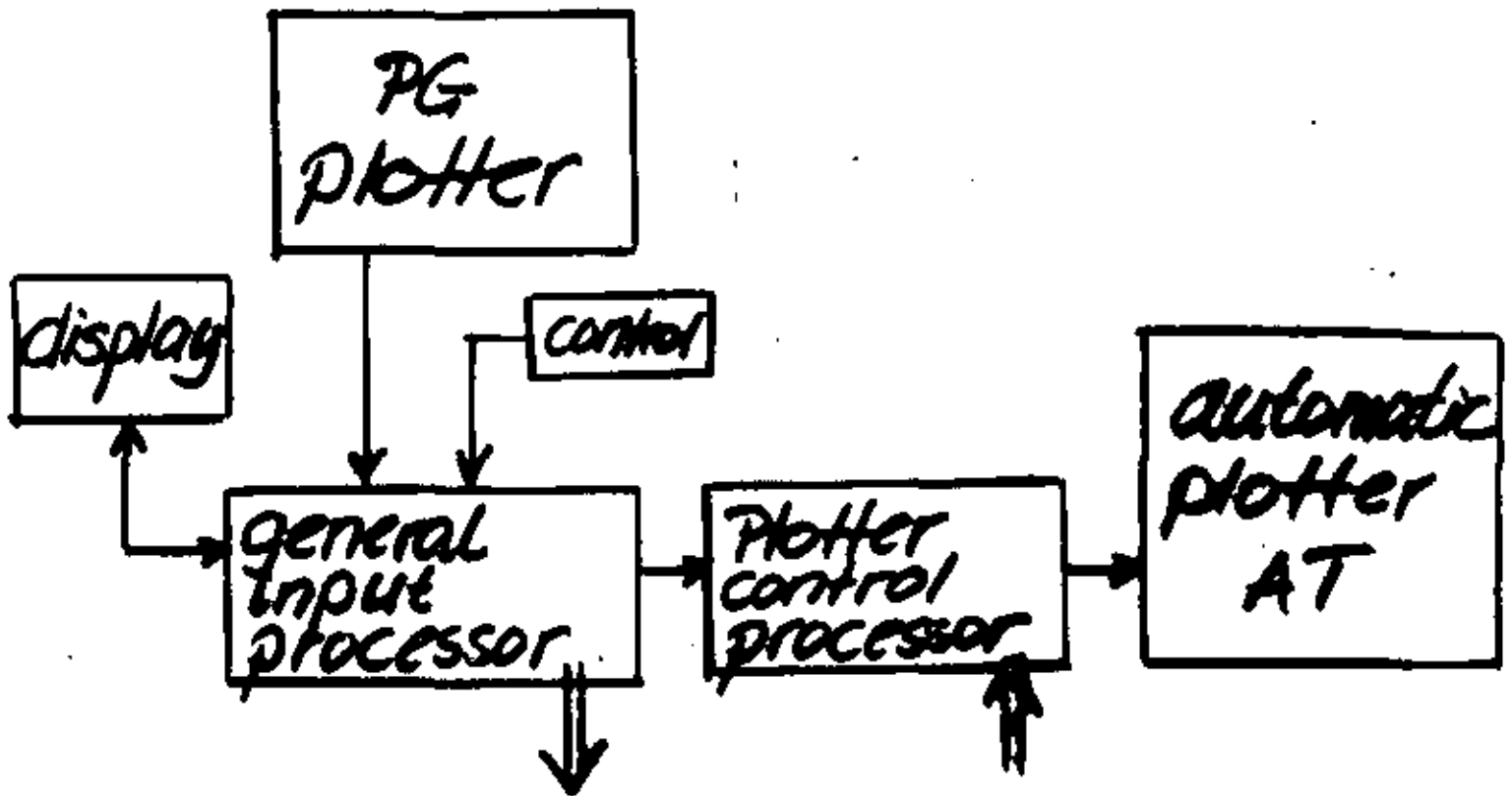
filtering

mono plotting

Wild AVIOTAB/PRI 1 system



Kern DC2-B Computer-supported plotting system





plotting

analytical plotters (7 nya i H-fors)
bara wild skumar

CAM Korn WILD PRI

1 Digital wawa plotting

IGS

land use
nationwide (~~1000000~~) inventory

"feature extraction by interactive digital image
processing system"

WAMS Wetlands Analytical Mapping System III

US Fish and
Wildlife Service
Florida

Triangulation (ADPS III analytical Plotting System III)
Digitizing (of wetland delineations)
Wetland Data Base

Varför automatisera kartpic?

+

mindre kostn.

datubank

kvantitet

flexibel stereometri

enklare utvärdering

personell utbildning

stora mängder data, tereringar

Flood elevations areas interactive PGZ/HP1000

(~~10~~) (Tennessee, US)

fruts

analog plotters

- electronic plotting tables
- fast coordinate recording
- computer-controlled
DTM-measurements
- computer supported
orientation and plotting

orthophotography

numerical control

correlators

analytical plotters

independent of interior
and exterior orientation

automatic scanning

semi — " — profiling and
cross-sectioning

increased accuracy

progressive block triang.

great flexibility

Analytical plotters

1987-8

DDT

ES K&E/H. Dillinger ESS-300-II

Italy Galileo Digital Stereoscopy

US OME AP/C4

PS Bendix DS-1

France Astra Master 77 (color + light)

German. Zeiss Maincomp C-100

+ ~~metre~~ drift

autom. installer. på

sted

Autom. drawing i profileret

to transfer points \otimes

progressive ~~draw~~ ^{stack} simulation

rel. av = 4-6 μm \Rightarrow 2-3 \times better

5x smaller in analog

(see recovery)

System for evaluation (Makarovic)

$S_{xy} = 2-3 \mu\text{m}$

\otimes 1. signalized (between stripes or between models = pin points)

\Rightarrow always expensive

2. natural points (30% or stereotides)

$S_{xy} = 3-7 \mu\text{m}$ microstereography
 $S_{xy} = 3 \mu\text{m}$ stereostereography

3. artificial points (inl on film characteristic)

4. three-plate comparator

5. analytical plotter

analytical plotters

K&E/H. Dell Foster, US	RSS-300-II
OMI, US	AP/C4
Bendix, US	US-1
Matra, France	Traster 77
Zeiss, Oberkochen, W. Germ.	C-100 Planicom

block triangulation

self calibration

progressive adjustment

attainable accuracy

position	1. comparator	12-25 μm .
	2. analog plotter	25 μm
	3. analytical plotter	12-25 μm .

height	1.	20 μm
	2.	25-40 μm .
	3.	20 μm

data processing

pocket calculators

desk top computers

mini computers

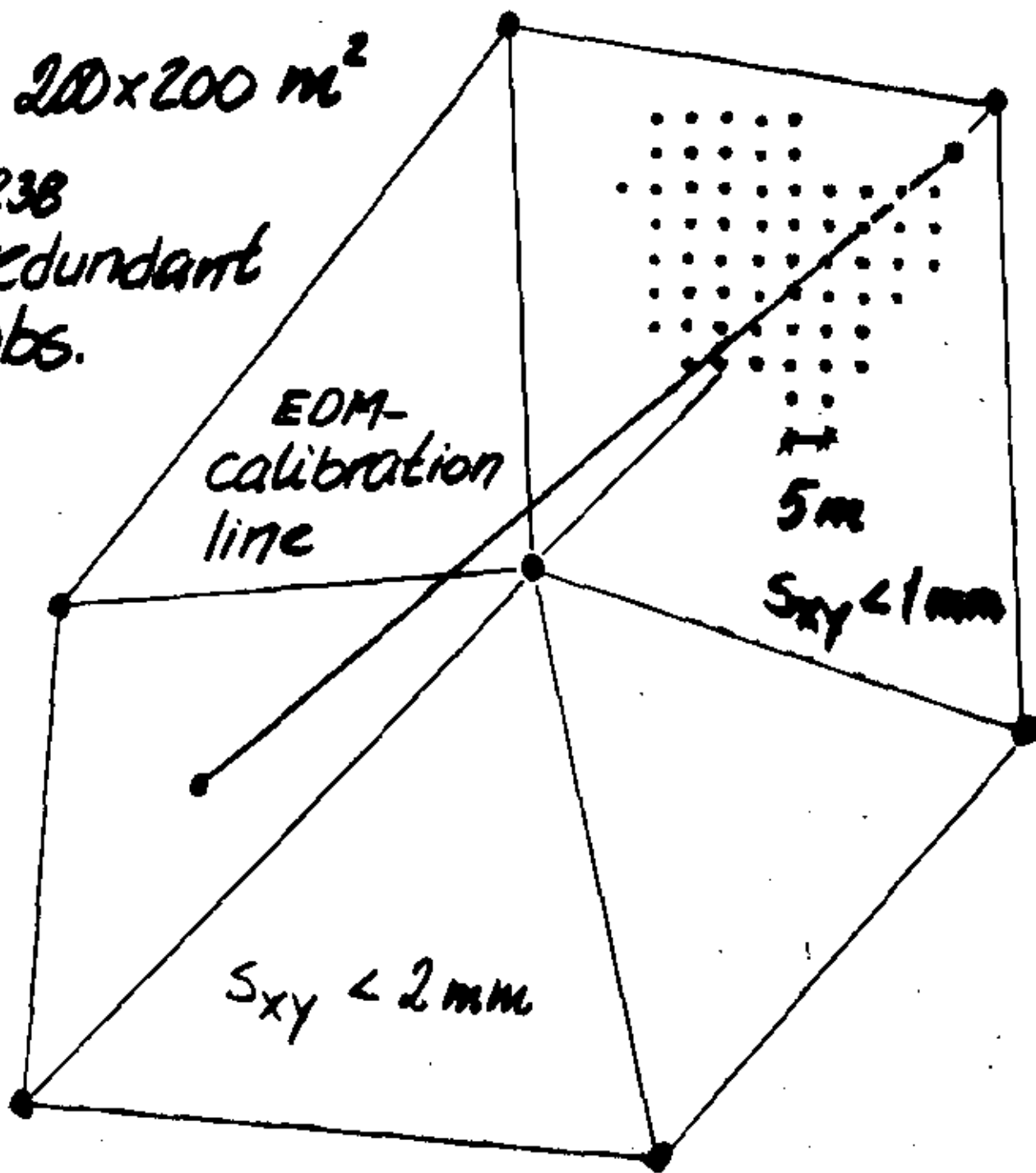
large computers

terminals

a high-accurate test field

$\approx 200 \times 200 \text{ m}^2$

238
redundant
obs.





accuracy studies

theoretical

simulation

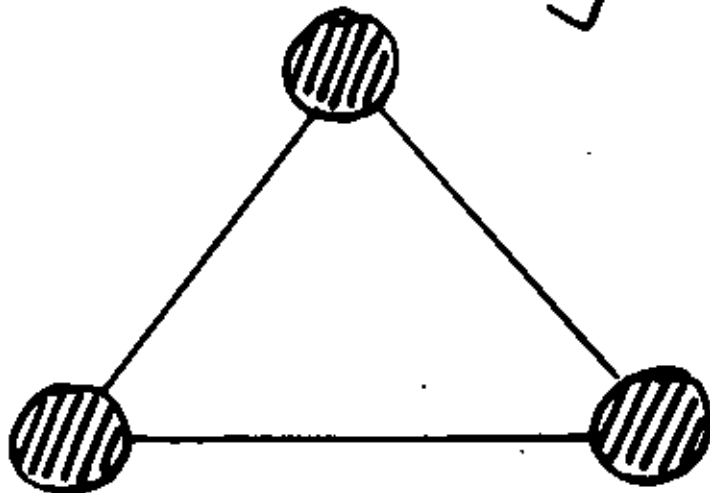
empirical

test field

practice

survey planning

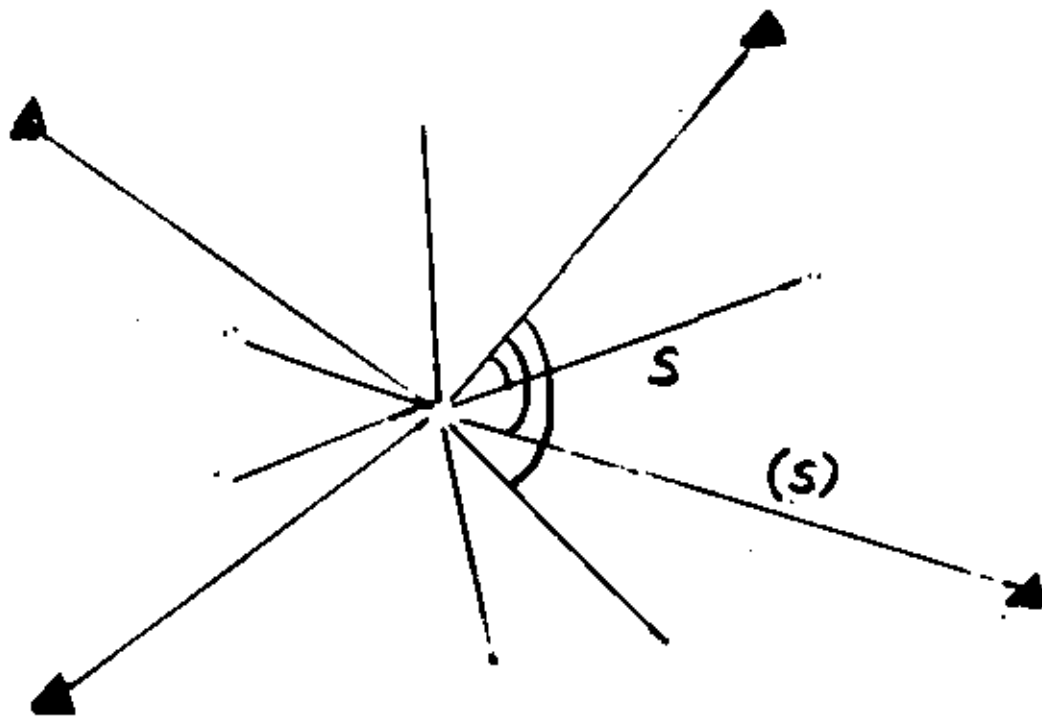
accuracy



geometry

method

ELECTRO-OPTICAL TACHEOMETRY
SURVEY SYSTEMS



RESECTION TECHNIQUE

setting out methods

orthogonal

polar

intersection

resection + polar

EDM-instruments at the
Swedish National Road Adm.

AGA Geodimeter 6

" " 12(A)

" " 14

" " 120

" " 700

Kern DM 501

" ME 300C

Wild DI 3(S)

" DI 10



AGA Geodat 120

CODE

0 CODE
1 DATA

STN


2 STN
3 IH

4 PCOD
5 PNO
6 SH

7 HOR
8 ELE
9 DIST

FUNCTIONS

F0 ON/OFF
F1ENT REG AMM POS
F1 TAPE OUT
F2 TAPE IN/CHECK
F3 V24/RS-232 OUT
F4 CALC OUT
F5
F6
F7 JMP POS 0
F8 SEARCH
F9 CONTINUE
F1 MEMORY
F10 CLEAR ALL
← DELETE
→ INSERT



SWITCHES

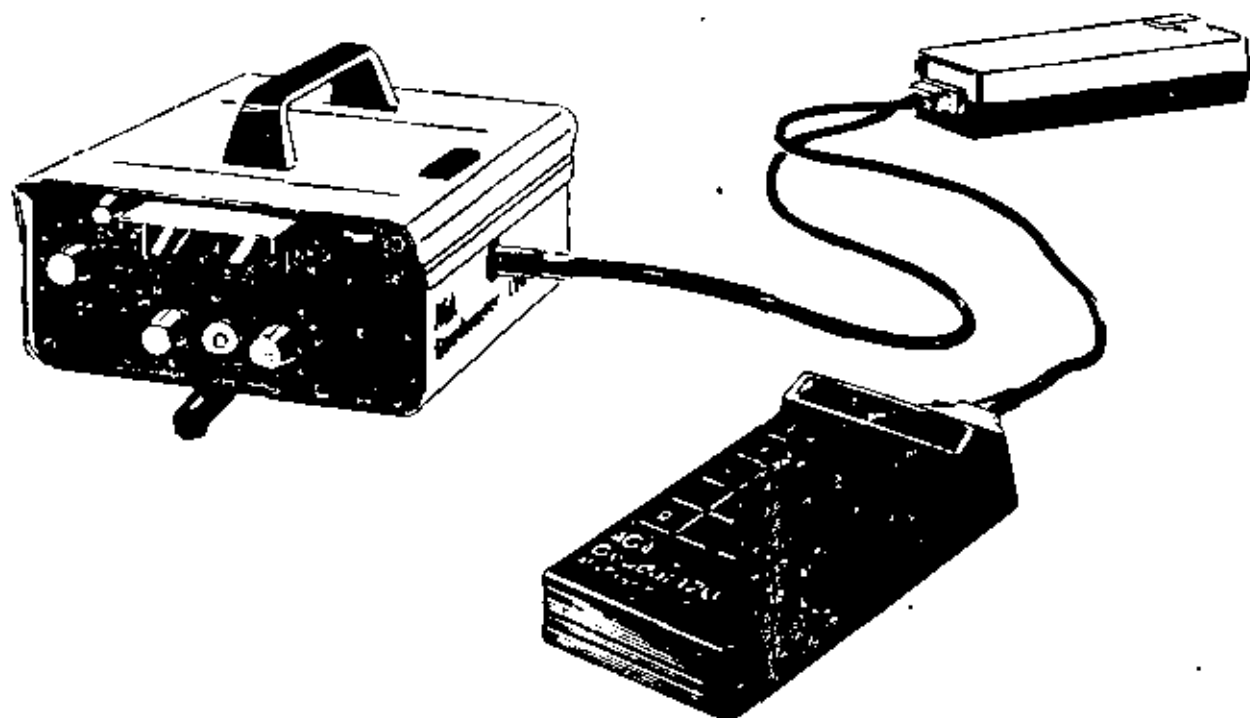
1 RESTART
2 POWER
3
4
5 RIGHT/LEFT BAUNDE
6
7
8
9
10
11
12

S00 S07 U07H

0 0 -
0 1 DIST REG
1 0 ELE REG
1 1 HOR REG

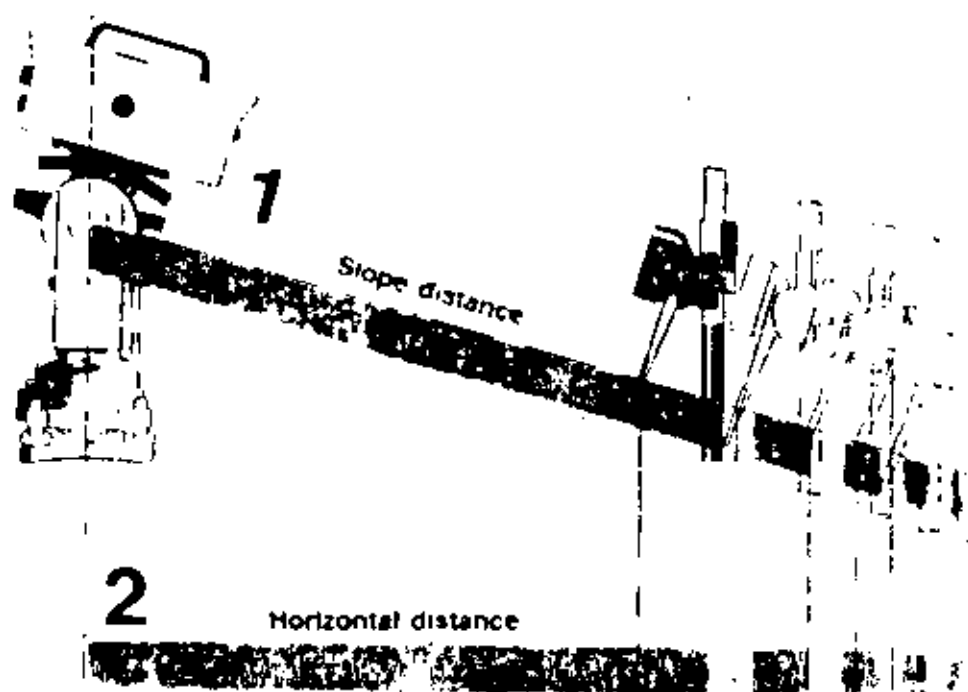
AGA

MEASURING SYSTEM 120

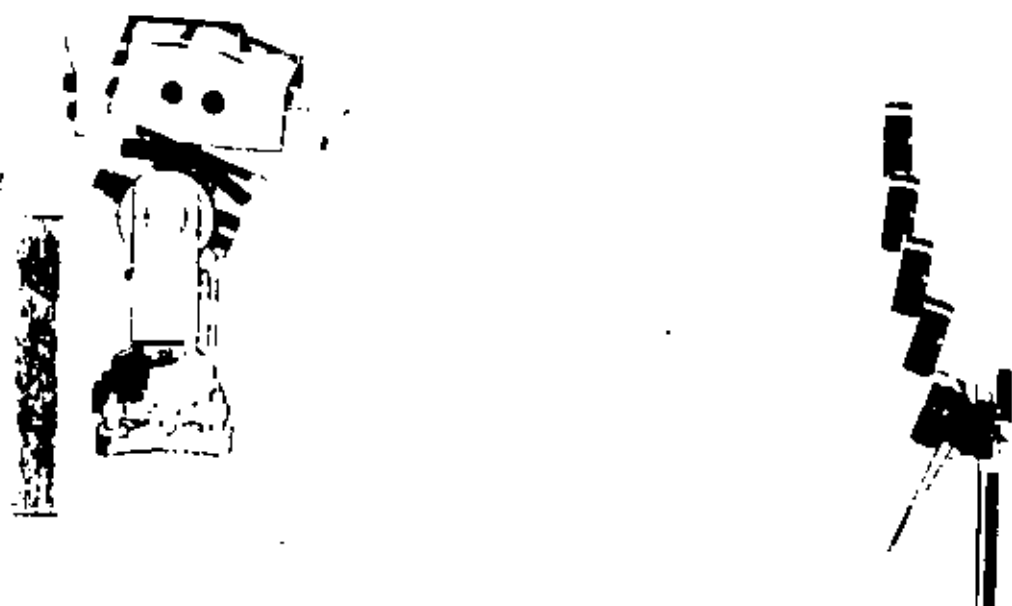


- Storage capacity: 16.000 characters
- Automatic storage of:
 - Slope distance
 - Vertical angle
- Manual storage of horizontal angle and station data
- Recall of stored data

THERE ARE THREE STAKE-OUT FUNCTIONS

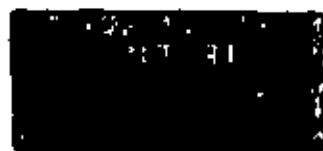


3

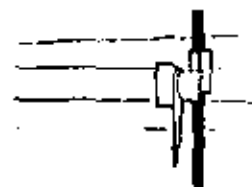


STAKING-OUT

- Distance measurement 2.5 times/second



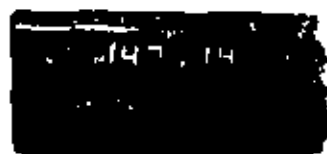
- Tracks moving targets



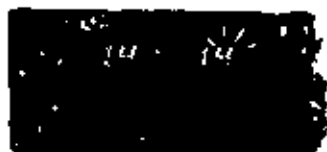
Max (4m / s)

- The display warns against poor accuracy

The instrument automatically checks if accuracy is to specification

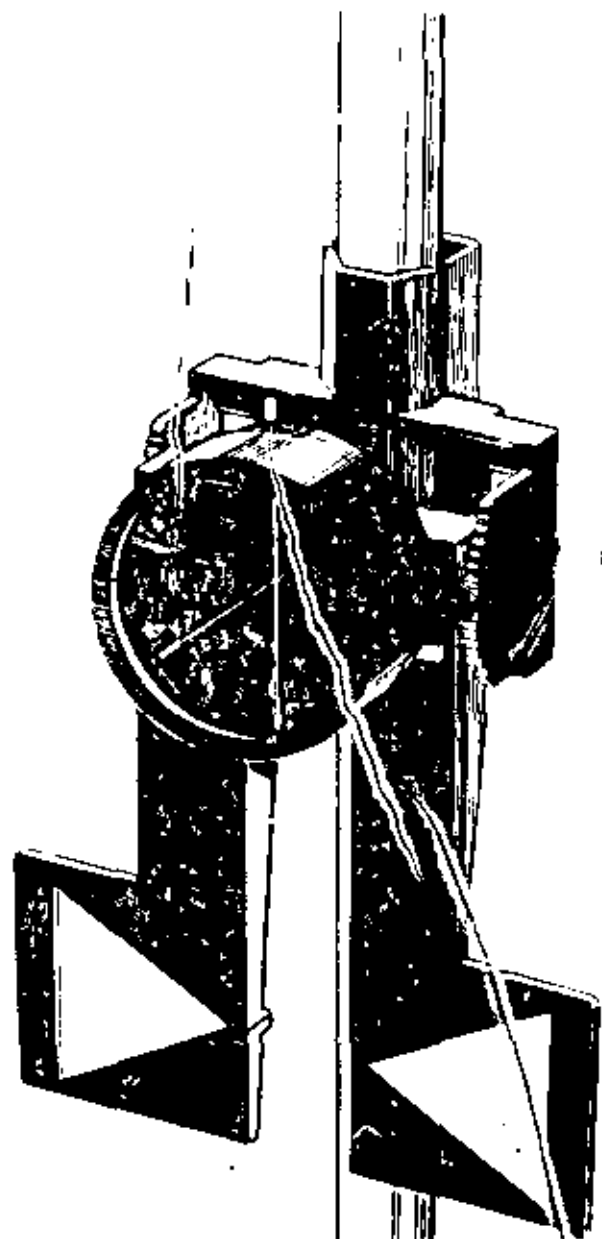
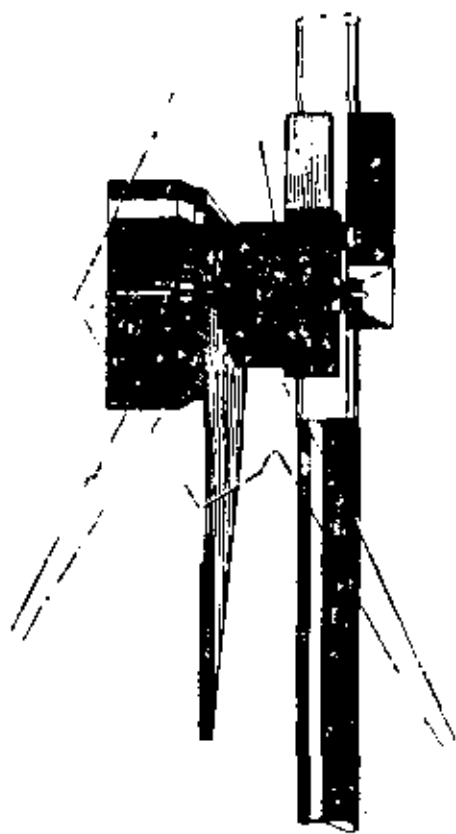


Good accuracy



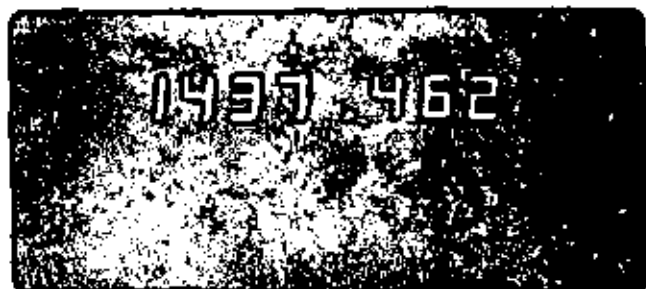
Flashing last figure indicates poor accuracy



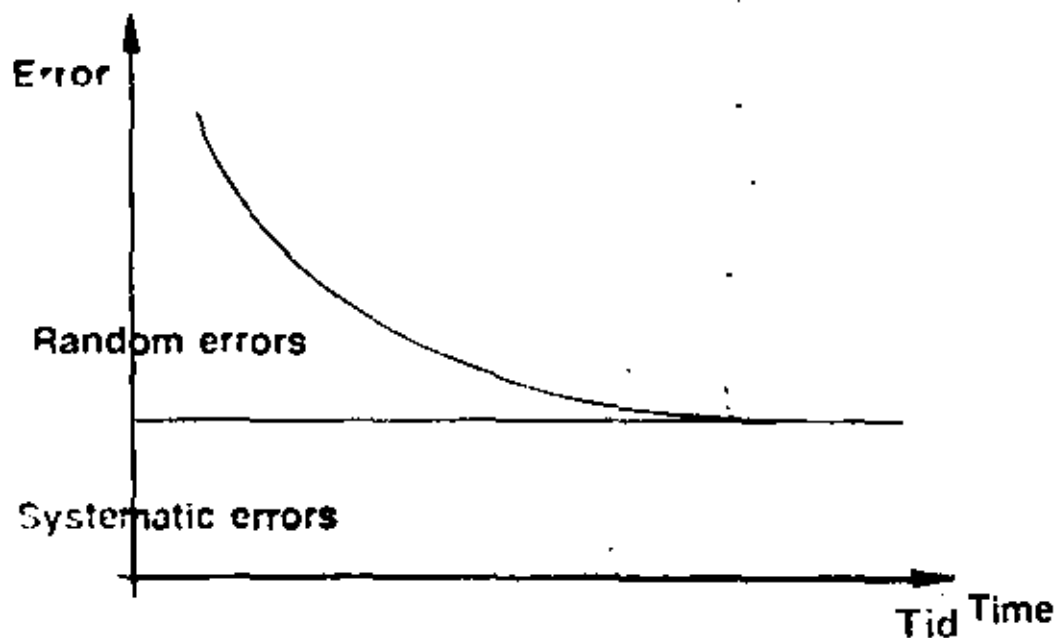


2-11-2

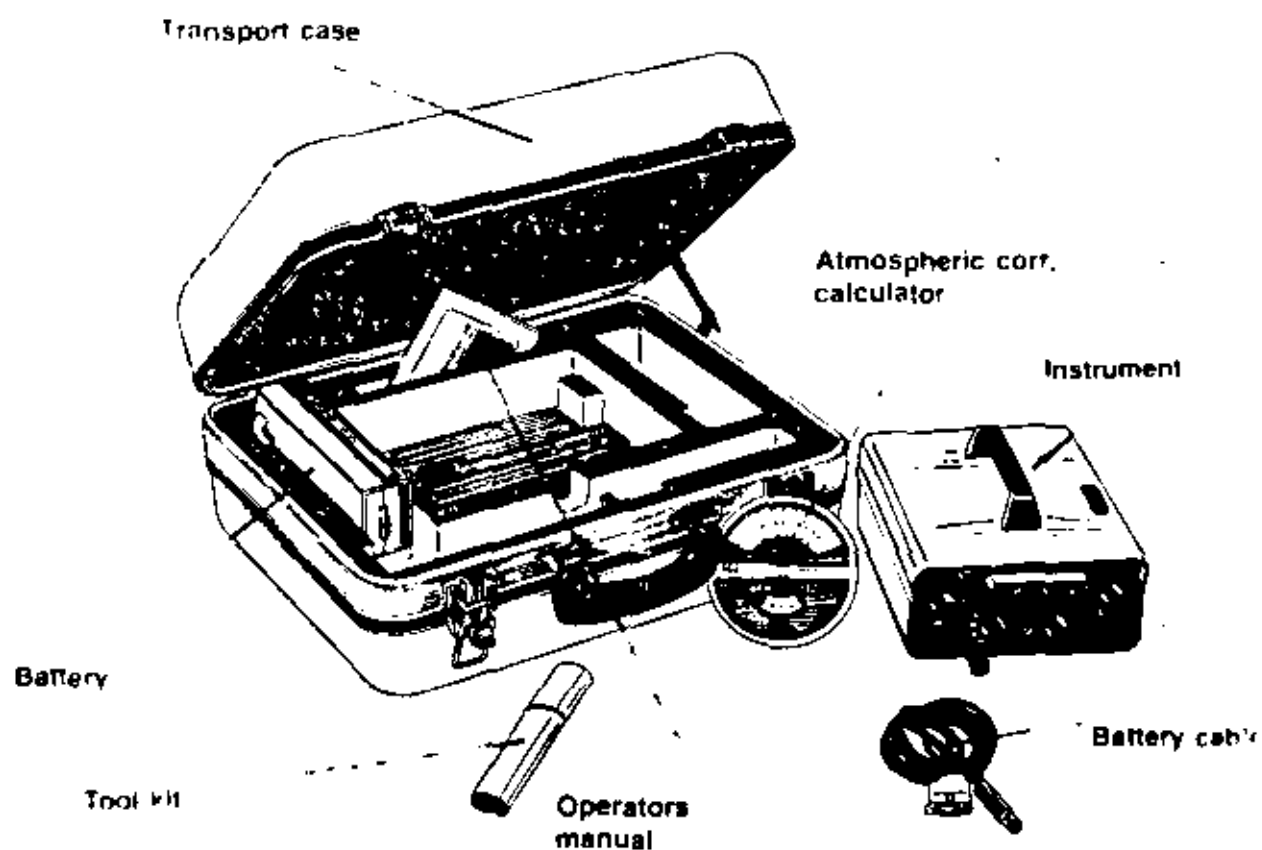
THE COMPLETE DISTANCE DISPLAYED NO AMBIGUITY



AUTOMATIC AVERAGING OF REPEAT MEASUREMENTS



BASIC EQUIPMENT

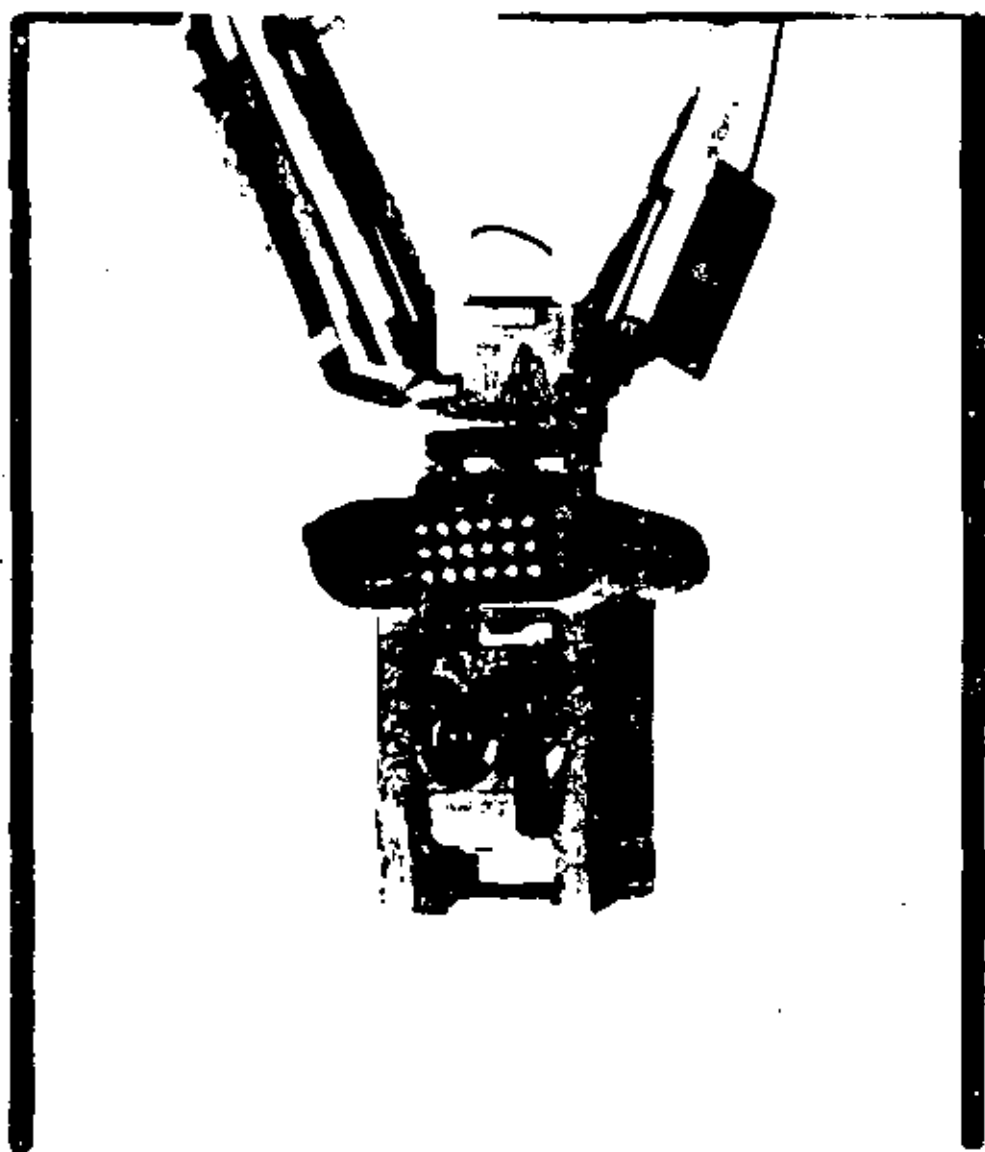


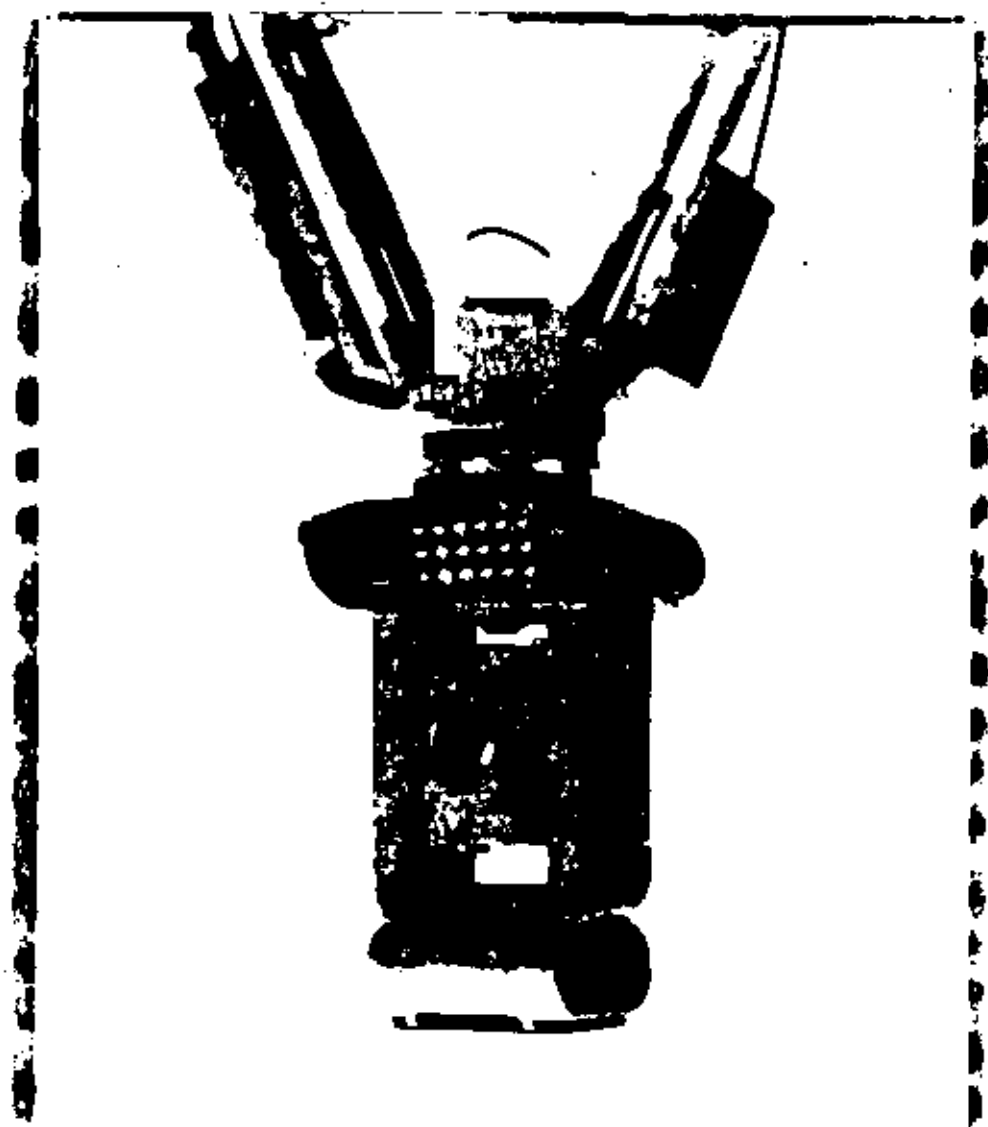


120

- 1 Totally automatic measuring**
- 2 Weight incl. batteries**
- 3 Tracking mode**
- 4 Good range**
- 5 Automatic data registration**
- 6 Flexibility**
- 7 Easy to use**
- 8 Automatic calculation of horizontal dist.**

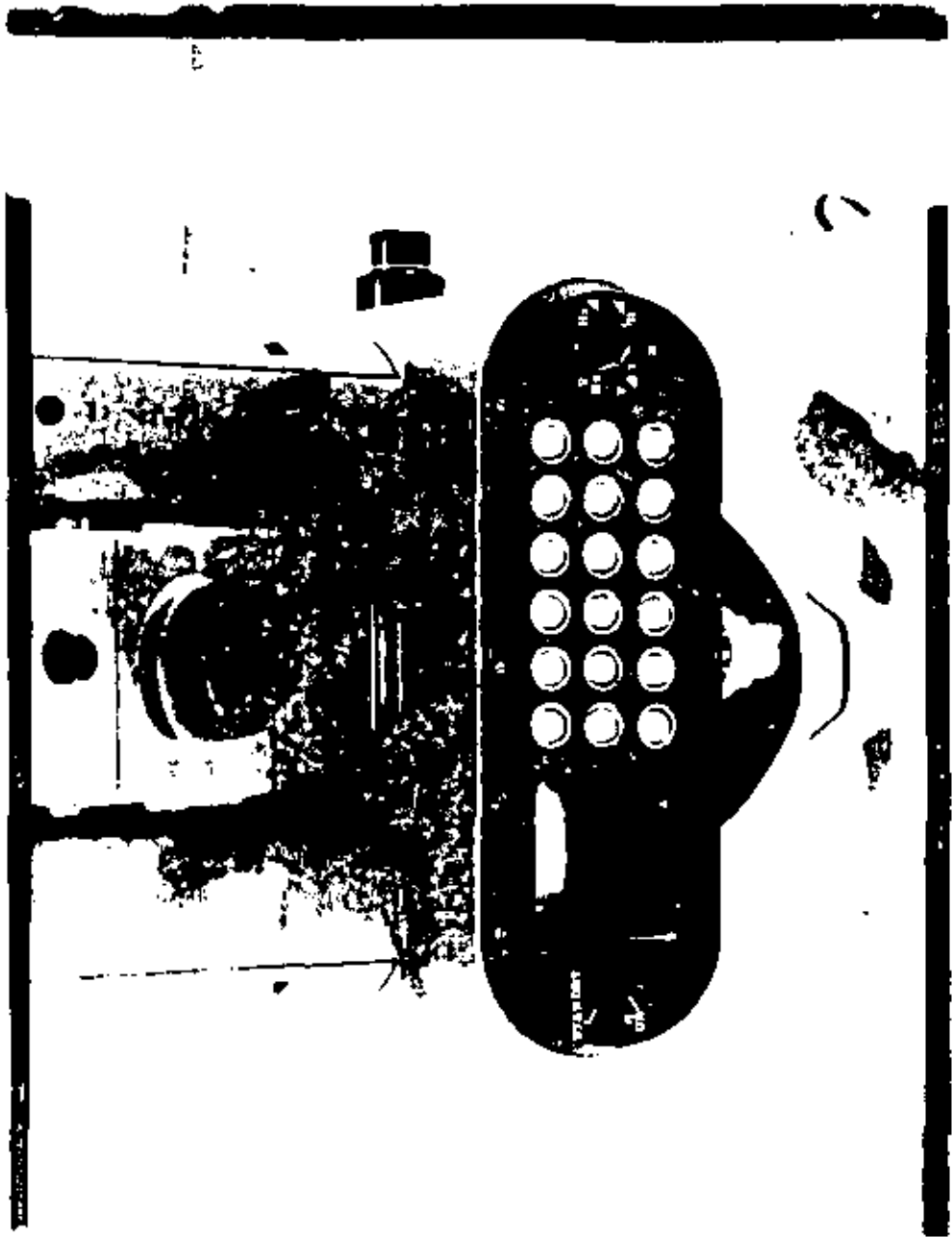










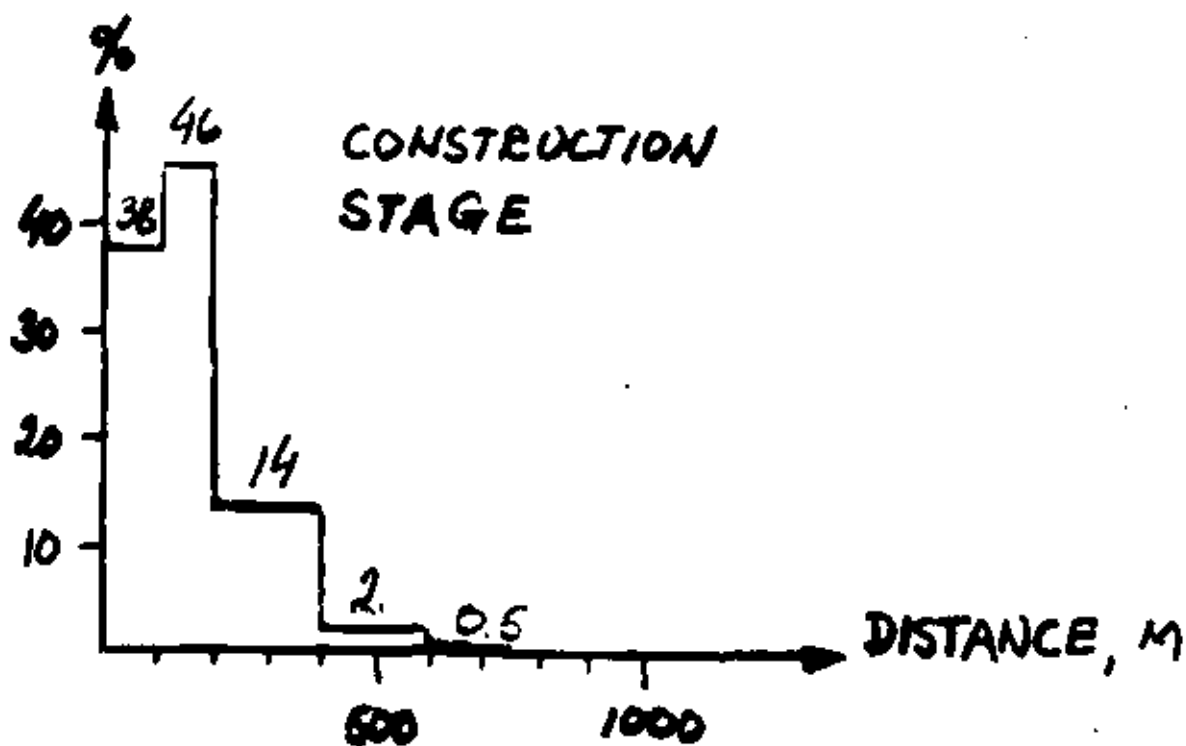
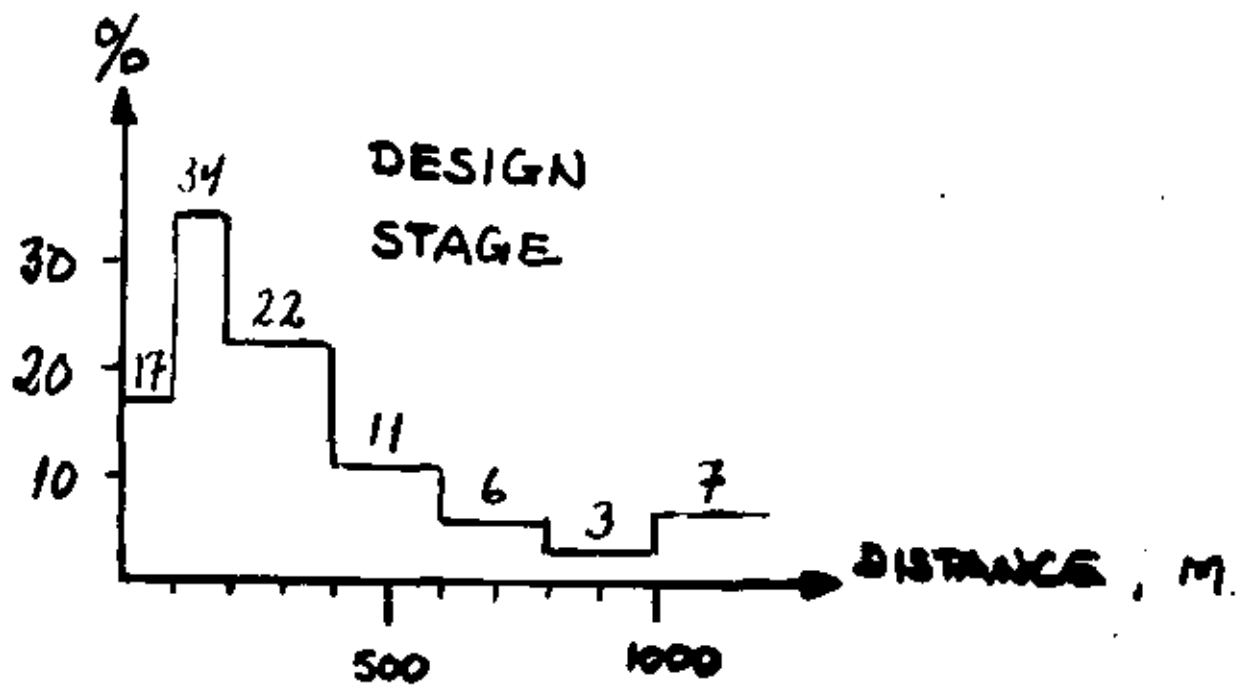


EDM-tachometers

type display recording

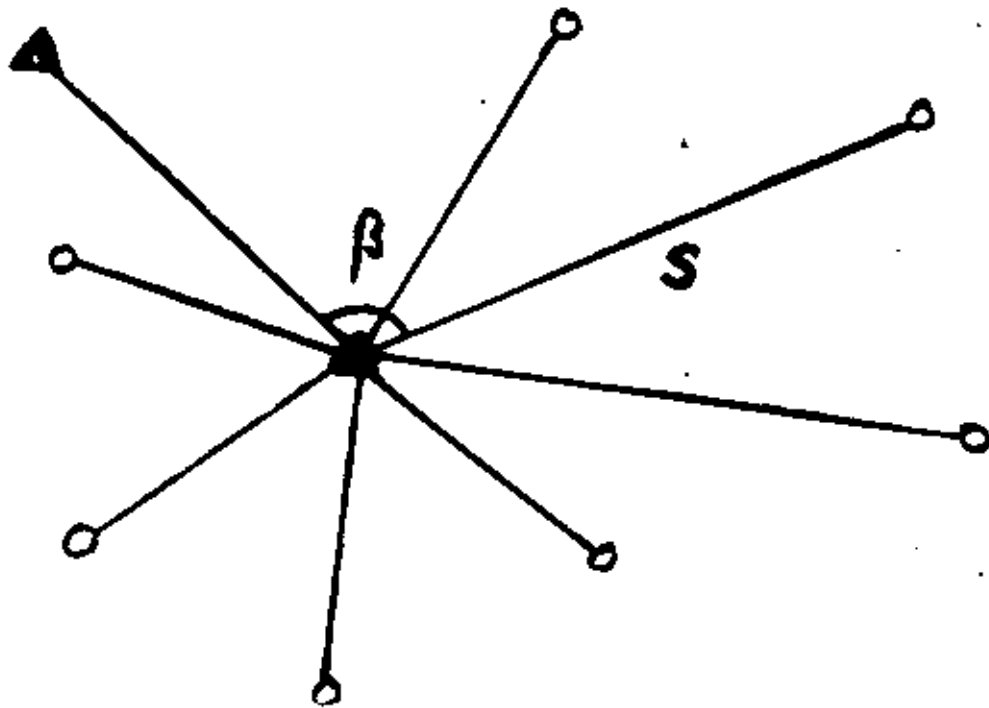


type	△	△	△	△	Hand	recording
HP3320	x	x	x	x	x	memory
Kern E1/DH501	x	x	x	x	x	memory
Wild TC1	x	x	x	x	x	tape
Zeiss Elta 2	x	x	x	x	x	memory
AGA G120	x	x	x	x		memory
Jena EOT 2000	x	(x)	(x)			tape
Wild DI35	x	(x)	(x)			memory
Zeiss Elta 4	x	x	x	x	x	—





ELECTRO-OPTICAL TACHEOMETRY SURVEY SYSTEMS



- POLAR MEASUREMENT
- WIDE RANGE
- LESS DEPENDENT OF TOPOGRAPHY, VEGETATION, TRAFFIC OR
- HIGH MEASURING SPEED
- CONSTANT AND HOMOGENEOUS ACCURACY
- SAFE DATA COLLECTION

surveying methods

polar measurements

traverses

intersections

directions

distances

resection



fordeliter

app. +
målbildning;
avläsning
högindex
rejtifiering

Gyroskopdelit

levels

funktionskontroll
planerare

lämna

ösa
riktning
innehålls

ECM

optiska
modulation
optiska delar
innehållning
resultat presentation
regimer
interf. paper tape
 cassette
 cellid state
 interface

instruments

theodolites

levels

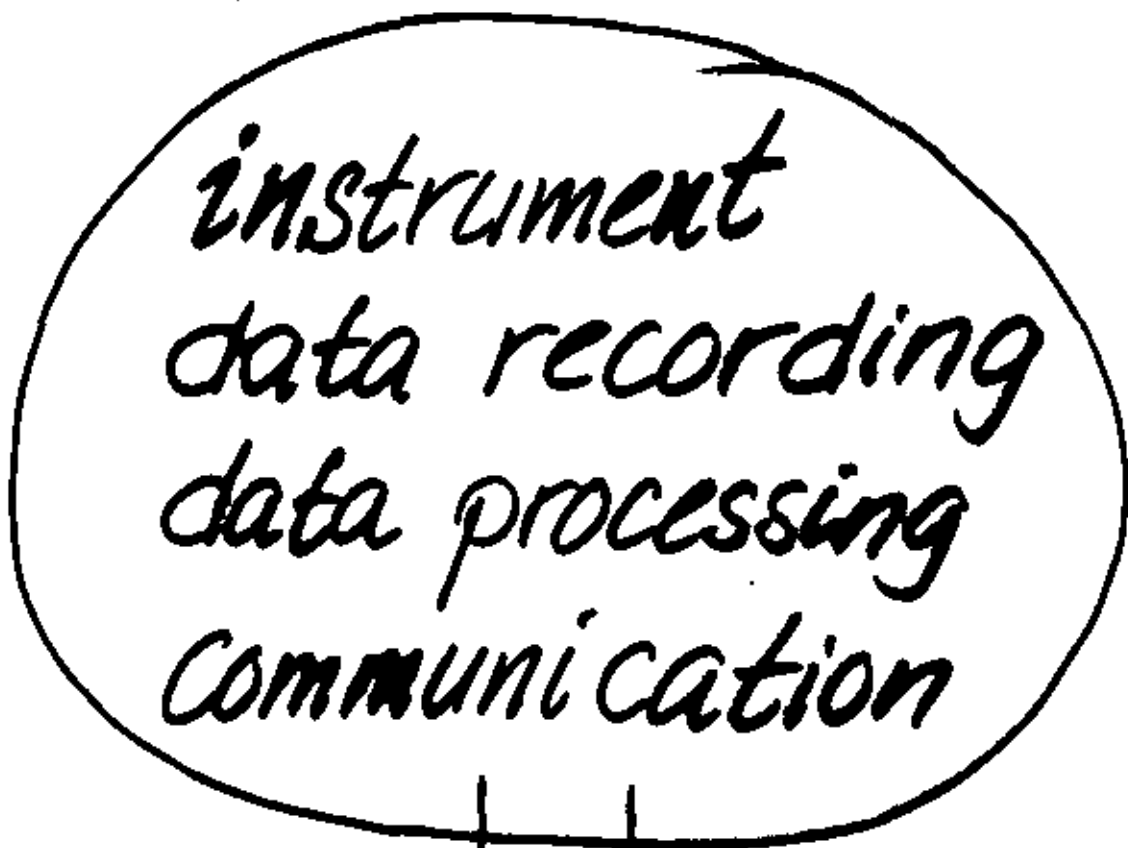
lasers

EDM

optical tachometers

EDM-tachometers

field surveying



surveying
setting out



DIRECTORIO DE ASISTENTES AL SEMINARIO SOBRE FOTOGRAMETRIA APLICADA
AL DISEÑO Y CONSTRUCCION DE OBRAS DE INGENIERIA CIVIL, DEL 26 AL
30 DE MARZO DE 1979.

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